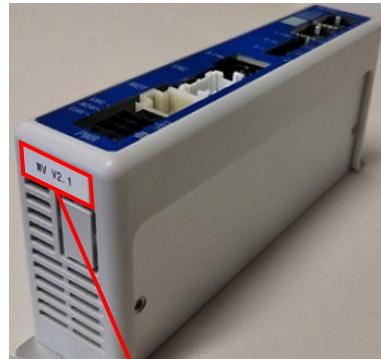


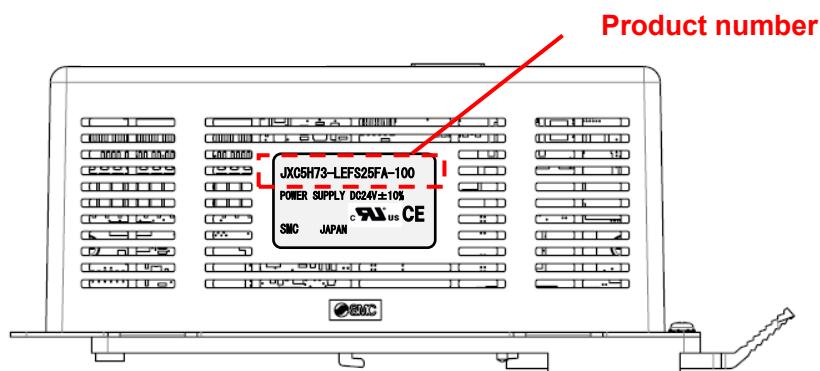
Parameter version selecting method

