Motorless Type

Electric Actuators

RoHS

Various servo motors can be mounted due to the addition of the motorless type!

Compatible Motors

Manufacturers of compatible motors	Series	Compatible interfaces						
		Pulse input	CC-Link	SSCNETⅢ	MECHATROLINK Ⅱ	MECHATROLINK Ⅲ	DeviceNet	EtherCAT
Mitsubishi Electric Corporation	MELSERVO-JN	●						
	MELSERVO-J3	●	●	●				
	MELSERVO-J4	●		●				
YASKAWA Electric Corporation	Σ-V	●			●	●	●	●
SANYO DENKI CO., LTD.	SANMOTION R	●						●
OMRON Corporation	Sysmac G5	●			●			●
Panasonic Corporation	MINAS-A4	●						
	MINAS-A5	●						

Slider Type *Series LEF*

Size: 25, 32, 40

Ball screw drive **Belt drive**

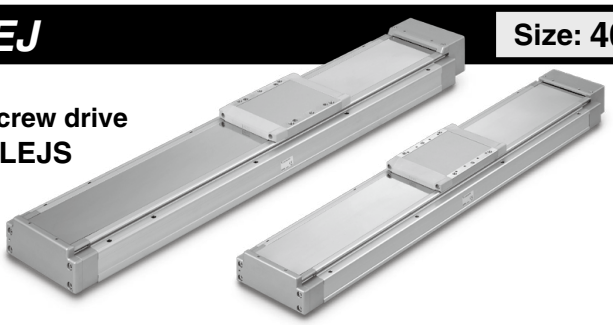
Max. work load: 60 kg
Max. speed: 2,000 mm/s (Belt drive),
1,000 mm/s (Ball screw drive)
Max. acceleration/deceleration: 20,000 mm/s²
Max. stroke: 3,000 mm (Belt drive)

High Rigidity Slider Type *Series LEJ*

Size: 40, 63

Ball screw drive

Max. work load: 85 kg
Max. speed: 1,200 mm/s
Max. acceleration/deceleration: 20,000 mm/s²



Rod Type *Series LEY*

Size: 25, 32, 63 Note)

Note) In-line motor type only

Max. pushing force: 1,910 N
Max. speed: 1,000 mm/s
Max. stroke: 800 mm

Guide Rod Type *Series LEYG*

Size: 25, 32

Max. pushing force: 736 N
Max. speed: 1,200 mm/s
Max. stroke: 300 mm

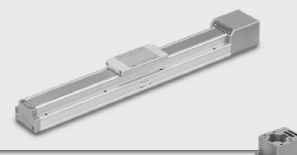
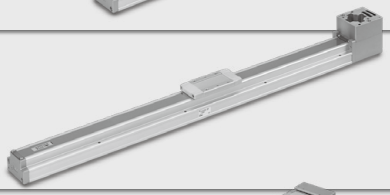
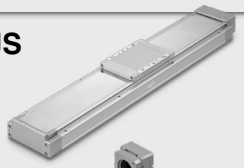
Series LE□

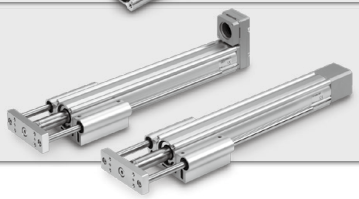
SMC

Series Variations/Compatible Motors

Series Variations

Series	Size 25	32	40	63
Slider Type/Series LEFS Ball screw drive	100 W	200 W	400 W	
Slider Type/Series LEFB Belt drive	100 W	200 W	400 W	
High Rigidity Slider Type/Series LEJS Ball screw drive			100 W	200 W
Rod Type/Series LEY	100 W	200 W		400 W
Guide Rod Type/ Series LEYG	100 W	200 W		

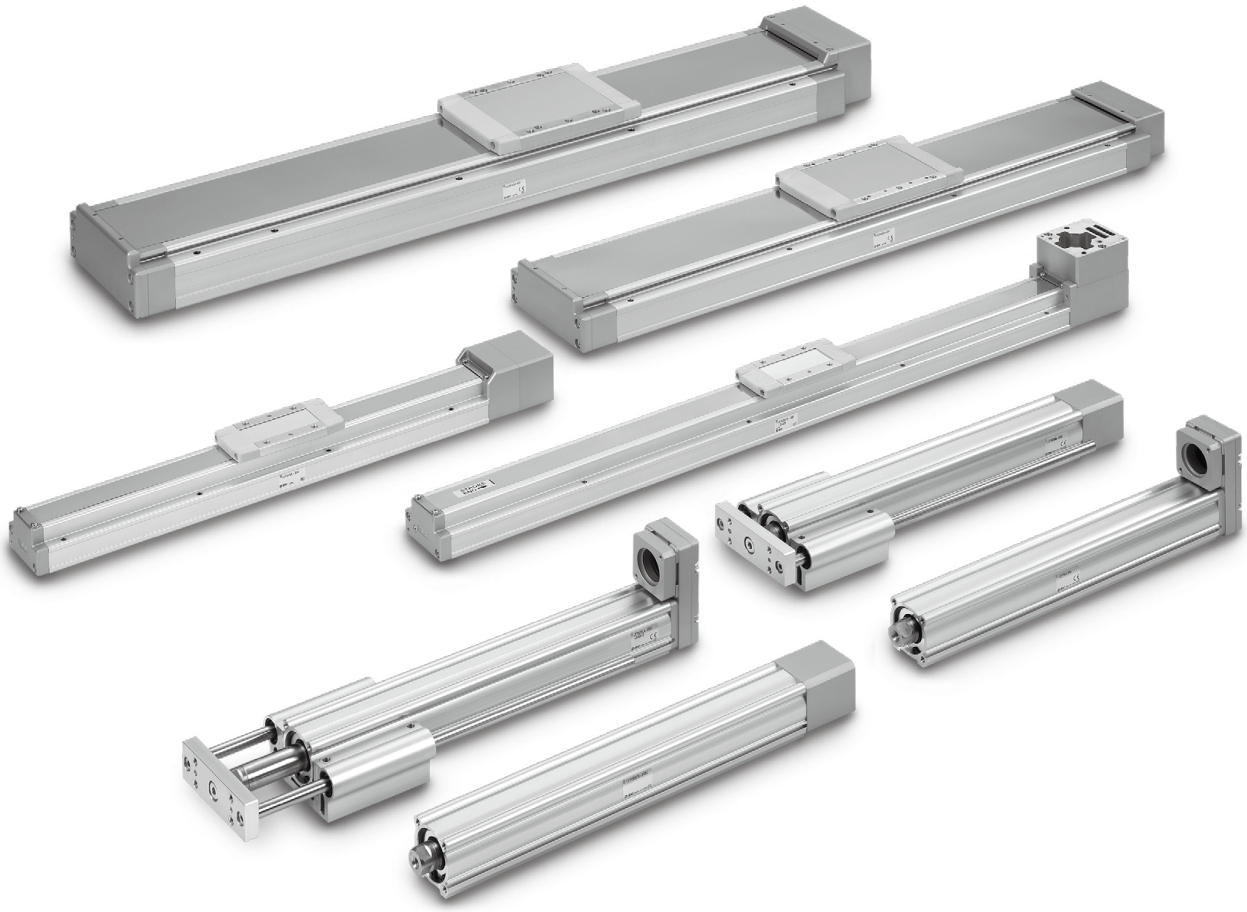


The values in ● shows the motor capacity.

Compatible Motors (100 W/200 W/400 W)

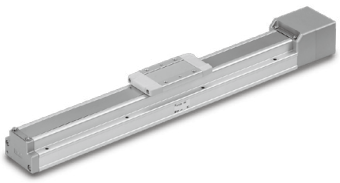
Manufacturer	Series	Type *1	Pulse input	CC-Link
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	
	MELSERVO-J3	HF-KP	●	●
	MELSERVO-J4	HG-KR	●	
YASKAWA Electric Corporation	Σ-V	SGMJV	●	
SANYO DENKI CO., LTD.	SANMOTION R	R2	●	
OMRON Corporation	Sysmac G5	R88M-K	●	
Panasonic Corporation	MINAS-A4	MSMD	●	
	MINAS-A5	MSMD/MHMD	●	

*1 Motors should be applicable to the mounting dimensions and compatible motor types. Select a motor after checking the specifications of each model. Additionally, when considering a motor other than those shown above, select a motor within the range of the specifications after checking the mounting dimensions.
*2 For details about compatible interfaces, refer to each manufacturer's catalog.



Compatible interfaces *2					
	SSCNET Ⅲ	MECHATROLINK Ⅱ	MECHATROLINK Ⅲ	DeviceNet™	EtherCAT®
	●				
	●				
		●	●	●	
		●			●
					●

Model Selection



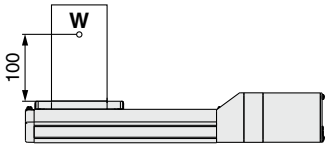
Selection Procedure

Step 1 Check the work load–speed. → **Step 2** Check the cycle time. → **Step 3** Check the allowable moment.

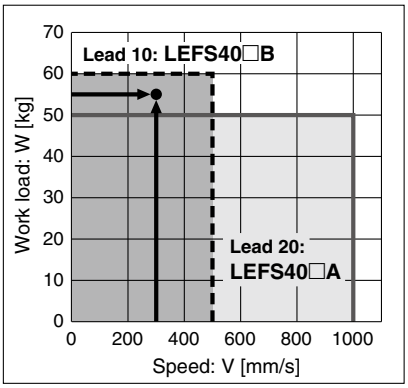
Selection Example

Operating conditions

- Workpiece mass: 55 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 3,000 [mm/s²]
- Stroke: 200 [mm]
- Mounting position: Horizontal upward
- Incremental encoder
- Workpiece mounting condition:



- Settling time



<Speed–Work load graph> (LEFS40)

Step 1 Check the work load–speed. <Speed–Work load graph>

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the <Speed–Work load graph> on page 4.

Selection example) The **LEFS40S4B-200** is temporarily selected based on the graph shown on the right side.

Step 2 Check the cycle time.

Calculate the cycle time using the following calculation method.

Cycle time:

T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1: Acceleration time and T3: Deceleration time can be obtained by the following equation.

$$T1 = V/a1 \text{ [s]} \qquad T3 = V/a2 \text{ [s]}$$

- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4: Settling time varies depending on the conditions such as motor types, load and in positioning of the step data. Therefore, please calculate the settling time with reference to the following value.

$$T4 = 0.05 \text{ [s]}$$

∗ The conditions for the settling time vary depending on the AC servo motor or driver to be used.

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 300/3000 = 0.1$ [s],

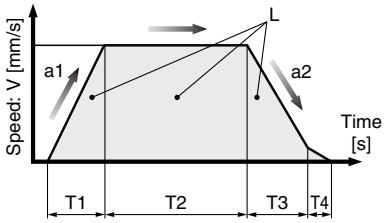
$T3 = V/a2 = 300/3000 = 0.1$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{200 - 0.5 \cdot 300 \cdot (0.1 + 0.1)}{300} = 0.57 \text{ [s]}$$

$T4 = 0.05$ [s]

Therefore, the cycle time can be obtained as follows.

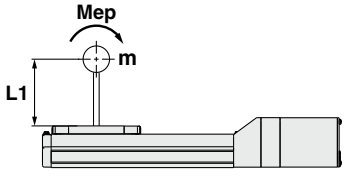
$T = T1 + T2 + T3 + T4 = 0.1 + 0.57 + 0.1 + 0.05 =$ **0.82 [s]**

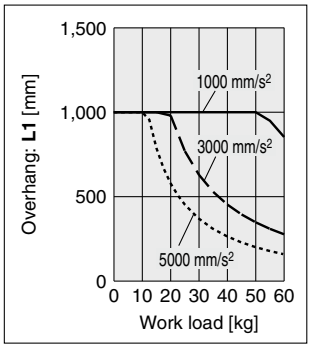


L : Stroke [mm]
··· (Operating condition)
V : Speed [mm/s]
··· (Operating condition)
a1: Acceleration [mm/s²]
··· (Operating condition)
a2: Deceleration [mm/s²]
··· (Operating condition)

T1: Acceleration time [s]
Time until reaching the set speed
T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
T4: Settling time [s]
Time until in position is completed

Step 3 Check the guide moment.





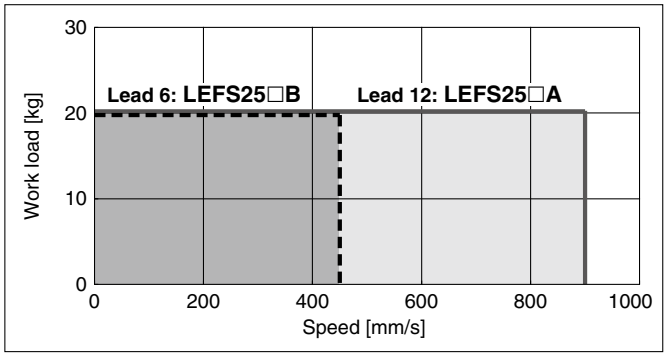
Based on the above calculation result, the LEFS40S4B-200 is selected.

Speed–Work Load Graph (Guide)

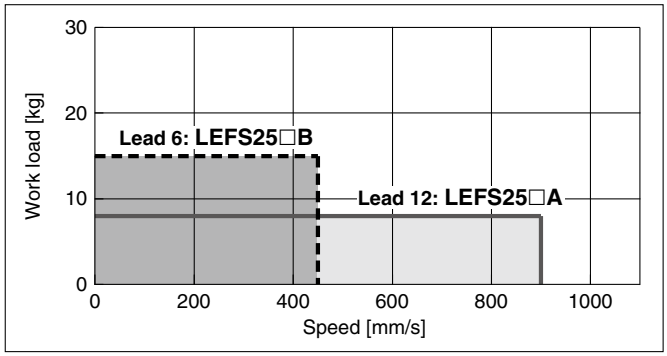
∗ The values shown below are allowable values of the actuator body. Do not use the actuator so that it exceeds these specification ranges.
∗ The allowable speed is restricted depending on the stroke. Select it by referring to "Allowable Stroke Speed" below.

