

Operation Manual

PRODUCT NAME

AC Servo Motor Driver (Parameter Configuration using Setup software (MR Configurator2[™]))

MODEL / Series / Product Number

LECS Series



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LECS Series / Driver Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "**Caution**," "**Warning**" or "**Danger**." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)^{*}, and other safety regulations.

1) ISO 4414: Pneumatic fluid power - General rules and safety requirements for systems and their components

ISO 4413: Hydraulic fluid power - General rules and safety requirements for systems and their components

IEC 60204-1: Safety of machinery - Electrical equipment of machines - Part 1: General requirements ISO 10218-1: Robots and robotic devices - Safety requirements for industrial robots - Part 1: Robots

etc.



Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

Warning indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.

Caution indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.



1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

- 2. Only personnel with appropriate training should operate machinery and equipment. The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.
- Do not service or attempt to remove product and machinery/equipment until safety is confirmed.
 The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
 - 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
 - 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. SMC products cannot be used beyond their specifications. They are not developed, designed, and manufactured to be used under the following conditions or environments. Use under such conditions or environments is not allowed.
 - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
 - 2. Use for nuclear power, railways, aviation, space equipment, ships, vehicles, military application, equipment affecting human life, body, and property, combustion equipment, entertainment equipment, emergency shut-off circuits, press clutches, brake circuits, safety equipment, etc., and use for applications that do not conform to standard specifications such as catalogs and operation manuals.
 - 3. Use for interlock circuits, except for use with double interlock such as installing a mechanical protection function in case of failure. Please periodically inspect the product to confirm that the product is operating properly.

Note that the Λ CAUTION level may lead to a serious consequence according to conditions. Please follow the instructions of both levels because they are important to personnel safety.



LECS Series / Driver Safety Instructions

↑ Caution

SMC develops, designs, and manufactures products to be used for automatic control equipment, and provides them for peaceful use in manufacturing industries.

Use in non-manufacturing industries is not allowed.

Products SMC manufactures and sells cannot be used for the purpose of transactions or certification specified in the Measurement Act of each country.

The new Measurement Act prohibits use of any unit other than SI units in Japan.

Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements". Read and accept them before using the product.

Limited warranty and Disclaimer

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.*2)
 - Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.

This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.

3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.

*2) Vacuum pads are excluded from this 1 year warranty.

A vacuum pad is a consumable part, so it is warranted for a year after it is delivered. Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty

Compliance Requirements

- 1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
- 2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

Introduction

It is recommended that the operator read the operation manual and operation manual (Simplified Edition) for LECS^D prior to use.

For the handling and details of other equipment, please refer to the operation manual for used equipment.

1. Parameter Configuration using Setup software (MR Configurator2[™])

This section describes the configuration procedure for main parameters using the setup software (MR Configurator2[™]: LEC-MRC2E). See the "LECS□ operation manual and operation manual (Simplified Edition)I" for parameter details.

1.1 Setup software (MR Configurator2[™])



*1 Setup software version 1.45X or above is required.

- *2 The setup software (MR Configurator2[™]:LEC-MRC2E) must be purchased as an additional item.
- *3 The USB cable (LEC-MR-J3USB) must be purchased as an additional item.

1.1.1 Installation Method

Perform installation according to the "MR Configurator2[™] instruction manual" (Manual/ib0300160*.pdf) contained on the setup software (MR Configurator2[™]) CD-ROM. The "MR Configurator2" software will be added to the PC.

1.2 Basic driver set-up for Initial Test Drive

If you turn on the power supply for the first time, refer to "LECS operation manual and operation manual (Simplified Edition)I".

1.2.1 Start up the Setup software (MR Configurator2[™])

- ① Connect the PC and LECS using the USB cable.
- 2 Turn on the power of the LECS \Box .
- ③ Start application "MR Configurator2".



Once the application starts, the screen below will be displayed.



1.2.2 "System Settings"

① From "Project" menu select "New", the "New project" window will be displayed.