Check the controller version of JXC



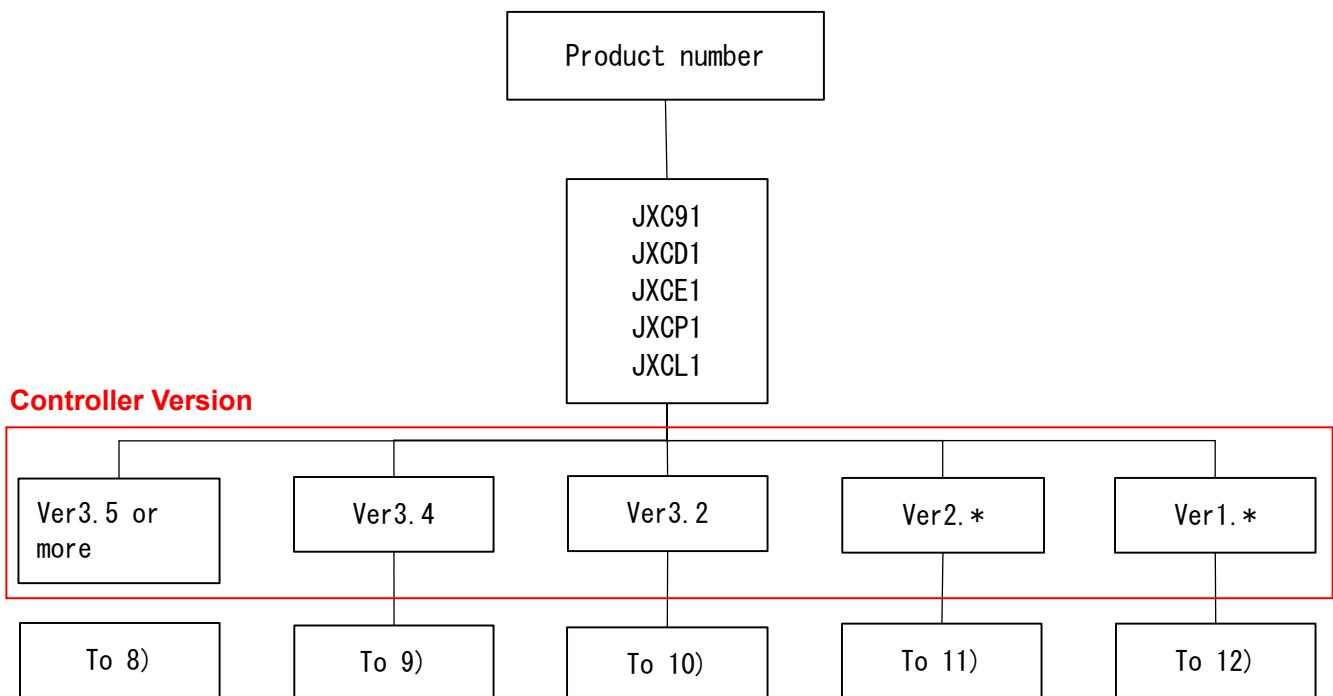
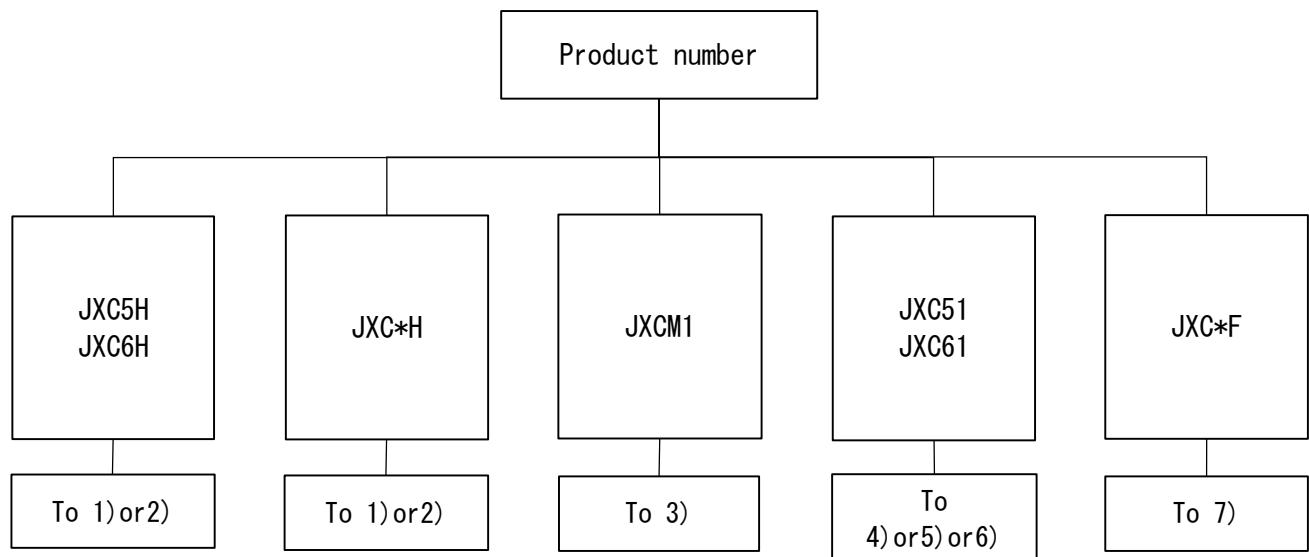
Controller Version