LEFS25/Ball Screw Drive

Horizontal

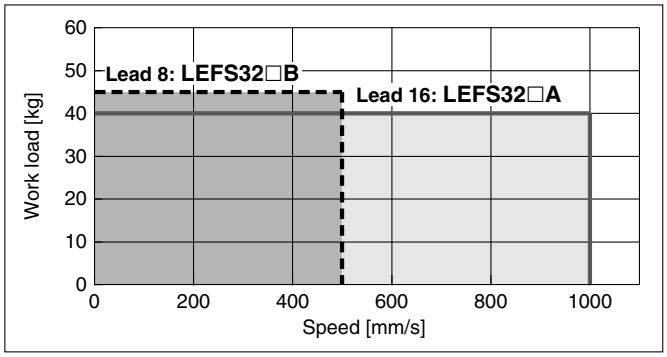


Vertical

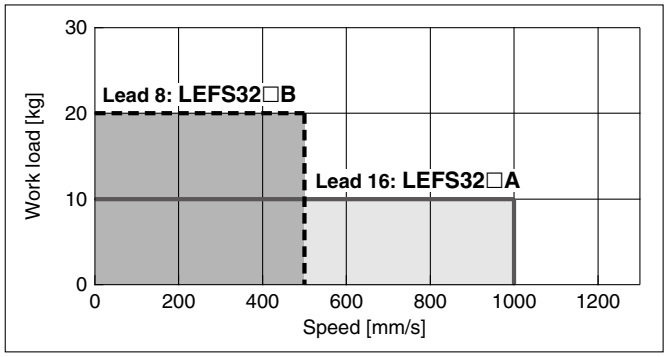


LEFS32/Ball Screw Drive

Horizontal

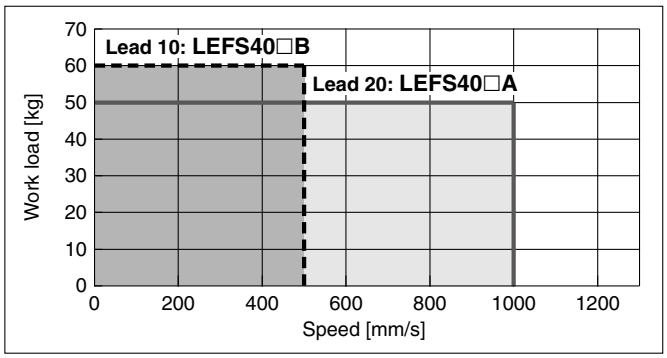


Vertical

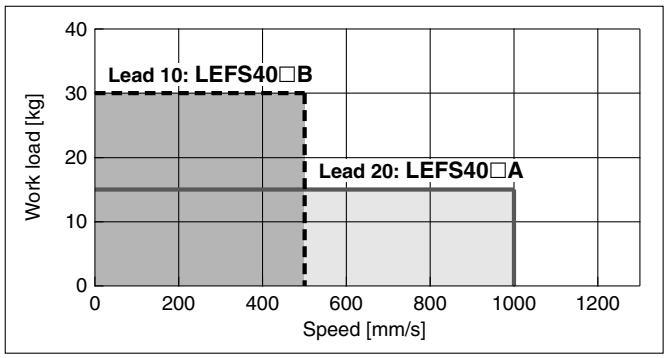


LEFS40/Ball Screw Drive

Horizontal



Vertical



Allowable Stroke Speed

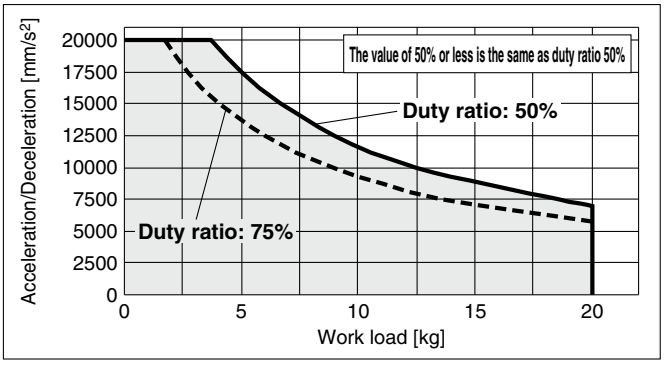
[mm/s]

Model	AC servo motor	Lead		Stroke [mm]									
		Symbol	[mm]	Up to 100	Up to 200	Up to 300	Up to 400	Up to 500	Up to 600	Up to 700	Up to 800	Up to 900	Up to 1000
LEFS25	100 W /□40	A	12	900				720	540	—	—	—	—
		B	6	450				360	270	—	—	—	—
		(Motor rotation speed)		(4500 rpm)				(3650 rpm)	(2700 rpm)	—	—	—	—
LEFS32	200 W /□60	A	16	1000					800	620	500	—	—
		B	8	500					400	310	250	—	—
		(Motor rotation speed)		(3750 rpm)					(3000 rpm)	(2325 rpm)	(1875 rpm)	—	—
LEFS40	400 W /□60	A	20	—	1000					940	760	620	520
		B	10	—	500					470	380	310	260
		(Motor rotation speed)		—	(3000 rpm)					(2820 rpm)	(2280 rpm)	(1860 rpm)	(1560 rpm)

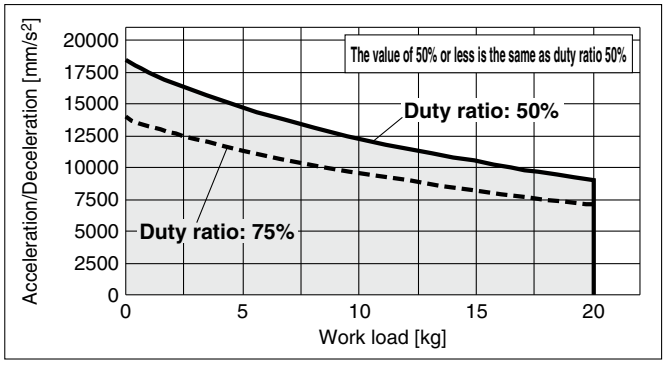
Work Load–Acceleration/Deceleration Graph (Guide)

LEFS25/Ball Screw Drive: Horizontal

LEFS25□A

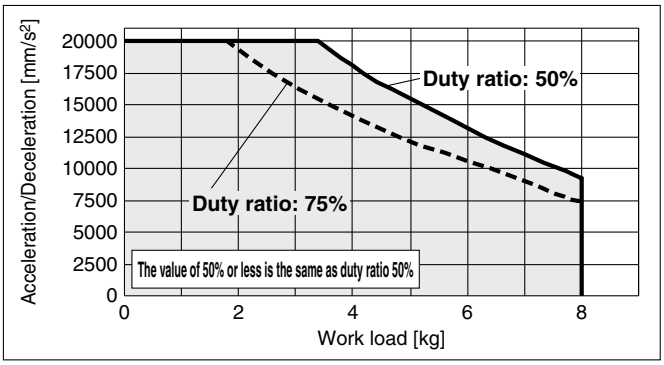


LEFS25□B

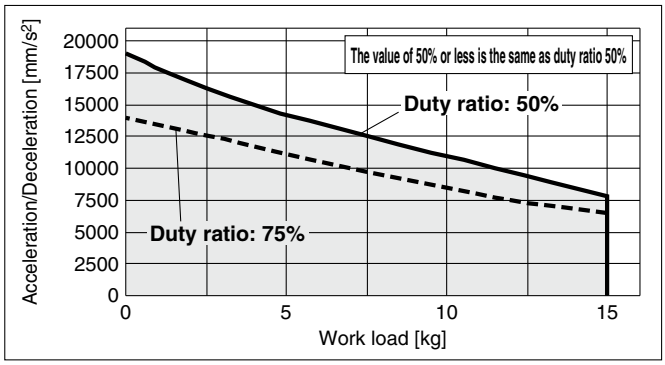


LEFS25/Ball Screw Drive: Vertical

LEFS25□A

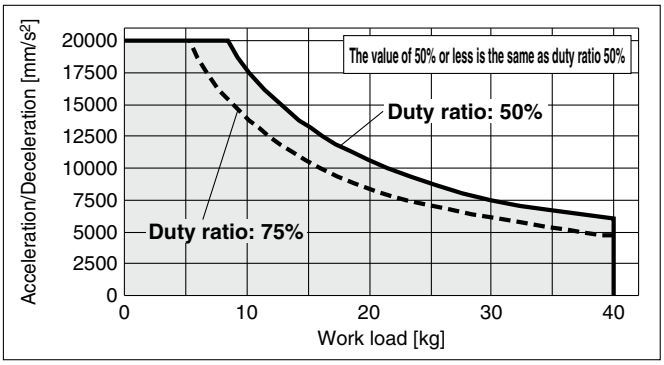


LEFS25□B

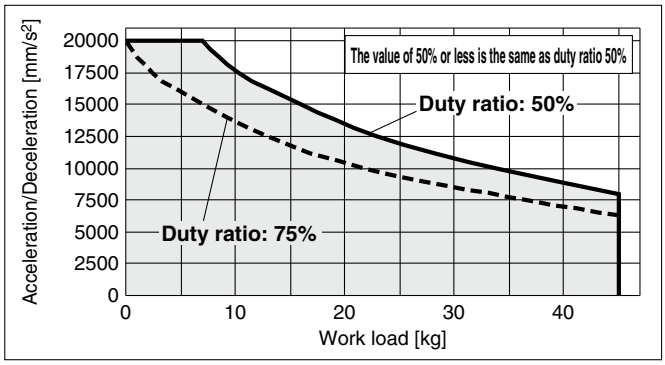


LEFS32/Ball Screw Drive: Horizontal

LEFS32□A

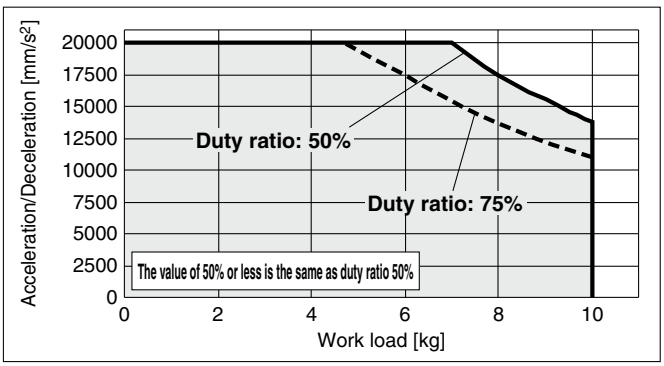


LEFS32□B

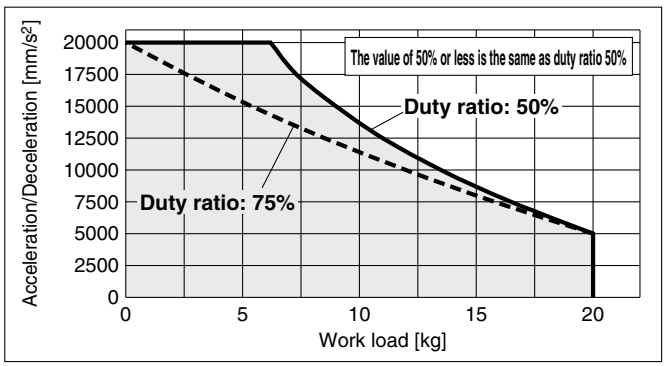


LEFS32/Ball Screw Drive: Vertical

LEFS32□A



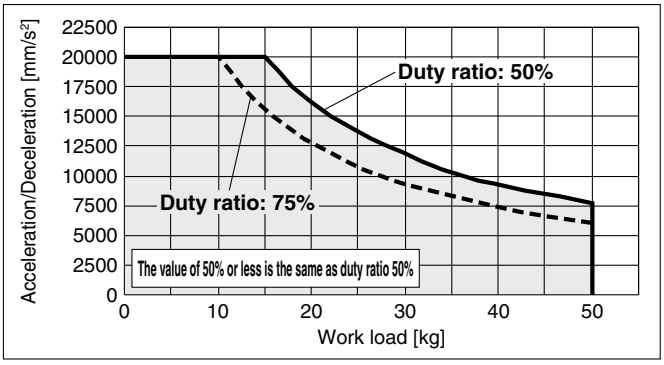
LEFS32□B



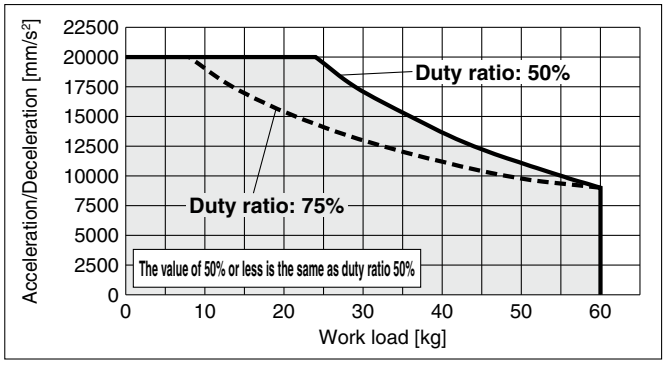
Work Load–Acceleration/Deceleration Graph (Guide)

LEFS40/Ball Screw Drive: Horizontal

LEFS40□A

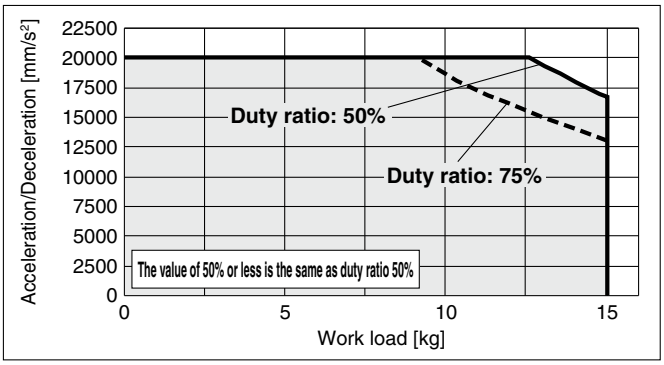


LEFS40□B

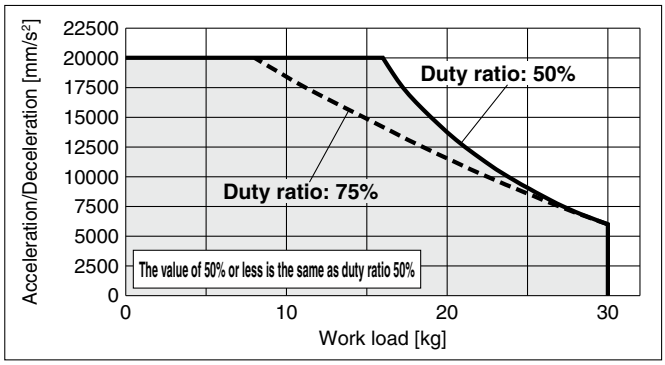


LEFS40/Ball Screw Drive: Vertical

LEFS40□A



LEFS40□B



These graphs are reference examples of when an SMC standard AC servo motor is mounted.
Determine the duty ratio after taking into account the load factor of the AC servo motor or driver to be used.
The values show the specifications with a standard SMC motor used. Please use this as a guide.

Dynamic Allowable Moment

* This graph shows the amount of allowable overhang when the center of gravity of the workpiece overhangs in one direction. When the center of gravity of the workpiece overhangs in two directions, refer to the Electric Actuator Selection Software for confirmation. http://www.smcworld.com

Acceleration/Deceleration ——1,000 mm/s² — — —3,000 mm/s² ·····5,000 mm/s² —·—·—10,000 mm/s² - - - -20,000 mm/s²