MELSOFT MR Configur	ator2 New Safety	project Positioning-data	Monitor	Diagnosis	Test Mode	Adjustment Tool	Window	Help	A-1		B-1-1	
] New	Ctrl+N	T 20 00 10	In 18 9	7								
y Open	CB1+O											
Close												
Save Save	Ctrl+S					New Projec	t					
Save As												
Delete						Model		MR-J3-A	~			
Read Other Format						Oneration mo	de		V			
System Setting						Multi-ave	mification					
Print Preview						- Mara-ax.						
Print	Ctrl+P					Station		00	~			
Exit MR Configurator?	Alt+E4					Option unit		No Connection	~			
						 O Serve 	amplifier	connection RS-422 (RS	-232C)			
						Com. spe	ed	AUTO	×			
						Port No.		ALITO	~			
						Sear		peed/port No. automatio	ally			
						The last-u	sed proje	ct will be opened whene	ver			
						the applic	ation is re	istarted				
								ОК	Cancel			
							_					

1.2.3 Model Selection

- The Mitsubishi Electric Corporation series will be displayed in the model selection list. Please select MR-JN-A if using the LECSA.
 MR-J4-A-S099(□) if using the LECSB-T.
 MR-J3-T if using the LECSC-T.
 MR-J4-B(-RJ) if using the LECSS-T.
 MR-J4-TM if using the LECSN□-T.
- 2 Please select "servo amplifier connection USB" as the communication device.
- ③ Click OK.
- ④ Click OK.





1.2.4 Driver ON LINE Check Check that the driver is enabled (ONLINE). Image: Image

It is OFFLINE when displayed as "

* For OFFLine, PC and amplifier aren't communicating. Confirm the following points.

- Is amplifier's power supply turning on?
- Are PC and amplifier connected with the USB cable?
- Is the USB driver installed?
- Is the setting of "Port" for USB connection corresponding?

1.3 Loading Parameters (Saved files)

- ① From the "Parameter Setting" window in the setup software, select "Open".
- ② Please specify location of the file.
- ③ Please select the file you wish to import parameters [.prm2].
- ④ Click "Open".
 Parameters will be loaded.



1.4 Parameter writting (PC \rightarrow LECS \Box (Driver))

- ① From the "Parameter" menu select "Parameter Setting", the "parameter setting" window will open.
- 2 The explanation of the parameter item is displayed in "MR2 Help".
 (When it is not displayed, from the "View" menu select "Docking window" "Docking Help".)

	Parameter Sat	fety Positioning		
	🖉 📑 Parameter :	Setting		
	Axis Name	Set ing		
	Darameter	Convertor		
	Parameter			
	Project View File Par	ator, New project - [Parameter Setting] amete Setting(Z) Parameter Safety Positioning-data Monitor	r Diagnosis Test-Mode Adiustment Tools Window Help	_ # ×
	: 🗅 🖻 💾 🖪 😧 : 🖥	I 🗤 🕫 🐨 🐨 🖬 🗤 🔯 🗈 🐨 🐨 🐼		
	Parameter Setting	×		4 Þ 🗸
	📕 Axis 1 💌 🚽 Rea	ad 🐻 et To Default 投 Verify 🦉 Parameter Copy 📄 Parameter B	llock	
	Dpen PSave As			
	 Enction display Common 	Common - Basic	Selected Items Write Single Axis Write	
	Basic Extension	Control mode(*STY)	Encoder output pulse (*ENRS)	
	Extension 2	Position control mode	Advance A-phase 90° by CCW Phase Setting	
	Position control	Control type selection	Number of encoder output pulse	
	- Torque control	Standard control/Max. torque up of HF-KP motor is invalid	4000 pulse Encoder Output Pulse	
	 Speed setting (Spee Servo adjustments 	Rotation direction (*POL) Rotation direction selection	Torque limit(TLP, TLN, TL2)	
	- Basic Extension	CCW dir. during fwd. pls. input, CW dir. during rev. pls. input	Reverse torque limit 100.0 % (0.0-100.0)	
	Gain changing		Internal torque limit 2 100.0 % (0.0-100.0)	
	Analog input		Zero speed(ZSP)	
3	Basic		Zero speed 50 r/min (0-10000)	
	Extension			
	I/O			
_	<			
2)	MR2 Help			+
	CONTROL M	ODE		
	Colort the control ma	de efernie enville		
	Also, select control lo	oop of servo amplifier and max. torque of HF-KP n	notor. (Only for MR-J3-A)	
	Ready		[Station 00] MR-J3-A Servo amplifier connection: USB	OVR CAP NUM SCRL

③ When each item of "List display" is clicked, "Parameter list" screen along each item is displayed. When "Basic" is selected, it is displayed as follows.