Check the product number of JXC



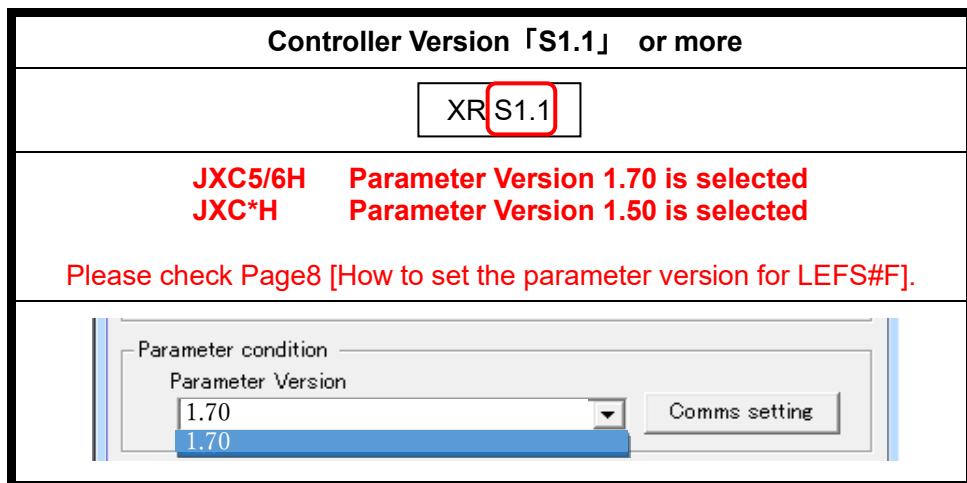
Check the parameter version and write it to JXC as the flowchart below.

A,B,E,F

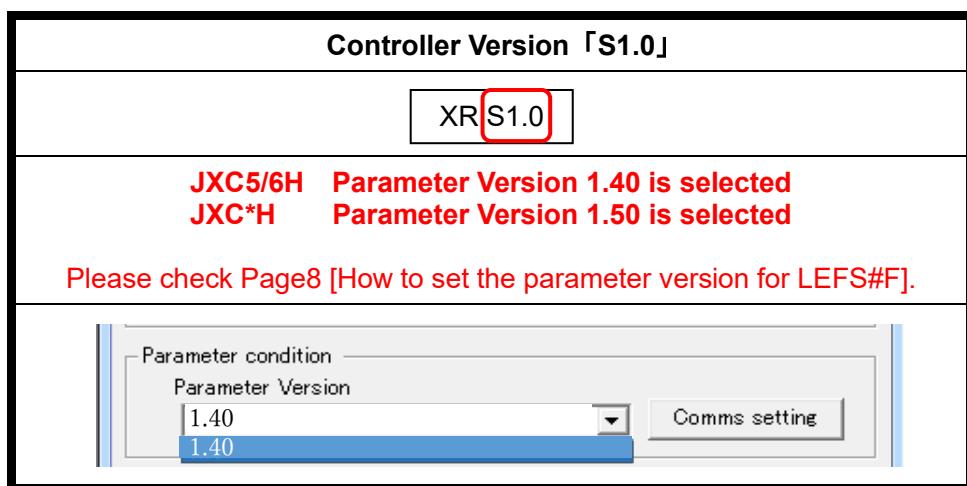


1) Contoroller series JXC*H(Controller Ver 1.1 or more)

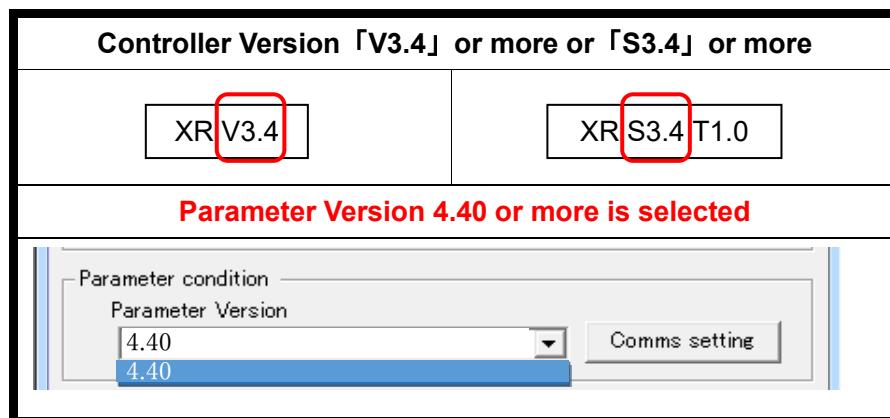
A,C,D

2) Contoroller series JXC*H (Controller Ver 1.0)