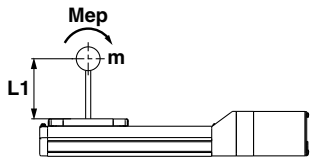
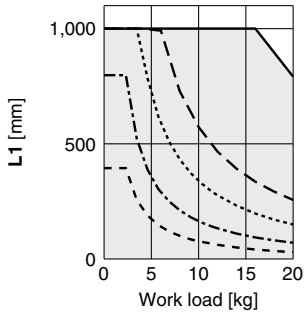
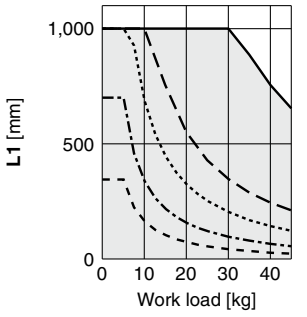
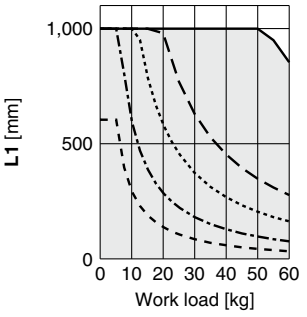
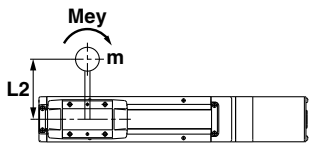
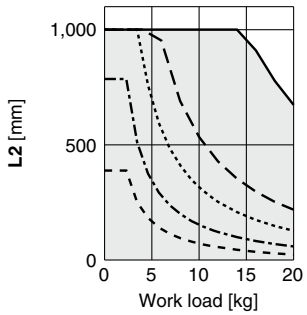
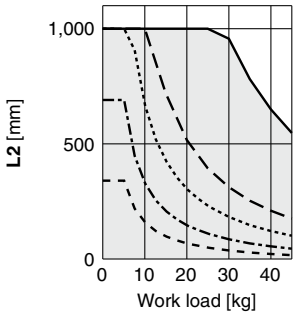
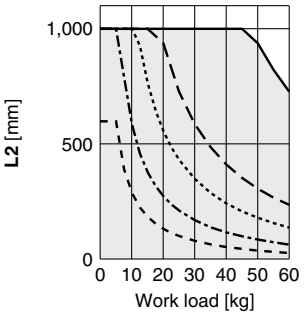
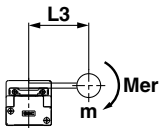
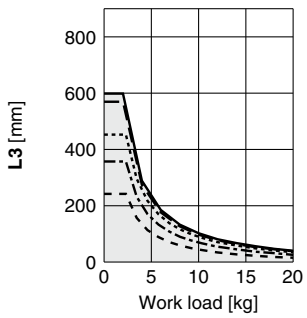
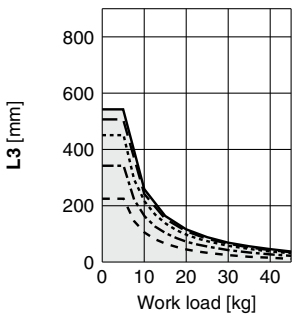
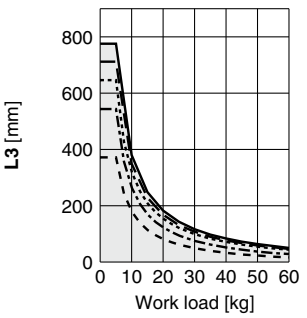
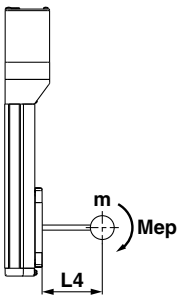
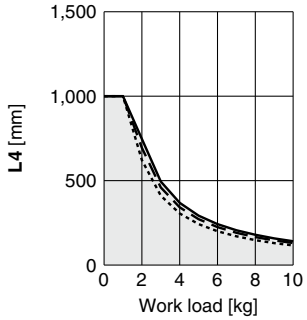
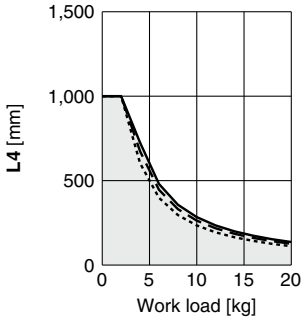
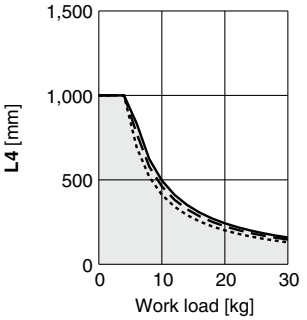
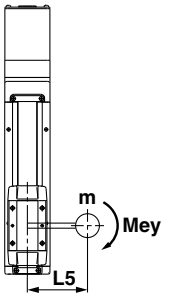
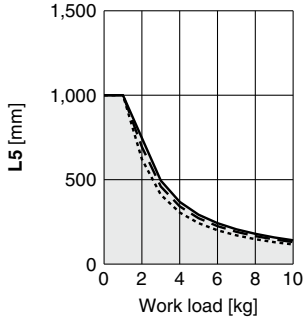
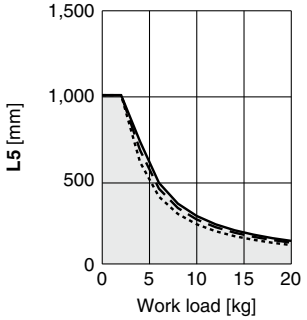
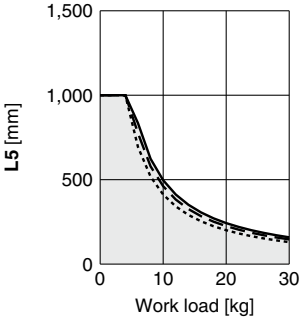
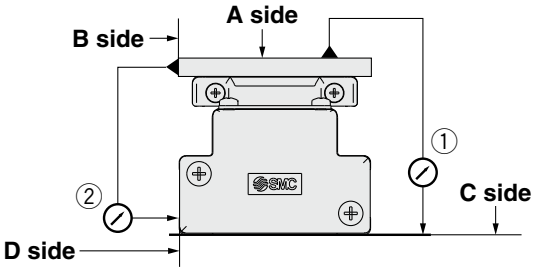
Orientation	Load overhanging direction **m**: Work load [kg] **Me**: Dynamic allowable moment [N·m] **L**: Overhang to the work load center of gravity [mm]		Model		
			LEFS25□	**LEFS32□**	**LEFS40□**
Horizontal		Pitching			
		Yawing			
		Rolling			
Vertical		Pitching			
		Yawing			

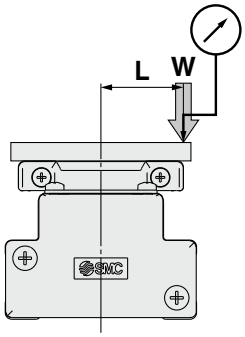
Table Accuracy

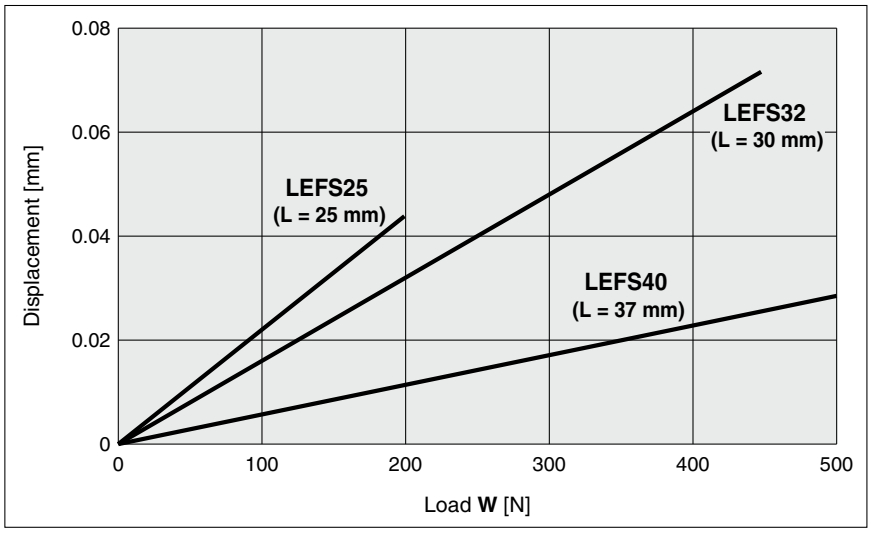


Model	Traveling parallelism [mm] (Every 300 mm)	
	① C side traveling parallelism to A side	② D side traveling parallelism to B side
LEFS25	0.05	0.03
LEFS32	0.05	0.03
LEFS40	0.05	0.03

Note) Traveling parallelism does not include the mounting surface accuracy.

Table Displacement (Reference Value)





Note 1) This displacement is measured when a 15 mm aluminum plate is mounted and fixed on the table.
Note 2) Please confirm the clearance and play of the guide separately.

Model Selection

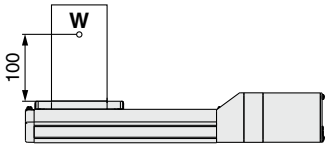
Selection Procedure

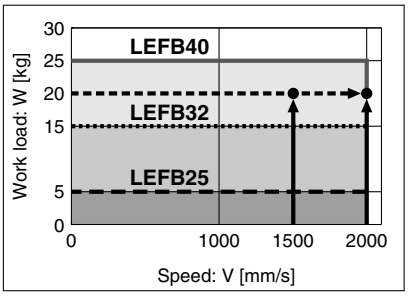
Step 1 Check the work load–speed. → **Step 2** Check the cycle time. → **Step 3** Check the allowable moment.

Selection Example

Operating conditions

- Workpiece mass: 20 [kg]
- Speed: 1,500 [mm/s]
- Acceleration/Deceleration: 3,000 [mm/s^2]
- Stroke: 2,000 [mm]
- Mounting position: Horizontal upward
- Workpiece mounting condition:





<Speed–Work load graph> (LEFB40)

Step 1 Check the work load–speed. <Speed–Work load graph>

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the <Speed–Work load graph> on page 10.

Selection example) The **LEFB40S4S-2000** is temporarily selected based on the graph shown on the right side.

Step 2 Check the cycle time.

Calculate the cycle time using the following calculation method.

Cycle time:

T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1: Acceleration time and T3: Deceleration time can be obtained by the following equation.

$$T1 = V/a1 \text{ [s]} \qquad T3 = V/a2 \text{ [s]}$$

- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4: Settling time varies depending on the conditions such as motor types, load and in positioning of the step data. Therefore, please calculate the settling time with reference to the following value.

$$T4 = 0.05 \text{ [s]}$$

∗ The conditions for the settling time vary depending on the AC servo motor or driver to be used.

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 1500/3000 = 0.5$ [s],

$T3 = V/a2 = 1500/3000 = 0.5$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{2000 - 0.5 \cdot 1500 \cdot (0.5 + 0.5)}{1500} = 0.83 \text{ [s]}$$

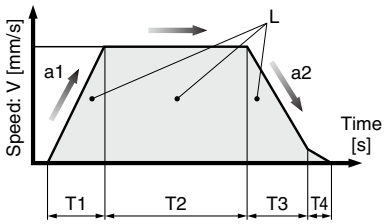
$T4 = 0.05$ [s]

Therefore, the cycle time can be obtained as follows.

$T = T1 + T2 + T3 + T4$

$= 0.5 + 0.83 + 0.5 + 0.05$

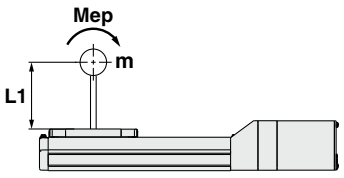
$=$ **1.88 [s]**

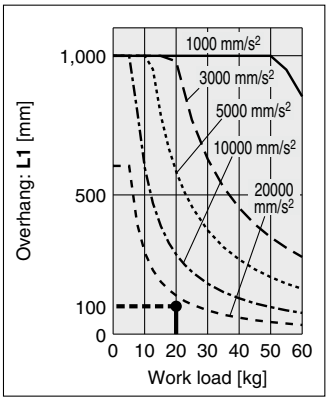


L : Stroke [mm]
··· (Operating condition)
V : Speed [mm/s]
··· (Operating condition)
a1: Acceleration [mm/s^2]
··· (Operating condition)
a2: Deceleration [mm/s^2]
··· (Operating condition)

T1: Acceleration time [s]
Time until reaching the set speed
T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
T4: Settling time [s]
Time until in position is completed

Step 3 Check the guide moment.



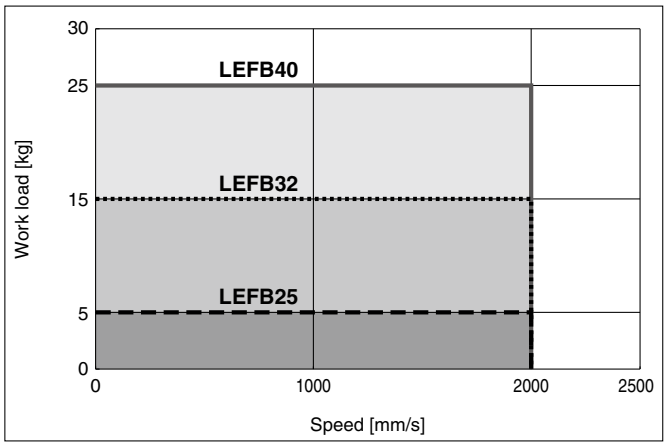


Based on the above calculation result, the LEFB40S4S-2000 is selected.

∗ The values shown below are allowable values of the actuator body.
Do not use the actuator so that it exceeds these specification ranges.

Speed–Work Load Graph (Guide)

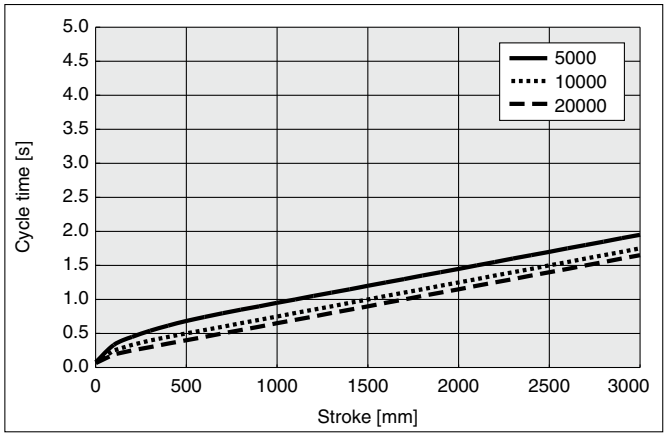
LEFB□/Belt Drive



Cycle Time Graph (Guide)

LEFB□/Belt Drive

LEFB25/32/40

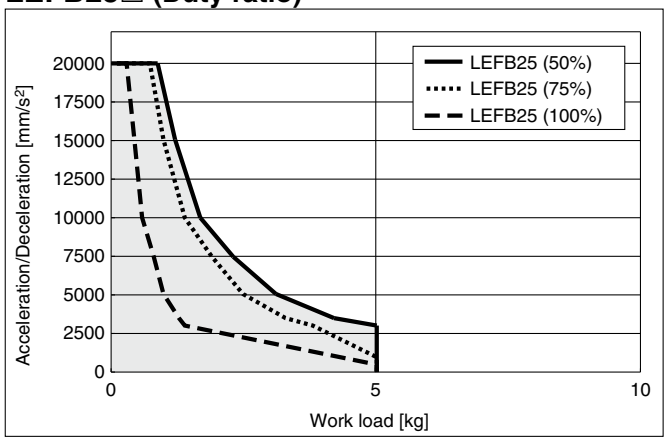


∗ Cycle time is for when maximum speed.
∗ Maximum stroke: LEFB25: 2000 mm
LEFB32: 2500 mm
LEFB40: 3000 mm

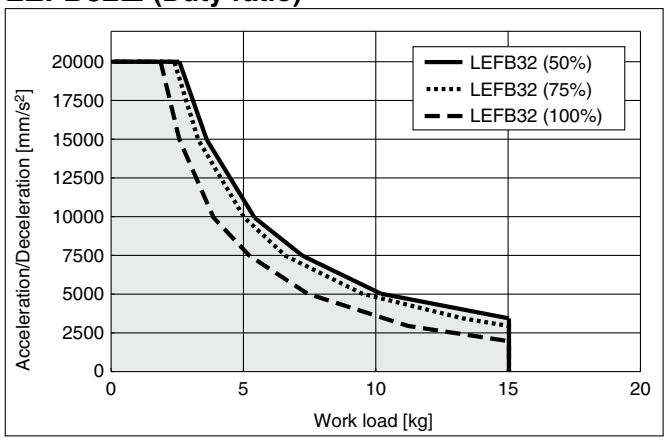
Work Load–Acceleration/Deceleration Graph (Guide)

LEFB□/Belt Drive

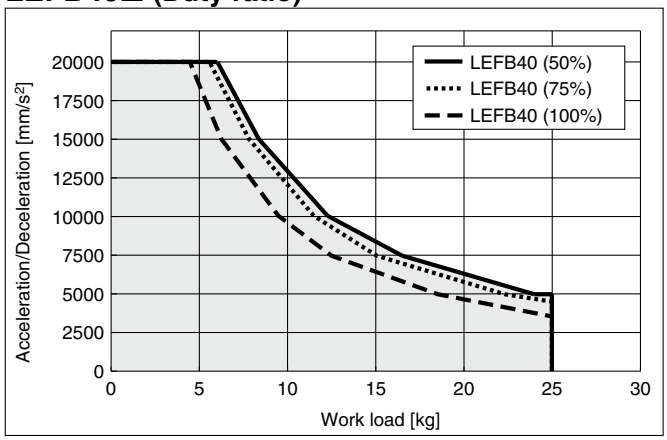
LEFB25□ (Duty ratio)



LEFB32□ (Duty ratio)



LEFB40□ (Duty ratio)



**These graphs are reference examples of when an SMC standard AC servo motor is mounted.
Determine the duty ratio after taking into account the load factor of the AC servo motor or driver to be used.
The values show the specifications with a standard SMC motor used. Please use this as a guide.**

Dynamic Allowable Moment

* This graph shows the amount of allowable overhang when the center of gravity of the workpiece overhangs in one direction. When the center of gravity of the workpiece overhangs in two directions, refer to the Electric Actuator Selection Software for confirmation. http://www.smcworld.com