Basic			Selected	Items Write Singl	e Axis Write
No.	Abbr.	Name	Units	Setting range	Axis 1
PA01	*STY	Control mode		0000-0F55	0000
PA02	*REG	Regenerative option		0000-71FF	0000
PA03	*ABS	Absolute position detection system		0000-0004	0000
PA04	*AOP1	Function selection A-1		0000-F031	0000
PA05	*FBP	Number of command input pulses per revolution		0-0 / 1000-50000	0
PA06	CMX	Elec. gear numerator (Cmd. pls. mult. factor num.)		1-1048576	1
PA07	CDV	Elec. gear denominator (Cmd. pls. mult. factor den.)		1-1048576	1
PA08	ATU	Auto tuning mode		0000-0003	0001
PA09	RSP	Auto tuning response		1-32	12
PA10	INP	In-position range	pulse	0-65535	100
PA11	TLP	Forward rotation torque limit	%	0.0-100.0	100.0
PA12	TLN	Reverse rotation torque limit	%	0.0-100.0	100.0
PA13	*PLSS	Command pulse input status		0000-0812	0000
PA14	*POL	Rotation direction selection		0-1	0
PA15	*ENR	Encoder output pulse	pulse/rev	1-1048576	4000
PA16	*ENR2	For manufacturer setting		0000-FFFF	0000
PA17	*MSR	For manufacturer setting		0000-FFFF	0000
PA18	*MTY	For manufacturer setting		0000-FFFF	0000
PA19	*BLK	Parameter block		0000-FFFF	000C

Refer to" LECS operation manual and operation manual (Simplified Edition)I", for details of each parameter.

- ④ Click on the "Single Axis Write" button.
- ${\rm 5}$ Turn the power ${\rm \widetilde{OFF}}$ and ON again. The Parameter is then enabled.

Basic			Selected	Items Write Single	Axis Write 5
No.	Abbr.	Name	Units	Setting raped	Axis1
PA01	*STY	Control mode		0000-0F55	0000
PA02	*REG	Regenerative option		0000-71FF	0000
PA03	*ABS	Absolute position detection system		0000-0004	0000
MELS		onfigurator2 writing. Continue? (Y) いいえ(N)			
) Writing amplifie	is finished. Please switch the power supply of the er off and on again.			
		ОК			

Please set the parameters for each actuator. Please change the parameter values according to usage.

Refer to "LECS operation manual and operation manual (Simplified Edition)I" for details of each parameter and how to change method.

Refer to "LECS Operation Manual (Simplified Edition)" for details of parameters recommended value of each actuator.

1.5 Saving Parameters

- ① From the "Parameter Setting" window in the setup software, select "Save As".
- ② Please specify location to be saved.
- ③ Please enter any file name.
- 4 Click "Save".

Files Saved .prm2

Settings files for parameters.

* Note Always upload current parameters from the driver to the software before saving. (See Section 1.3 for uploading.)

	Parameter Setting					
	Axis1 🖌 🗧 Read	🐻 Set To Default 🛛 🗛 Verify	Parameter Copy	Parameter Block		
1	Dper Save As					
-	Generation display Common Basic Extension Extension 2 Commonent parts Position control Speed control Speed setting (Spee Servo adjustments Basic Extension Gain changing Digital I/O Analog input Basic Gain/filter Extension	nmito Cont Posi Cont Star Star Cott Cont Star Cott Cott Cont Cont Star Cott Cott Cont Cont Cont Cont Cont Cont	存 ハードディスク シードディスク 空き領域 リムーバブル記憶 シンローバブル記憶 のVD RW 3 ファイル名(N): ファイルの種類(T):	ドライブ (1) 2002 (C:) 85.4 GB/141 GB 域があるデバイス (1) ドライブ (D:) User Parameter Files(*prm2)	× (保存(S) キャンセル	

1.5.1 Read parameters from the LECSA driver

If you read the parameters of the driver to the software, please do the "read" operation.

- ① From the View menu bar "parameter (A)" please click on the "parameter setting (P)". "Parameter Settings" screen will display.
- 2 $\mbox{Please click on the "Read".}$

Parameter Setting (2)		
Axis1 🖌 📢 Read 🖏 Se	t To Default 🛛 🖓 Verify 🖉 Pa	arameter Copy 📄 Parameter Block
🔁 Open 💾 Save As 📑 Copy 🦷	Paste 📉 Undo 👧 Redo	
MELSOFT MR Configurator2		
Execute reading. Continue?		
(+1)(2)		

1.6 Help Function

By selecting "MR Configurator2 Help" in "Help" from any window of the setup software, a "HELP" screen will be shown.



Revision history

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