D

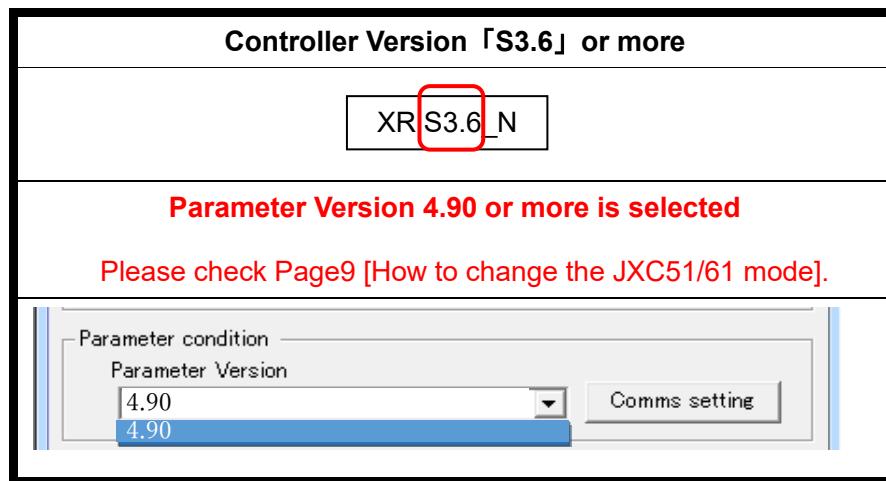
3) Contoroller series JXCM1

F

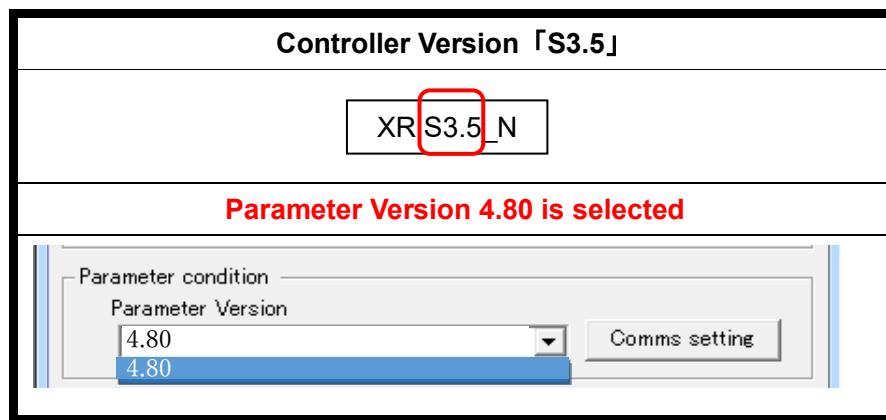


4)Contoroller series JXC51, JXC61(Controller Ver3.6 or more)

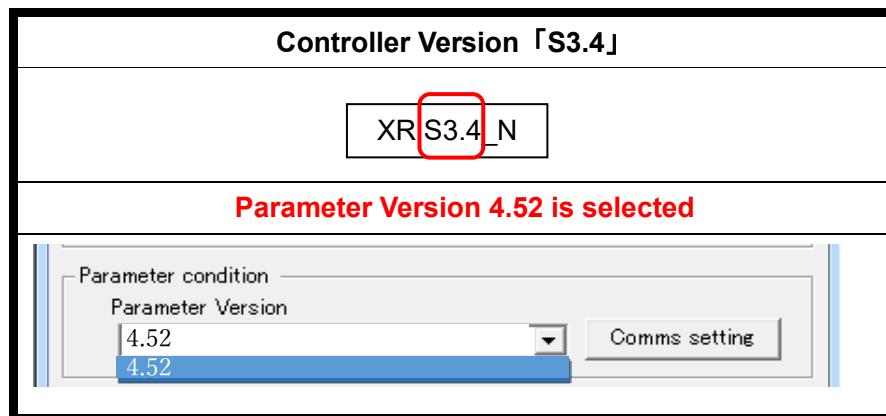
F

5)Contoroller series JXC51, JXC61(Controller Ver3.5)