Acceleration/Deceleration ——1,000 mm/s² — — —3,000 mm/s² ·····5,000 mm/s² —·—·—10,000 mm/s² - - - - 20,000 mm/s²

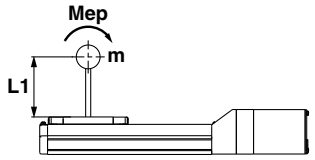
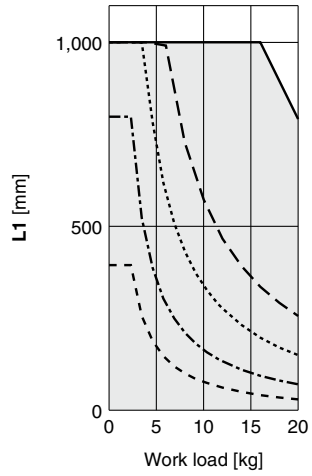
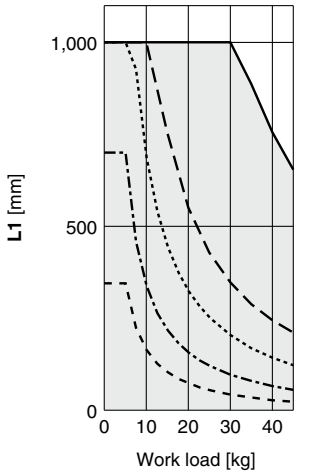
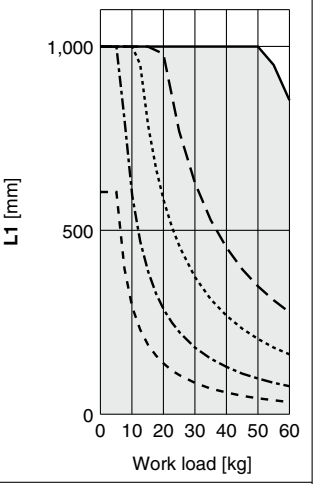
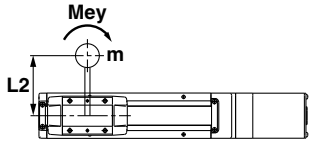
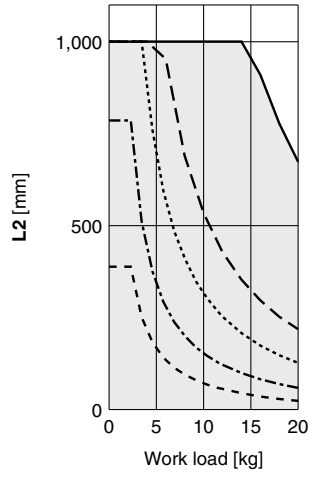
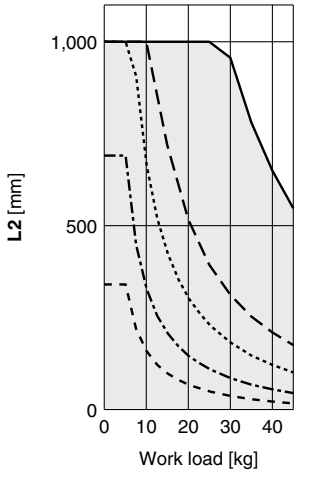
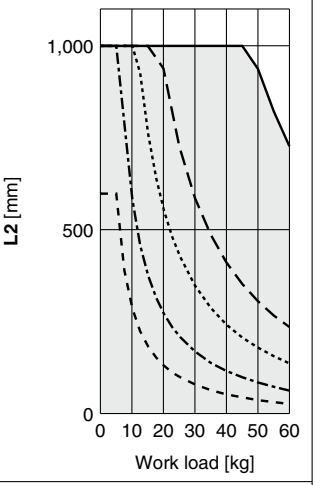
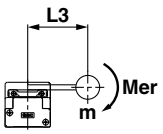
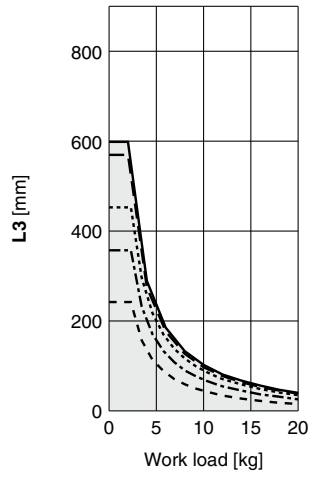
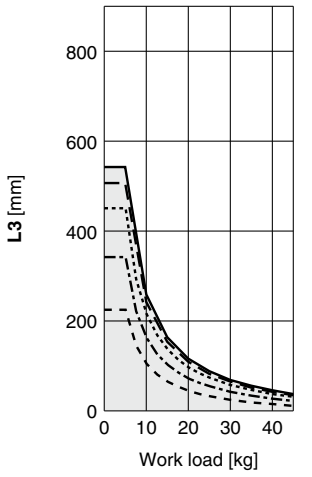
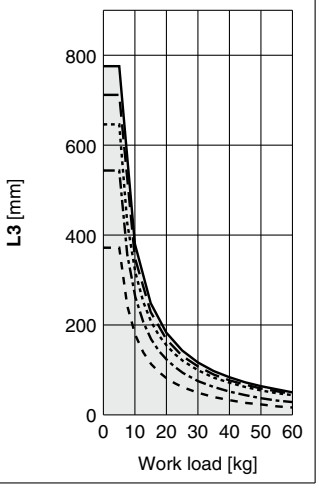
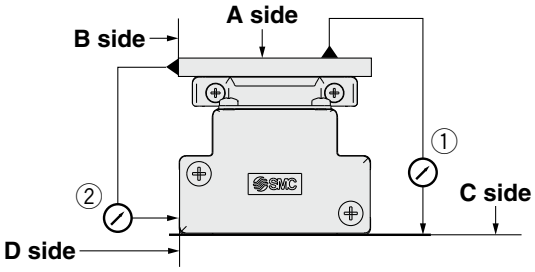
Orientation	Load overhanging direction **m**: Work load [kg] **Me**: Dynamic allowable moment [N·m] **L**: Overhang to the work load center of gravity [mm]		Model LEFB25□	Model LEFB32□	Model LEFB40□
Horizontal		Pitching			
		Yawing			
		Rolling			

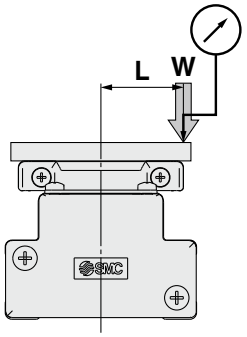
Table Accuracy

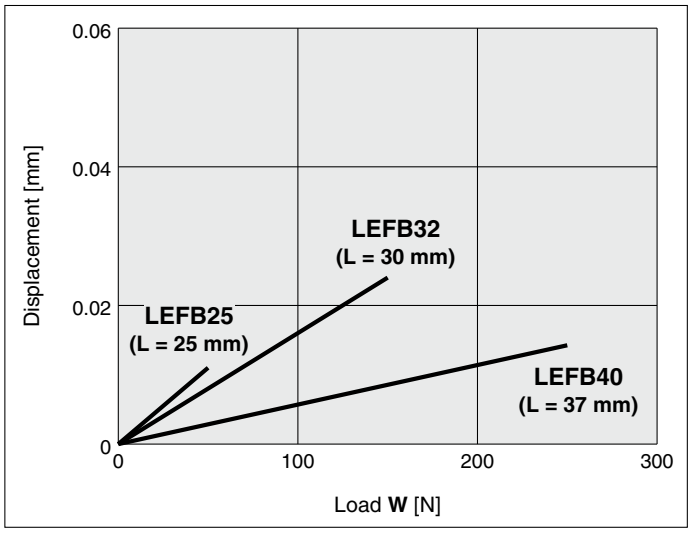


Model	Traveling parallelism [mm] (Every 300 mm)	
	① C side traveling parallelism to A side	② D side traveling parallelism to B side
LEFB25	0.05	0.03
LEFB32	0.05	0.03
LEFB40	0.05	0.03

Note) Traveling parallelism does not include the mounting surface accuracy.

Table Displacement (Reference Value)

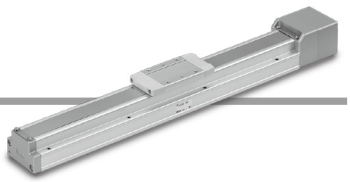




Note 1) This displacement is measured when a 15 mm aluminum plate is mounted and fixed on the table.
Note 2) Please confirm the clearance and play of the guide separately.

Electric Actuator/Slider Type
Ball Screw Drive Motorless Type
Series LEFS
LEFS25, 32, 40

RoHS



How to Order

LEFS 25 NZ A – 100
❶ ❷ ❸ ❹

❶ Size

25
32
40

❷ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y

∗ Refer to the “Compatible Motors”.
∗ When no motor flange is required, use "NN" for the motor type symbol. Please order “motor flange option” on page 18 separately.

❸ Lead [mm]

Symbol	LEFS25	LEFS32	LEFS40
A	12	16	20
B	6	8	10

❹ Stroke [mm]

100	100
to	to
1000	1000

∗ Refer to the applicable stroke table.

∗ Applicable stroke table ●Standard

Model \ Stroke (mm)	100	200	300	400	500	600	700	800	900	1000
LEFS25	●	●	●	●	●	●	—	—	—	—
LEFS32	●	●	●	●	●	●	●	●	—	—
LEFS40	—	●	●	●	●	●	●	●	●	●

∗ Consult with SMC for non-standard strokes as they are produced as special orders.

Compatible Motors

Applicable motor model			Size/Motor type					
			25		32		40	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—	●	—
	MELSERVO-J3	HF-KP						
	MELSERVO-J4	HG-KR						
YASKAWA Electric Corporation	Σ-V	SGMJV						
SANYO DENKI CO., LTD.	SANMOTION R	R2						
OMRON Corporation	Sysmac G5	R88M-K			—	●	—	●
Panasonic Corporation	MINAS-A4	MSMD	—					
	MINAS-A5	MSMD/MHMD						

Specifications Note 1) Note 2) Note 3) Note 4) Note 5)

LEFS25/32/40 AC Servo Motor

Model				LEFS25		LEFS32		LEFS40	
Actuator specifications	Stroke [mm]			100, 200, 300, 400 500, 600		100, 200, 300, 400 500, 600, 700, 800		200, 300, 400, 500, 600 700, 800, 900, 1000	
	Work load [kg]		Horizontal	20	20	40	45	50	60
			Vertical	8	15	10	20	15	30
	Speed [mm/s] * The values shown in ( ) are motor rotation speed.	Stroke range	Up to 400	900 (4500 [rpm])	450 (4500 [rpm])	1000 (3750 [rpm])	500 (3750 [rpm])	1000 (3000 [rpm])	500 (3000 [rpm])
			401 to 500	720 (3600 [rpm])	360 (3600 [rpm])	1000 (3750 [rpm])	500 (3750 [rpm])	1000 (3000 [rpm])	500 (3000 [rpm])
			501 to 600	540 (2700 [rpm])	270 (2700 [rpm])	800 (3000 [rpm])	400 (3000 [rpm])	1000 (3000 [rpm])	500 (3000 [rpm])
			601 to 700	—	—	620 (2325 [rpm])	310 (2325 [rpm])	940 (2820 [rpm])	470 (2820 [rpm])
			701 to 800	—	—	500 (1875 [rpm])	250 (1875 [rpm])	760 (2280 [rpm])	380 (2280 [rpm])
			801 to 900	—	—	—	—	620 (1860 [rpm])	310 (1860 [rpm])
			901 to 1000	—	—	—	—	520 (1560 [rpm])	260 (1560 [rpm])
	Pushing return to origin speed [mm/s]			30 or less					
	Positioning repeatability [mm]			±0.02					
	Ball screw specifications		Thread size [mm]	ø10		ø12		ø15	
			Lead [mm]	12	6	16	8	20	10
			Shaft length [mm]	Stroke + 150		Stroke + 185		Stroke + 235	
	Max. acceleration/deceleration [mm/s²]			20000 Note 6)					
	Impact/Vibration resistance [m/s²]			50/20					
	Actuation type			Ball screw					
	Guide type			Linear guide					
	Operating temperature range [°C]			5 to 40					
	Operating humidity range [%]			90 RH or less (No condensation)					
Applicable motor specifications	Motor shape			□40		□60			
	Motor type			AC servo motor (100 V/200 V)					
	Rated output capacity [W]			100		200		400	
	Rated torque [N·m]			0.32		0.64		1.3	
	Rated rotation [rpm]			3000					
Other specifications Note 7)	Actuation unit weight [kg]			0.2		0.3		0.55	
	Other inertia [kg·cm²]			0.02		0.08		0.08	
	Friction coefficient			0.05					
	Mechanical efficiency			0.8					

Note 1) These specifications are allowable values of the actuator body. Do not use the actuator so that it exceeds these values.
Note 2) When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
Note 3) This product does not include the motor and motor mounting bolts. (Provided by customer)
For the shaft-end shape of the motor, please prepare the round type.
Note 4) Take loose prevention measures for the motor mounting bolts.
Note 5) Do not allow collisions at either end of the table traveling distance at a speed exceeding “pushing return to origin speed”.
Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 6) Maximum acceleration/deceleration changes according to the work load.
Refer to “Work Load–Acceleration/Deceleration Graph” for ball screw drive on page 5.
Note 7) Each value is a guide. Use such value to select a motor capacity.

Weight

Series	LEFS25					
Stroke [mm]	100	200	300	400	500	600
Product weight [kg]	1.70	2.00	2.25	2.55	2.80	3.10

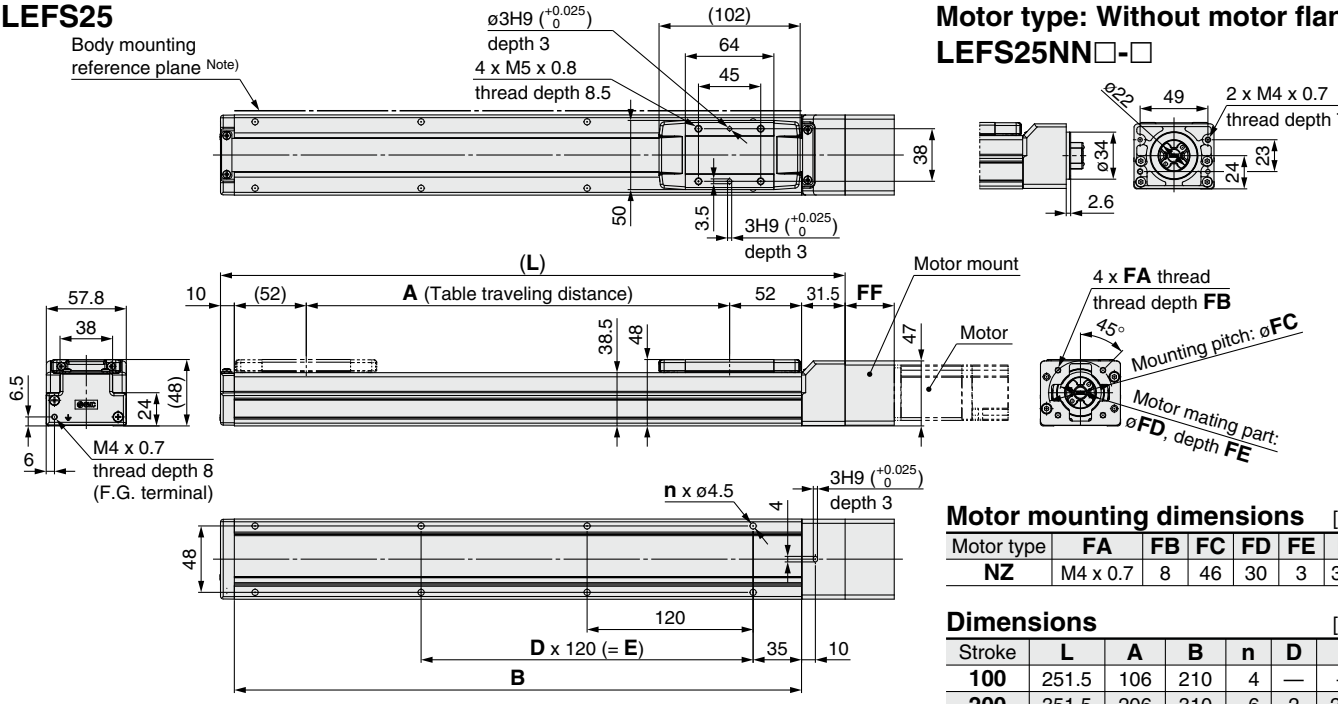
Series	LEFS32							
Stroke [mm]	100	200	300	400	500	600	700	800
Product weight [kg]	2.60	3.00	3.40	3.80	4.20	4.60	5.00	5.40