F

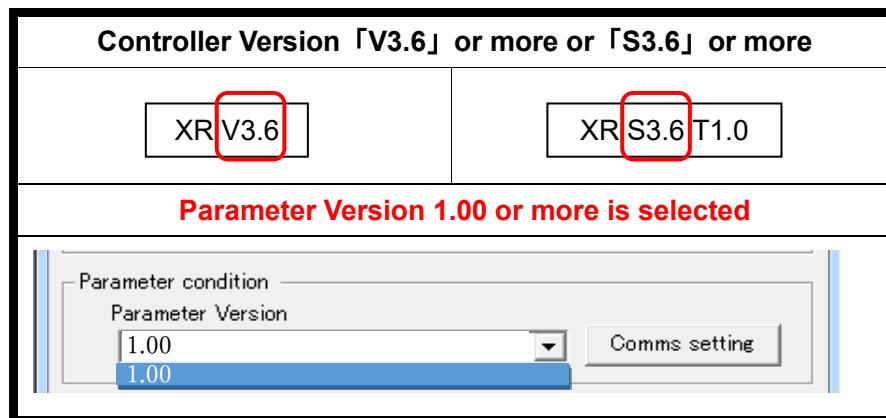
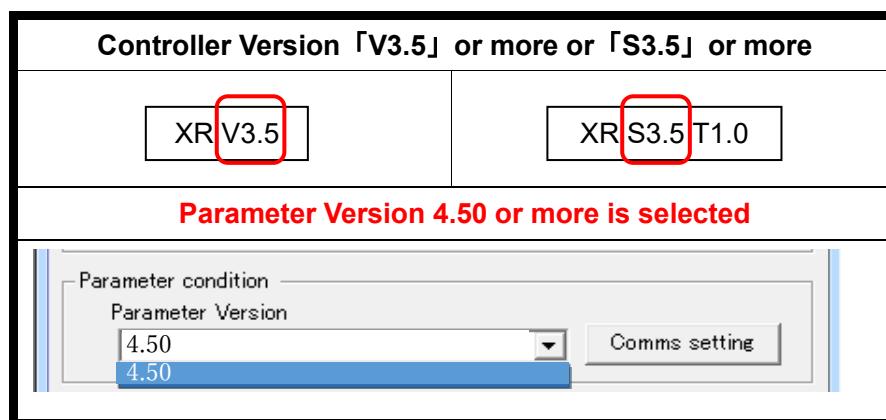
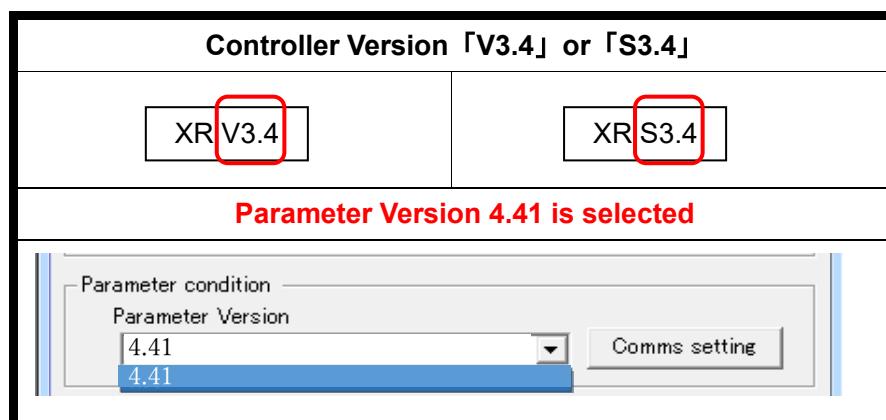
6)Contoroller series JXC51, JXC61(Controller Ver3.4)

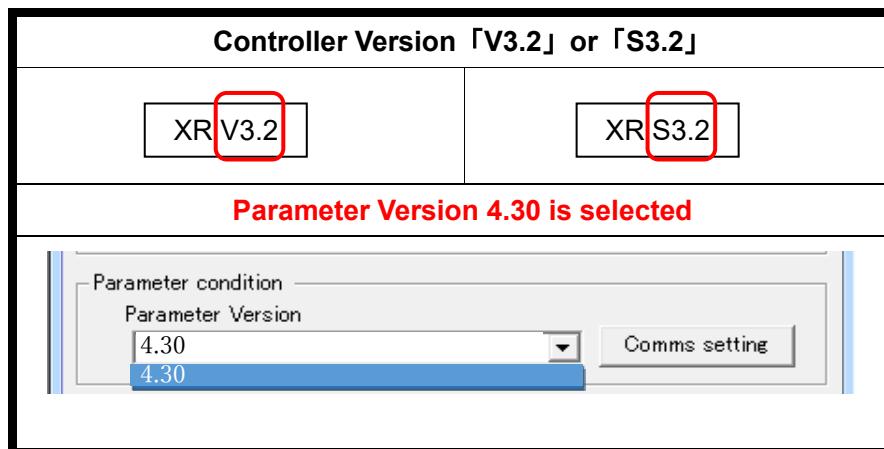
F



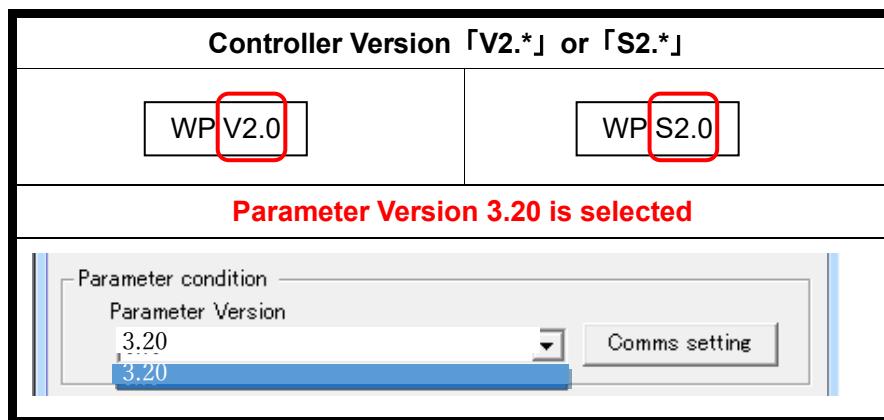
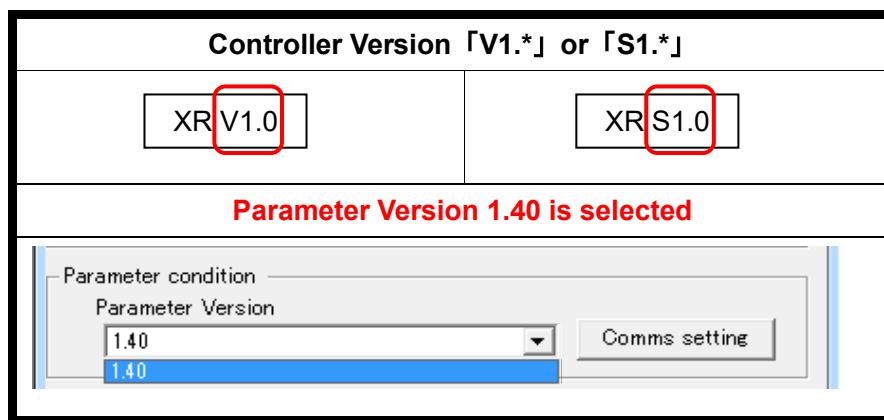
7)Contoroller series JXC*F(Controller Ver3.6 or more)