Series	LEFS40								
Stroke [mm]	200	300	400	500	600	700	800	900	1000
Product weight [kg]	4.80	5.35	5.95	6.50	6.95	7.60	8.15	8.75	9.30

Refer to "Motor Mounting" on page 17 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEFS25



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Motor type: Without motor flange LEFS25NN□-□

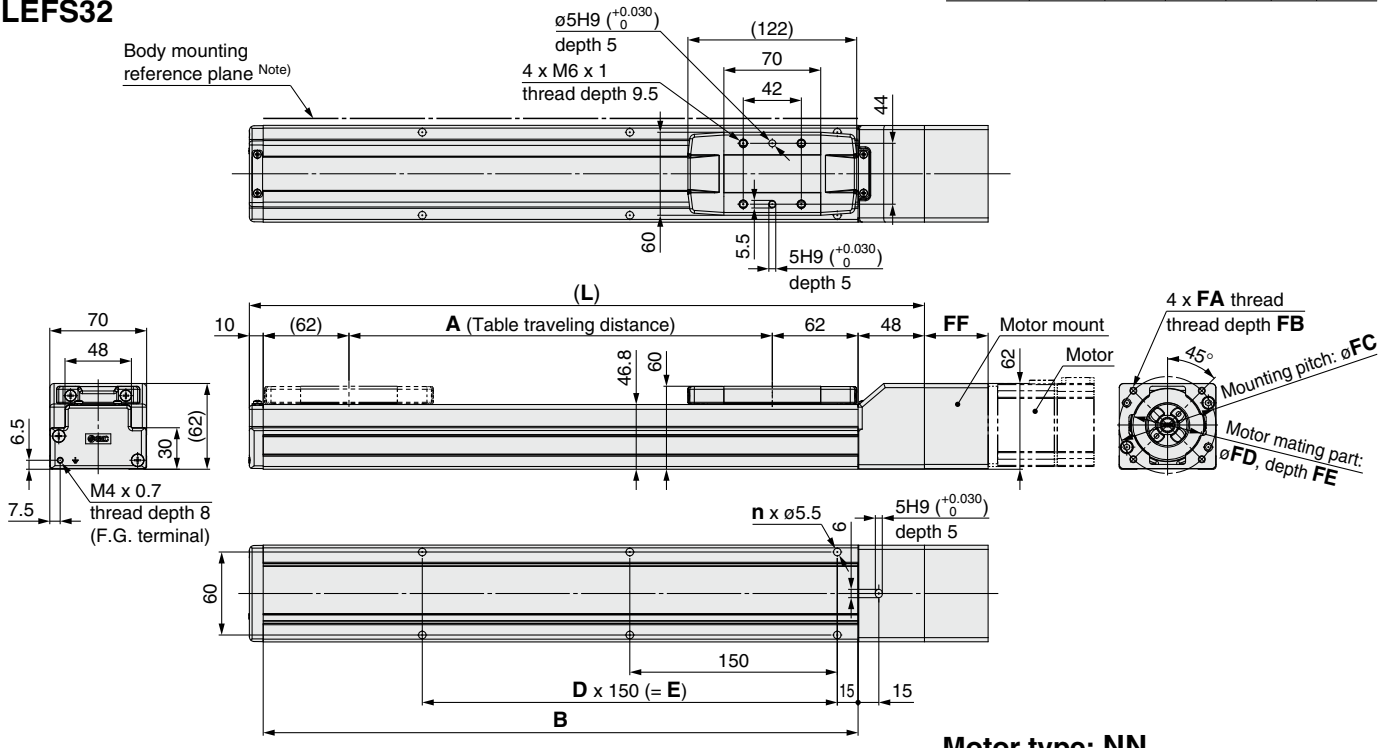
Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M4 x 0.7	8	46	30	3	35.5

Dimensions [mm]

Stroke	L	A	B	n	D	E
100	251.5	106	210	4	—	—
200	351.5	206	310	6	2	240
300	451.5	306	410	8	3	360
400	551.5	406	510	8	3	360
500	651.5	506	610	10	4	480
600	751.5	606	710	12	5	600

LEFS32



Dimensions [mm]

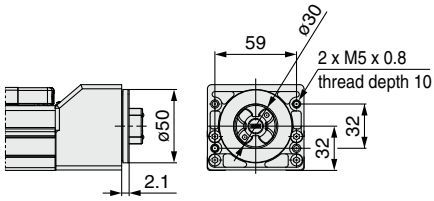
Stroke	L	A	B	n	D	E
100	288	106	230	4	—	—
200	388	206	330	6	2	300
300	488	306	430	6	2	300
400	588	406	530	8	3	450
500	688	506	630	10	4	600
600	788	606	730	10	4	600
700	888	706	830	12	5	750
800	988	806	930	14	6	900

Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	10.5	70	50	5	46
NY	M4 x 0.7	8	70	50	5	46

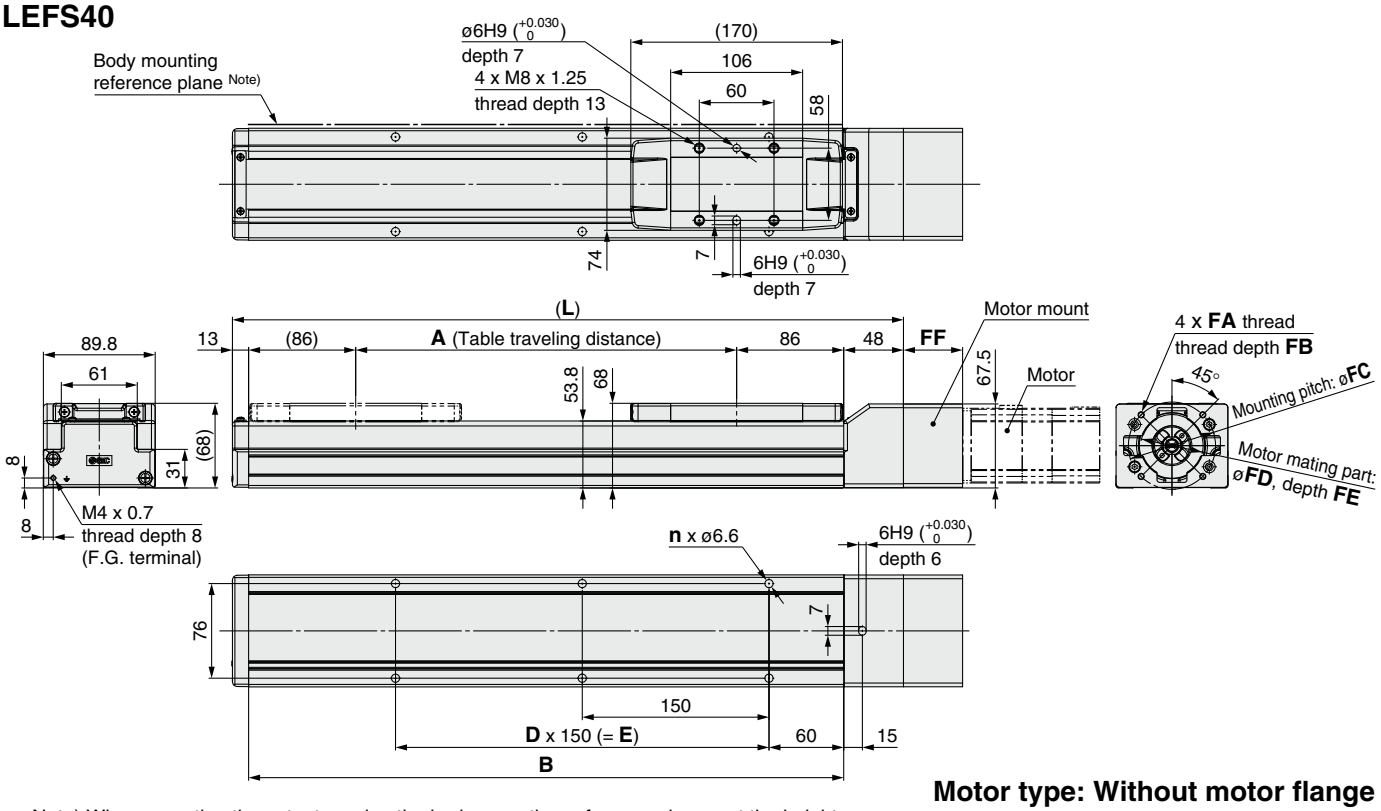
Motor type: NN Without motor flange LEFS32NN□-□



Refer to "Motor Mounting" on page 17 for details about motor mounting and included parts.

Dimensions: Ball Screw Drive

LEFS40

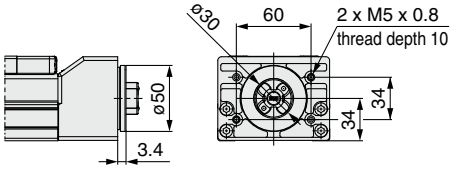


Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
200	439	206	378	6	2	300
300	539	306	478	6	2	300
400	639	406	578	8	3	450
500	739	506	678	10	4	600
600	839	606	778	10	4	600
700	939	706	878	12	5	750
800	1039	806	978	14	6	900
900	1139	906	1078	14	6	900
1000	1239	1006	1178	16	7	1050

Motor type: Without motor flange
LEFS40NN□-□



Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	10.5	70	50	5	46
NY	M4 x 0.7	8	70	50	5	46

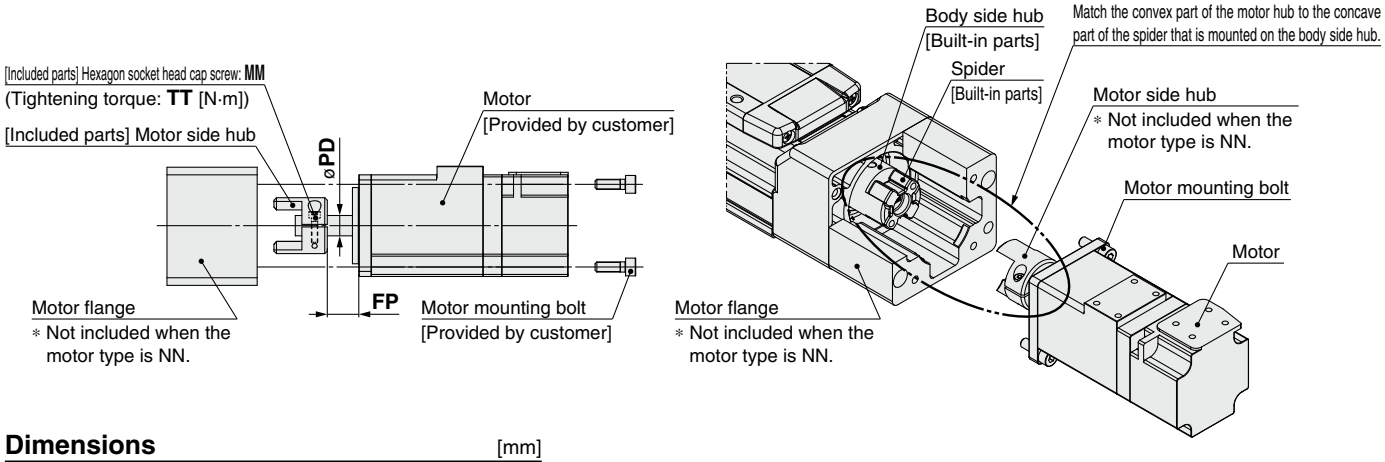
- The motor and motor mounting bolts should be provided by the customer.
- When selecting the motor type NN, no motor flange and hub include with the product. The body side hub and spider are specially designed, so order the motor flange option on page 18 separately.

Motor Mounting

Mounting procedure

1) Fix the motor (provided by customer) and the motor hub with the MM hexagon socket head cap screw.
2) Check the motor hub position, and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the motor flange with the motor mounting bolts (provided by customer).

Mounting diagram



Dimensions

[mm]

Size	Motor type	MM	TT	PD	FP
25	**NZ**	M2.5 x 10	1.0	8	12.4
32	**NZ**	M3 x 12	1.5	14	17.5
	NY	M4 x 12	2.5	11	
40	**NZ**	M3 x 12	1.5	14	17.5
	NY	M3 x 12	1.5	14	

Included Parts List

Size: 25

Description	Qty. Motor type	
	NZ	**NN**
Motor side hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Size: 32

Description	Qty. Motor type	
	NZ/NY	**NN**
Motor side hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Size: 40

Description	Qty. Motor type	
	NY/NZ	**NN**
Motor side hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Series LEFS
Motor Mounting Parts

Motor Flange Option

When the motor type "NN" is selected for the model, no motor flange for motor mounting includes with the product.
Select an applicable motor flange option according to the part number shown below, and then order it.

How to Order

LEFS – MF 25 – NZ

Ball screw drive

❶ Size

25	For LEF□25
32	For LEF□32
40	For LEF□40

❷ Motor type

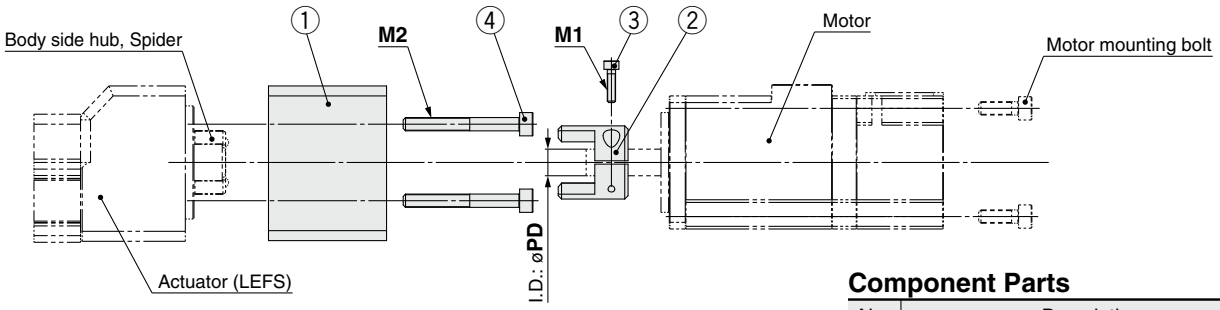
NZ	Mounting type Z
NY	Mounting type Y

∗ For LEFS-MF25, select only NZ.

Compatible Motors

Applicable motor model			Size/Motor type					
			25		**32**		**40**	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—	●	—
	MELSERVO-J3	HF-KP						
	MELSERVO-J4	HG-KR						
YASKAWA Electric Corporation	Σ-V	SGMJV						
SANYO DENKI CO., LTD.	SANMOTION R	R2						
OMRON Corporation	Sysmac G5	R88M-K						
Panasonic Corporation	MINAS-A4	MSMD	—		—	●	—	●
	MINAS-A5	MSMD/MHMD						

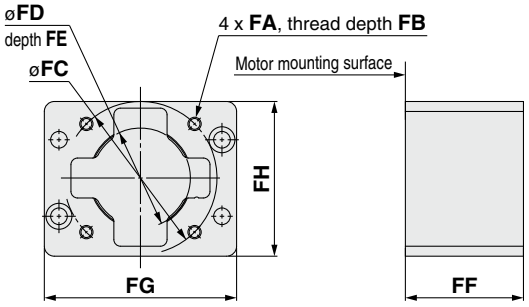
Dimensions: Motor Flange Option



Component Parts

No.	Description	Qty.
1	**Motor flange**	1
2	**Hub (Motor side)**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor flange mounting)**	2

Motor flange details



Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH	M1	M2	PD
25	**NZ**	M4 x 0.7	8	46	30	3	35.5	57.8	46.5	M2.5 x 10	M4 x 35	8
32	**NZ**	M5 x 0.8	10	70	50	5	46	69.8	61.5	M3 x 12	M5 x 40	14
	NY	M4 x 0.7	8							M4 x 12		11
40	**NZ**	M5 x 0.8	10				47.5	89.8	70	M3 x 12		14
	NY											

Electric Actuator/Slider Type
Belt Drive Motorless Type
Series LEFB
LEFB25, 32, 40

RoHS

How to Order

LEFB 25 ❶ ❷ NZ ❸ S ❹ – 100 ❺

❶ Size

25
32
40

❷ Motor mounting position

Nil	Top mounting
U	Bottom mounting

❸ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y

∗ Refer to the “Compatible Motors”.
∗ When no motor flange is required, use "NN" for the motor type symbol. Please order “motor flange option” on page 29 separately.