B

8)Contoroller series JXC*1(Controller Ver3.5 or more)9)Contoroller series JXC*1(Controller Ver3.4)

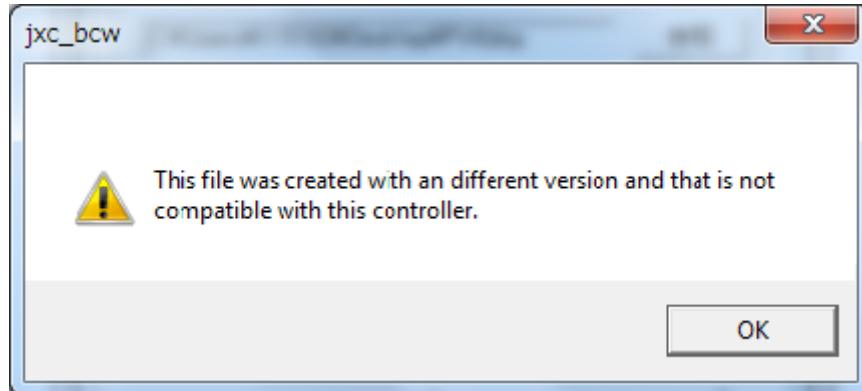
10)Contoroller series JXC*1(Controller Ver3.2)**11)Contoroller series JXC*1(Controller Ver2.*)**

E

**12)Contoroller series JXC*1(Controller Ver1.*)**

⚠ Caution

Please note that only the controller as whom the created version is the same can write it about backup file (.bkp) created with JXC-BCW. The following window is displayed for a different combination.



JXC*H series

D

How to set the parameter version for LEFS*F

JXC*H series can be used with JXC-BCW by selecting parameters (7 types) according to the LEFS*F mounting posture (horizontal or vertical), weight to be conveyed, and speed.

Please write the parameter of the parameter version that matches the operating conditions to the controller.



Figure 1 Parameter condition input screen

Table 1 Parameter version and operating conditions (If the latest version is 1.70 or 1.50)

Parameter Version		Operating conditions			
JXC5H/6H	JXC*H	Mounting posture	Transport weight	Speed	Acceleration
1.71	1.51	Horizontal	Heavy	Low speed	3000mm/s ²
1.72	1.52			↓	
1.73	1.53			↓	
1.74	1.54			High speed	
1.75	1.55		Light	Low speed	9800mm/s ²
1.76	1.56			High speed	
1.77	1.57	Vertical	Common setting		

1.70	1.50	Factory default
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Parameters can be written to the JXC*H series, which is not a blank controller (JXC*H*-BC), with JXC-BCW.

When writing parameter to the controller other than the blank controller (JXC*H*-BC), write parameter that match the actuator part number as well as the operating conditions.

ex) Controller part number : JXC5H71-LEFS25FA-200

Compatible actuator part number

JXC51/61 series

How to change the JXC51/61 mode

F

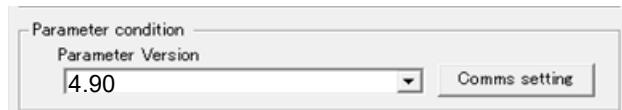


Figure 2 Parameter condition input screen

Table 2 Parameter version and operating conditions (If the latest version is 4.90)

Parameter Version	Operating conditions
4.90	Normal mode(Factory default)

4.91	JXC51 LECP1 mode
4.92	JXC51 LECP2 mode
4.93	JXC61 LECP1 mode
4.94	JXC61 LECP2 mode

Parameters can be written to the JXC51/61 series, which is not a blank controller (JXC51/61-BC), with JXC-BCW.

When writing parameter to the controller other than the blank controller (JXC51/61-BC), write parameter that match the actuator part number as well as the operating conditions.

ex) Controller part number : JXC5171-LEFS25FA-200

Compatible actuator part number