❹ Equivalent lead [mm]

S	54

❺ Stroke [mm]

100	100
to	to
3000	3000

∗ Refer to the applicable stroke table.

∗ Applicable stroke table

● Standard/○ Produced upon receipt of order

	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2500	3000
LEFB25	●	●	●	●	●	●	●	●	○	●	○	○	●	○	○	○	○	●	—	—
LEFB32	●	●	●	●	●	●	●	●	○	●	○	○	●	○	○	○	○	●	●	—
LEFB40	●	●	●	●	●	●	●	●	○	●	○	○	●	○	○	○	○	●	●	●

∗ Consult with SMC as all non-standard and non-made-to-order strokes are produced as special orders.

Compatible Motors

Applicable motor model			Size/Motor type					
			25		32		40	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—	●	—
	MELSERVO-J3	HF-KP						
	MELSERVO-J4	HG-KR						
YASKAWA Electric Corporation	Σ-V	SGMJV						
SANYO DENKI CO., LTD.	SANMOTION R	R2						
OMRON Corporation	Sysmac G5	R88M-K			—	●	—	●
Panasonic Corporation	MINAS-A4	MSMD	—					
	MINAS-A5	MSMD/MHMD						

Specifications Note 2) Note 3) Note 4) Note 5)

LEFB25/32/40 AC Servo Motor

Model			LEFB25	LEFB32	LEFB40
Actuator specifications	Stroke [mm] Note 1)		300, 400, 500 600, 700, 800 900, 1000, (1100) 1200, (1300, 1400) 1500, (1600, 1700) (1800, 1900), 2000	300, 400, 500 600, 700, 800 900, 1000, (1100) 1200, (1300, 1400) 1500, (1600, 1700) (1800, 1900), 2000 2500	300, 400, 500 600, 700, 800 900, 1000, (1100) 1200, (1300, 1400) 1500, (1600, 1700) (1800, 1900), 2000 2500, 3000
	Work load [kg]	Horizontal	5	15	25
	Speed [mm/s] ∗ The value shown in ( ) is motor rotation speed.		2000 (2222 [rpm])		
	Pushing return to origin speed [mm/s]		30 or less		
	Positioning repeatability [mm]		±0.08		
	Equivalent lead [mm]		54		
	Max. acceleration/deceleration [mm/s²]		20000 Note 6)		
	Impact/Vibration resistance [m/s²]		50/20		
	Actuation type		Belt		
	Guide type		Linear guide		
	Operating temperature range [°C]		5 to 40		
	Operating humidity range [%]		90 RH or less (No condensation)		
Applicable motor specifications	Motor shape		□40	□60	
	Motor type		AC servo motor (100 V/200 V)		
	Rated output capacity [W]		100	200	400
	Rated torque [N·m]		0.32	0.64	1.3
	Rated rotation [rpm]		3000		
Other specifications	Actuation unit weight [kg]		0.2	0.3	0.55
	Other inertia [kg·cm²]		0.1	0.2	0.25
	Friction coefficient		0.05		
	Mechanical efficiency		0.8		

Note 1) These specifications are allowable values of the actuator body. Do not use the actuator so that it exceeds these values.
Note 2) When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
Note 3) This product does not include the motor and motor mounting bolts. (Provided by customer)
For the shaft-end shape of the motor, please prepare the round type.
Note 4) Take loose prevention measures for the motor mounting bolts.
Note 5) Do not allow collisions at either end of the table traveling distance at a speed exceeding “pushing return to origin speed”.
Additionally, when running the positioning operation, do not set within 3 mm of both ends.
Note 6) Maximum acceleration/deceleration changes according to the work load.
Refer to “Work Load–Acceleration/Deceleration Graph” for belt drive on page 10.

Weight

Series	LEFB25																	
Stroke [mm]	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
Product weight [kg]	2.5	2.75	3	3.25	3.5	3.75	4	4.25	4.5	4.75	5	5.25	5.5	5.75	6	6.25	6.5	6.75

Series	LEFB32																		
Stroke [mm]	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2500
Product weight [kg]	4.00	4.35	4.70	5.05	5.40	5.75	6.10	6.45	6.80	7.15	7.50	7.85	8.20	8.55	8.90	9.25	9.60	9.95	11.70

Series	LEFB40																			
Stroke [mm]	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2500	3000
Product weight [kg]	5.70	6.15	6.60	7.05	7.50	7.95	8.40	8.85	9.30	9.75	10.20	10.65	11.10	11.55	12.00	12.45	12.90	13.35	15.60	17.85

Handling

⚠Caution

1. The belt drive actuator cannot be used vertically for applications.

2. In the case of the belt drive actuator, vibration may occur during operation at speeds within the actuator specifications, this could be caused by the operating conditions. Change the speed setting to a speed that does not cause vibration.

Maintenance

⚠Warning

Maintenance frequency

Perform maintenance according to the table below.

Frequency	Appearance check	Internal check	Belt check
Inspection before daily operation	○	—	—
Inspection every 6 months/1000 km/ 5 million cycles*	○	○	○

* Select whichever comes sooner.

● Items for visual appearance check

1. Loose set screws, Abnormal dirt
2. Check of flaw and cable joint
3. Vibration, Noise

Maintenance

⚠Warning

● Items for internal check

1. Lubricant condition on moving parts.
2. Loose or mechanical play in fixed parts or fixing screws.

● Items for belt check

Stop operation immediately and replace the belt when belt appear to be below. Further, ensure your operating environment and conditions satisfy the requirements specified for the product.

a. Tooth shape canvas is worn out.
Canvas fiber becomes fuzzy. Rubber is removed and the fiber becomes whitish. Lines of fibers become unclear.

b. Peeling off or wearing of the side of the belt
Belt corner becomes round and frayed thread sticks out.

c. Belt partially cut
Belt is partially cut. Foreign matter caught in teeth other than cut part causes flaw.

d. Vertical line of belt teeth
Flaw which is made when the belt runs on the flange.

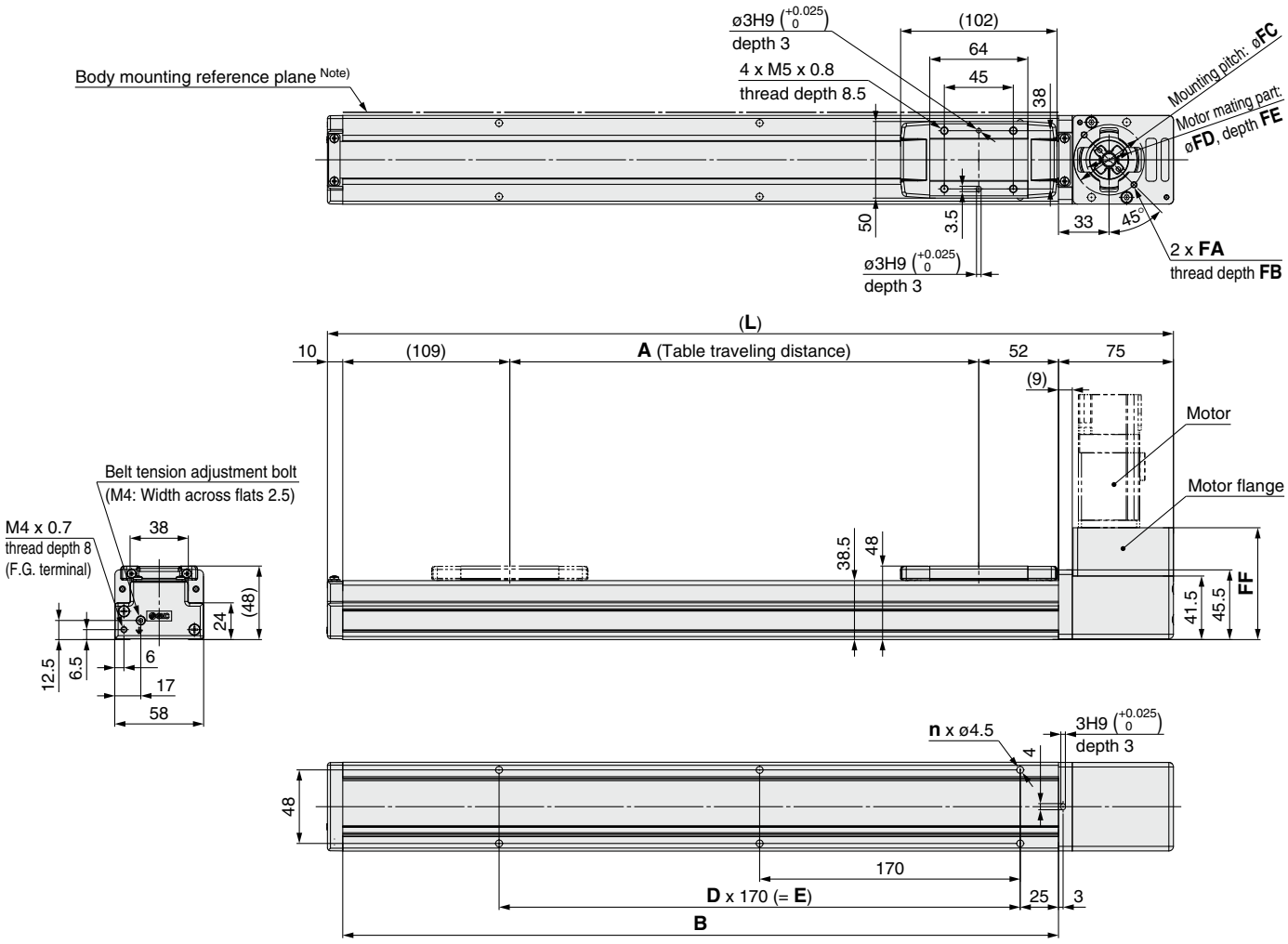
e. Rubber back of the belt is softened and sticky.

f. Crack on the back of the belt

Refer to "Motor Mounting" on page 28 for details about motor mounting and included parts.

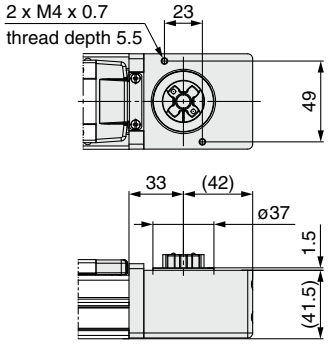
Dimensions: Belt Drive

LEFB25/Motor top mounting type



Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Motor type: NN Without motor flange
LEFB25NNS-□



Dimensions [mm]

Stroke	L	A	B	n	D	E
300	552	306	467	6	2	340
400	652	406	567	8	3	510
500	752	506	667	8	3	510
600	852	606	767	10	4	680
700	952	706	867	10	4	680
800	1052	806	967	12	5	850
900	1152	906	1067	14	6	1020
1000	1252	1006	1167	14	6	1020
1100	1352	1106	1267	16	7	1190
1200	1452	1206	1367	16	7	1190
1300	1552	1306	1467	18	8	1360
1400	1652	1406	1567	20	9	1530
1500	1752	1506	1667	20	9	1530
1600	1852	1606	1767	22	10	1700
1700	1952	1706	1867	22	10	1700
1800	2052	1806	1967	24	11	1870
1900	2152	1906	2067	24	11	1870
2000	2252	2006	2167	26	12	2040

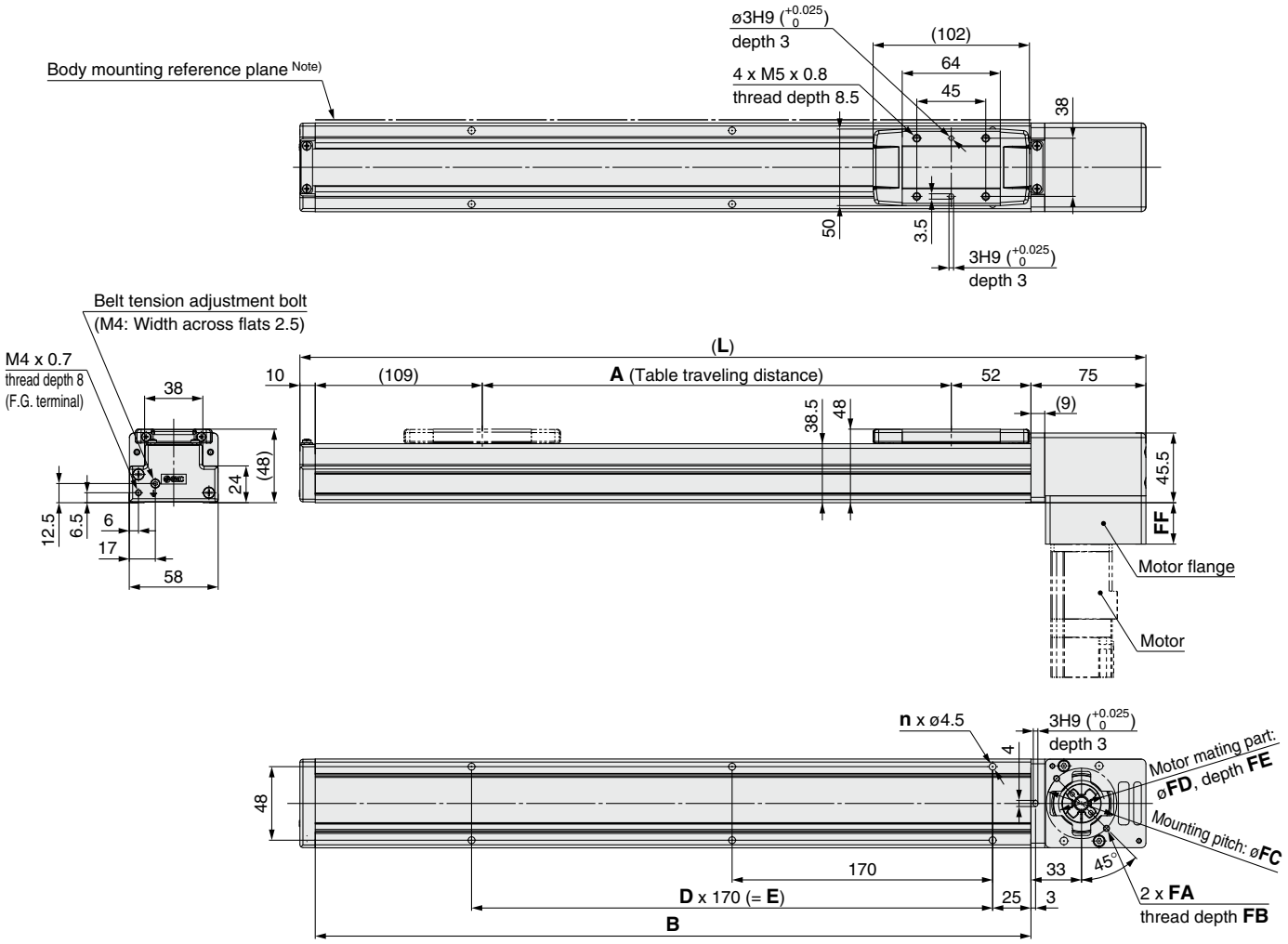
Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M4 x 0.7	8	46	30	3	73

Refer to "Motor Mounting" on page 28 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB25U/Motor bottom mounting type

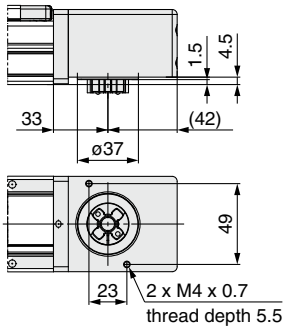


Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
300	552	306	467	6	2	340
400	652	406	567	8	3	510
500	752	506	667	8	3	510
600	852	606	767	10	4	680
700	952	706	867	10	4	680
800	1052	806	967	12	5	850
900	1152	906	1067	14	6	1020
1000	1252	1006	1167	14	6	1020
1100	1352	1106	1267	16	7	1190
1200	1452	1206	1367	16	7	1190
1300	1552	1306	1467	18	8	1360
1400	1652	1406	1567	20	9	1530
1500	1752	1506	1667	20	9	1530
1600	1852	1606	1767	22	10	1700
1700	1952	1706	1867	22	10	1700
1800	2052	1806	1967	24	11	1870
1900	2152	1906	2067	24	11	1870
2000	2252	2006	2167	26	12	2040

Motor type: NN Without motor flange
LEFB25UNNS-□



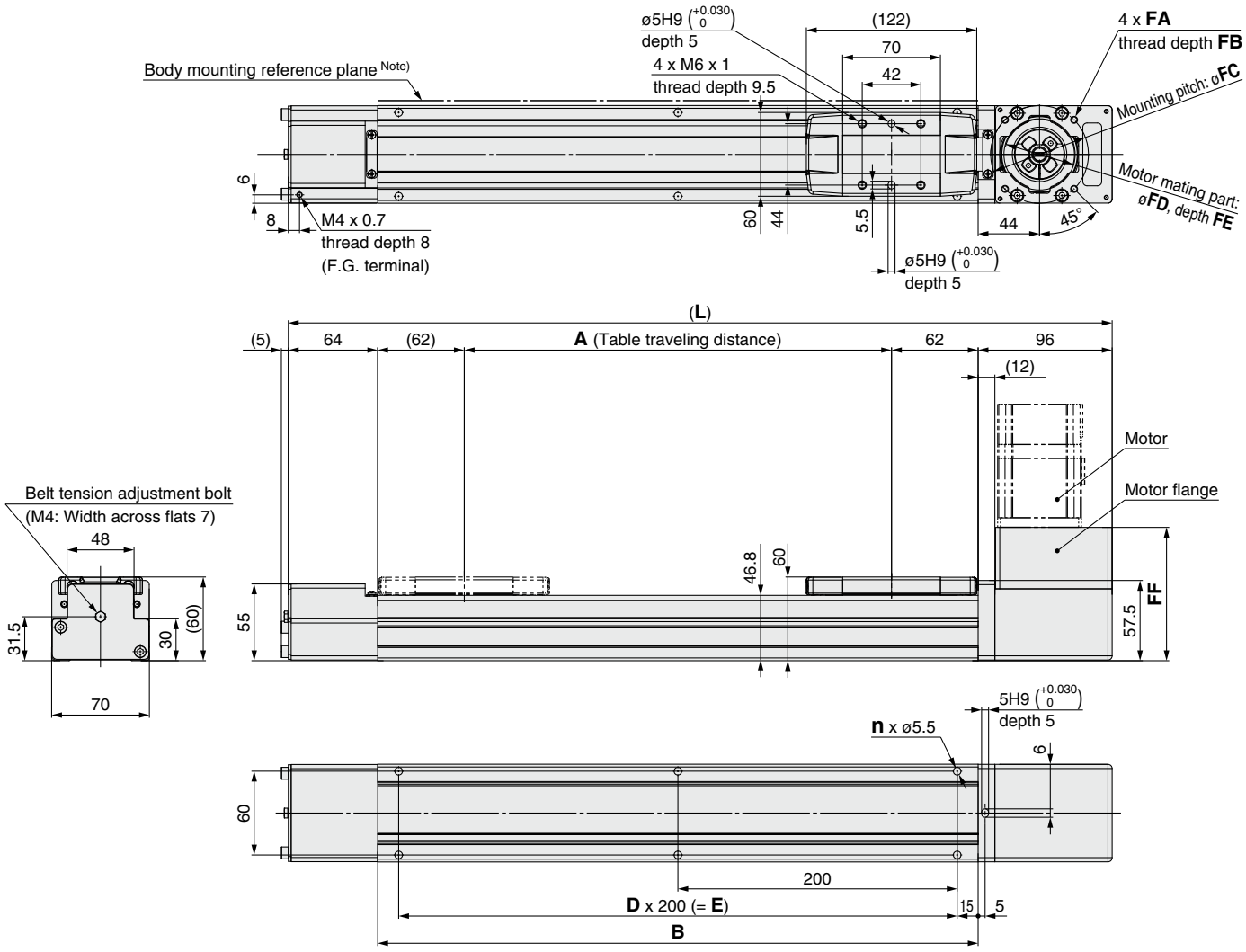
Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M4 x 0.7	8	46	30	3	27

Refer to "Motor Mounting" on page 28 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB32/Motor top mounting type

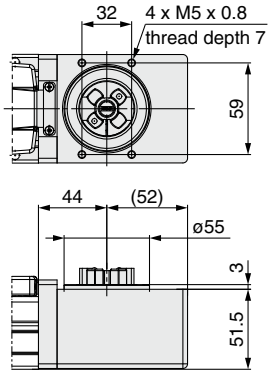


Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
300	590	306	430	6	2	400
400	690	406	530	6	2	400
500	790	506	630	8	3	600
600	890	606	730	8	3	600
700	990	706	830	10	4	800
800	1090	806	930	10	4	800
900	1190	906	1030	12	5	1000
1000	1290	1006	1130	12	5	1000
1100	1390	1106	1230	14	6	1200
1200	1490	1206	1330	14	6	1200
1300	1590	1306	1430	16	7	1400
1400	1690	1406	1530	16	7	1400
1500	1790	1506	1630	18	8	1600
1600	1890	1606	1730	18	8	1600
1700	1990	1706	1830	20	9	1800
1800	2090	1806	1930	20	9	1800
1900	2190	1906	2030	22	10	2000
2000	2290	2006	2130	22	10	2000
2500	2790	2506	2630	28	13	2600

Motor type: NN Without motor flange
LEFB32NNS-□



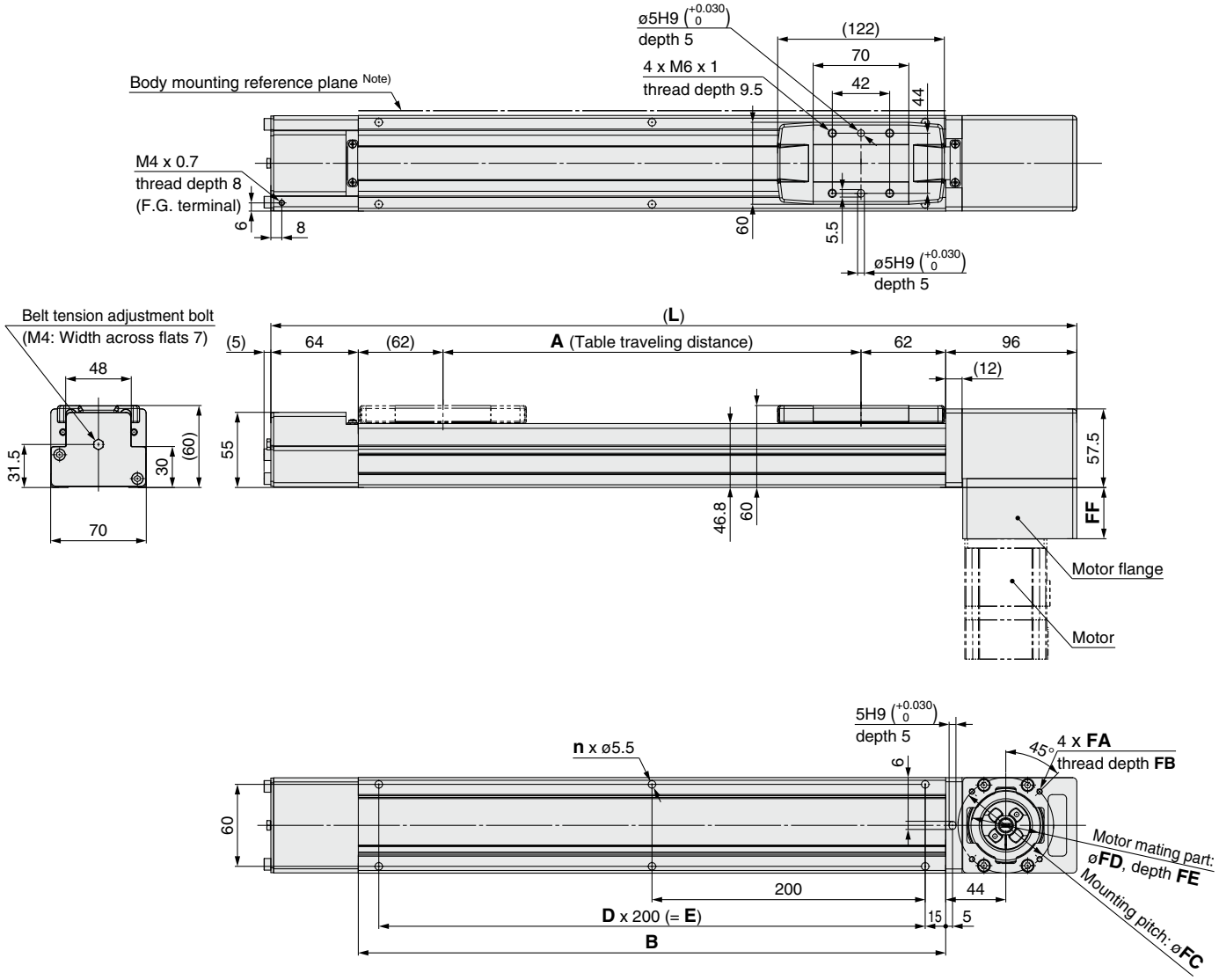
Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	95.5
NY	M4 x 0.7	8	70	50	4	95.5

Refer to "Motor Mounting" on page 28 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB32U/Motor bottom mounting type

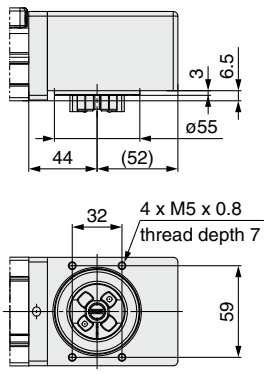


Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
300	590	306	430	6	2	400
400	690	406	530	6	2	400
500	790	506	630	8	3	600
600	890	606	730	8	3	600
700	990	706	830	10	4	800
800	1090	806	930	10	4	800
900	1190	906	1030	12	5	1000
1000	1290	1006	1130	12	5	1000
1100	1390	1106	1230	14	6	1200
1200	1490	1206	1330	14	6	1200
1300	1590	1306	1430	16	7	1400
1400	1690	1406	1530	16	7	1400
1500	1790	1506	1630	18	8	1600
1600	1890	1606	1730	18	8	1600
1700	1990	1706	1830	20	9	1800
1800	2090	1806	1930	20	9	1800
1900	2190	1906	2030	22	10	2000
2000	2290	2006	2130	22	10	2000
2500	2790	2506	2630	28	13	2600

Motor type: NN Without motor flange
LEFB32UNNS-□



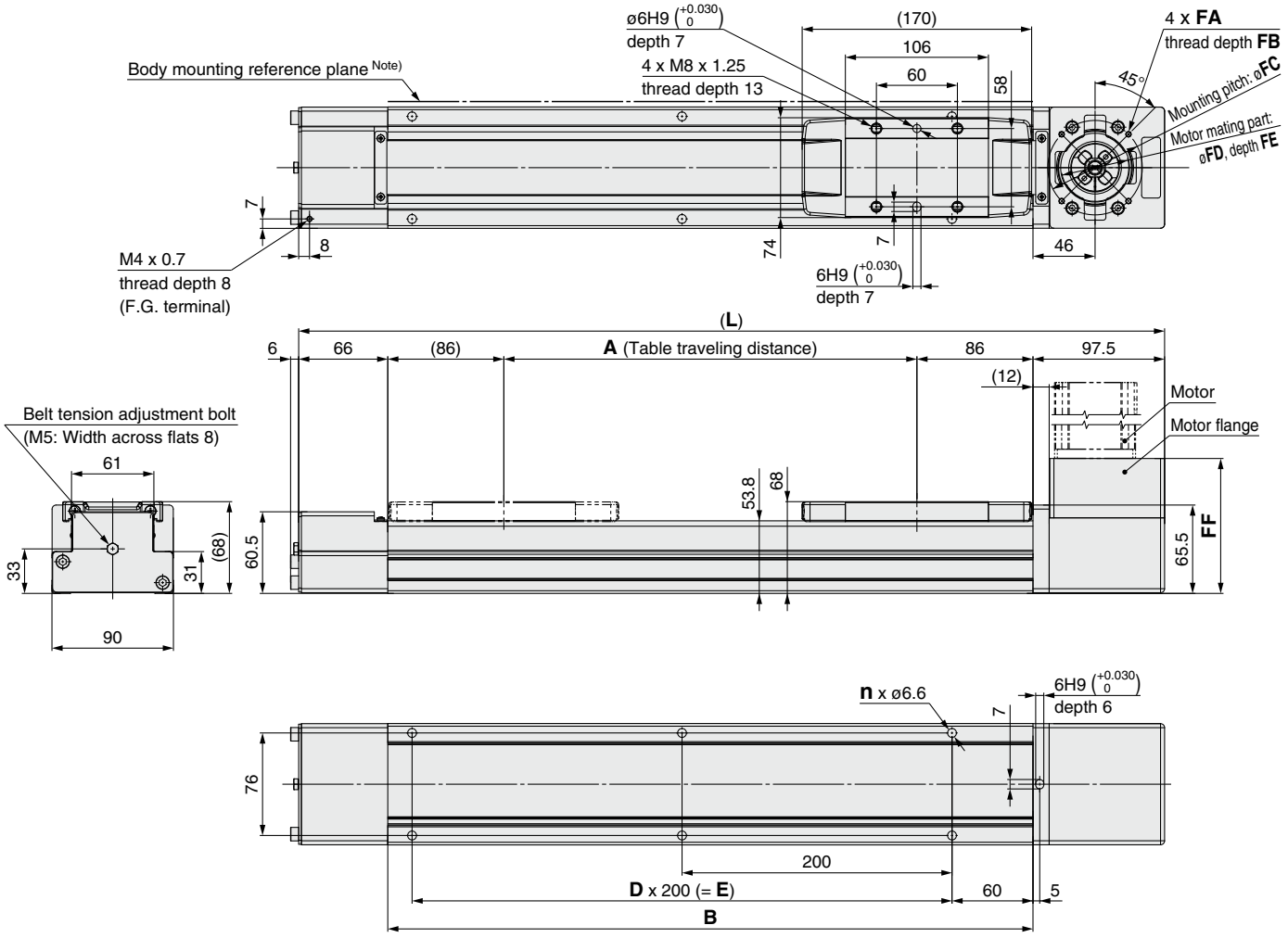
Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	37.5
NY	M4 x 0.7	8	70	50	4	37.5

Refer to "Motor Mounting" on page 28 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB40/Motor top mounting type

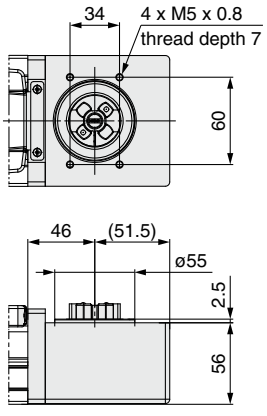


Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions [mm]

Stroke	L	A	B	n	D	E
300	641.5	306	478	6	2	400
400	741.5	406	578	6	2	400
500	841.5	506	678	8	3	600
600	941.5	606	778	8	3	600
700	1041.5	706	878	10	4	800
800	1141.5	806	978	10	4	800
900	1241.5	906	1078	12	5	1000
1000	1341.5	1006	1178	12	5	1000
1100	1441.5	1106	1278	14	6	1200
1200	1541.5	1206	1378	14	6	1200
1300	1641.5	1306	1478	16	7	1400
1400	1741.5	1406	1578	16	7	1400
1500	1841.5	1506	1678	18	8	1600
1600	1941.5	1606	1778	18	8	1600
1700	2041.5	1706	1878	20	9	1800
1800	2141.5	1806	1978	20	9	1800
1900	2241.5	1906	2078	22	10	2000
2000	2341.5	2006	2178	22	10	2000
2500	2841.5	2506	2678	28	13	2600
3000	3341.5	3006	3178	32	15	3000

Motor type: NN Without motor flange
LEFB40NNS-□



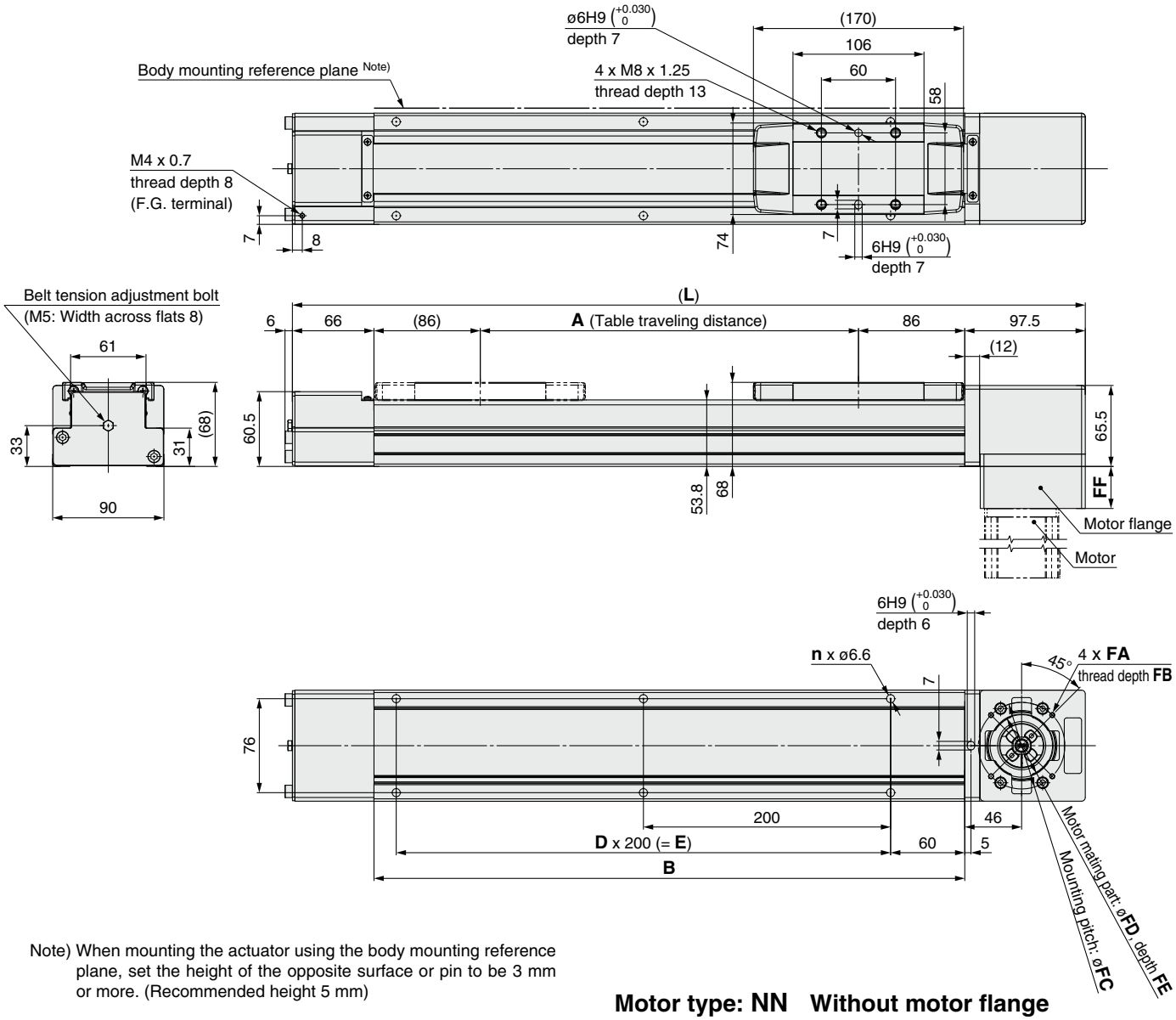
Motor mounting dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	100
NY	M4 x 0.7	8	70	50	4	100

Refer to "Motor Mounting" on page 28 for details about motor mounting and included parts.

Dimensions: Belt Drive

LEFB40U/Motor bottom mounting type



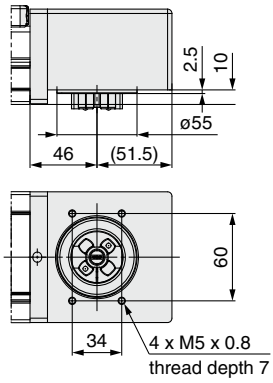
Note) When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height 5 mm)

Dimensions

[mm]

Stroke	L	A	B	n	D	E
300	641.5	306	478	6	2	400
400	741.5	406	578	6	2	400
500	841.5	506	678	8	3	600
600	941.5	606	778	8	3	600
700	1041.5	706	878	10	4	800
800	1141.5	806	978	10	4	800
900	1241.5	906	1078	12	5	1000
1000	1341.5	1006	1178	12	5	1000
1100	1441.5	1106	1278	14	6	1200
1200	1541.5	1206	1378	14	6	1200
1300	1641.5	1306	1478	16	7	1400
1400	1741.5	1406	1578	16	7	1400
1500	1841.5	1506	1678	18	8	1600
1600	1941.5	1606	1778	18	8	1600
1700	2041.5	1706	1878	20	9	1800
1800	2141.5	1806	1978	20	9	1800
1900	2241.5	1906	2078	22	10	2000
2000	2341.5	2006	2178	22	10	2000
2500	2841.5	2506	2678	28	13	2600
3000	3341.5	3006	3178	32	15	3000

Motor type: NN Without motor flange
LEFB40UNNS-□



Motor mounting dimensions

[mm]

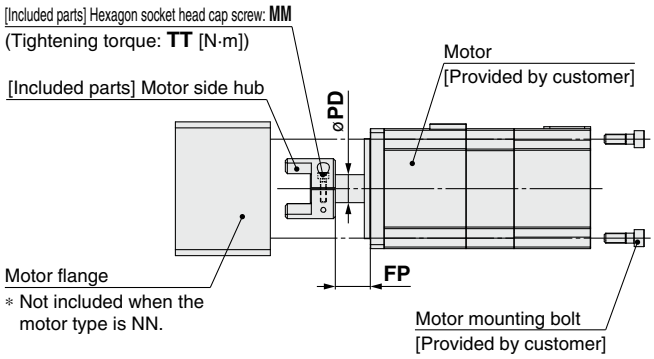
Motor type	FA	FB	FC	FD	FE	FF
NZ	M5 x 0.8	9	70	50	4	34
NY	M4 x 0.7	8	70	50	4	34

- The motor and motor mounting bolts should be provided by the customer.
- When selecting the motor type NN, no motor flange and hub include with the product. The body side hub and spider are specially designed, so order the motor flange option on page 29 separately.

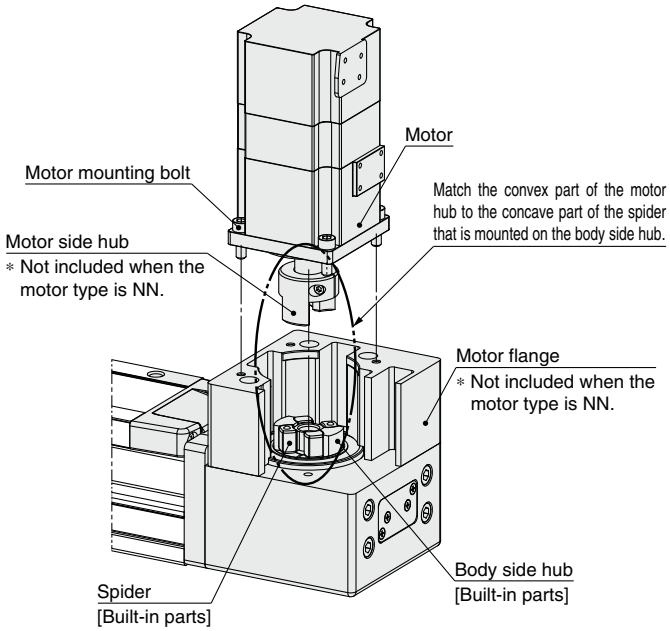
Motor Mounting

Mounting procedure

1) Fix the motor (provided by customer) and the motor hub with the MM hexagon socket head cap screw.
2) Check the motor hub position, and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the motor flange with the motor mounting bolts (provided by customer).



Mounting diagram



Dimensions

[mm]

Size	Motor type	MM	TT	PD	FP
25	**NZ**	M2.5 x 10	1.0	8	12.4
32	**NZ**	M3 x 12	1.5	14	17.5
	NY	M4 x 12	2.5	11	
40	**NZ**	M3 x 12	1.5	14	17.5
	NY	M3 x 12	1.5	14	

Included Parts List

Size: 25

Description	Qty. Motor type	
	NZ	**NN**
Motor side hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Size: 32

Description	Qty. Motor type	
	NZ/NY	**NN**
Motor side hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Size: 40

Description	Qty. Motor type	
	NY/NZ	**NN**
Motor side hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Series LEFB
Motor Mounting Parts

Motor Flange Option

When the motor type "NN" is selected for the model, no motor flange for motor mounting includes with the product.
Select an applicable motor flange option according to the part number shown below, and then order it.

How to Order

LEFB–MF25–NZ

Belt drive ● — ❶ — ❷

❶ Size

25	For LEF□25
32	For LEF□32
40	For LEF□40

❷ Motor type

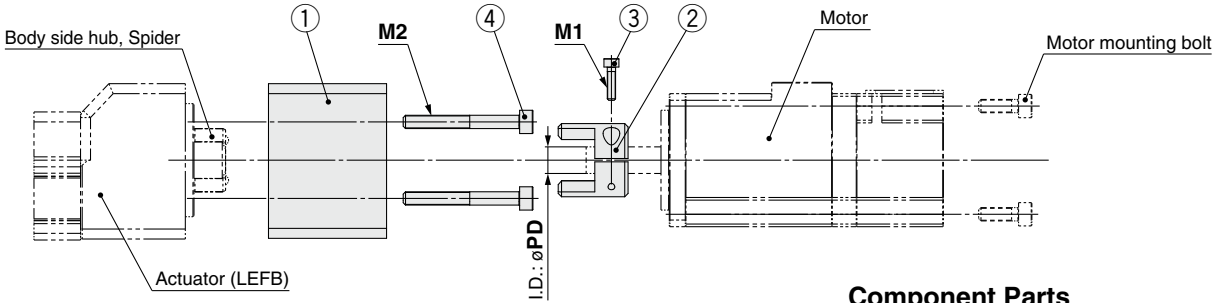
NZ	Mounting type Z
NY	Mounting type Y

∗ For LEFB-MF25, select only NZ.

Compatible Motors

Applicable motor model			Size/Motor type					
			25		**32**		**40**	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—	●	—
	MELSERVO-J3	HF-KP						
	MELSERVO-J4	HG-KR						
YASKAWA Electric Corporation	Σ-V	SGMJV						
SANYO DENKI CO., LTD.	SANMOTION R	R2						
OMRON Corporation	Sysmac G5	R88M-K						
Panasonic Corporation	MINAS-A4	MSMD	—		—	●	—	●
	MINAS-A5	MSMD/MHMD						

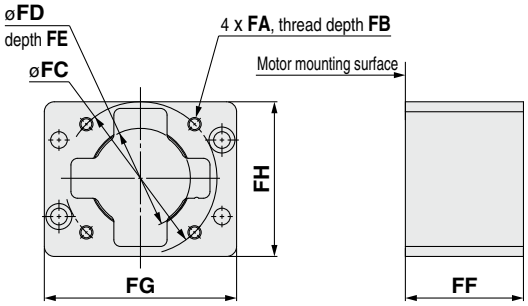
Dimensions: Motor Flange Option



Component Parts

No.	Description	Qty.
1	**Motor flange**	1
2	**Hub (Motor side)**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor flange mounting)**	2

Motor flange details



Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	FH	M1	M2	PD
25	**NZ**	M4 x 0.7	8	46	30	3	31.5	57.8	65.5	M2.5 x 10	M4 x 30	8
32	**NZ**	M5 x 0.8	10	70	50	4	44	69.8	83.5	M3 x 12	M5 x 45	14
	NY	M4 x 0.7	8							M4 x 12		11
40	**NZ**	M5 x 0.8	10				44	89.8	85	M3 x 12		14
	NY											

Series LEF
Electric Actuator/ Specific Product Precautions 1

Be sure to read before handling. Refer to "Handling Precautions for SMC Products" (M-E03-3) for Safety Instructions and the Operation Manual for Electric Actuator Precautions. Please download it via our website, http://www.smcworld.com

Design

⚠Caution

1. Do not apply a load in excess of the operating limit.

Select a suitable actuator by load and allowable moment. If the product is used outside of the operating limit, the eccentric load applied to the guide will be excessive and have adverse effects such as creating play on the guide, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

This can cause failure.

Selection

⚠Warning

1. Do not increase the speed in excess of the operating limit.

Select a suitable actuator by the relationship of the allowable work load and speed, and the allowable speed of each stroke. If the product is used outside of the operating limit, it will have adverse effects such as creating noise, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

This can cause failure.

3. When the product repeatedly cycles with partial strokes (see the table below), operate it at a full stroke at least once every 10 strokes.

Otherwise, lubrication can run out.

Model	Partial stroke
LEF□25	65 mm or less
LEF□32	70 mm or less
LEF□40	105 mm or less

4. When external force is applied to the table, it is necessary to add external force to the work load as the total carried load for the sizing.

When a cable duct or flexible moving tube is attached to the actuator, the sliding resistance of the table increases and may lead to operational failure of the product.

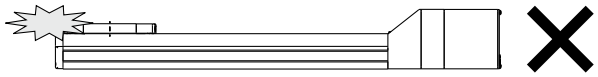
Handling

⚠Caution

1. Do not allow the table to hit the end of stroke.

When the driver parameters, origin or programs are set incorrectly, the table may collide against the stroke end of the actuator during operation. Please check these points before use.

If the table collides against the stroke end of the actuator, the guide, ball screw, belt or internal stopper can be broken. This may lead to abnormal operation.



Handle the actuator with care when it is used in the vertical direction as the workpiece will fall freely from its own weight.

2. The actual speed of this actuator is affected by the work load and stroke.

Check specifications with reference to the model selection section of the catalog.

3. Do not apply a load, impact or resistance in addition to the transferred load during return to origin.

4. Do not dent, scratch or cause other damage to the body and table mounting surfaces.

This may cause unevenness in the mounting surface, play in the guide or an increase in the sliding resistance.

5. Do not apply strong impact or an excessive moment while mounting a workpiece.

If an external force over the allowable moment is applied, it may cause play in the guide or an increase in the sliding resistance.

6. Keep the flatness of mounting surface 0.1 mm or less.

Unevenness of a workpiece or base mounted on the body of the product may cause play in the guide and an increase in the sliding resistance.

7. Do not hit the table with the workpiece in the positioning operation and positioning range.

Electric Actuator/ Specific Product Precautions 2

Be sure to read before handling. Refer to "Handling Precautions for SMC Products" (M-E03-3) for Safety Instructions and the Operation Manual for Electric Actuator Precautions. Please download it via our website, http://www.smcworld.com

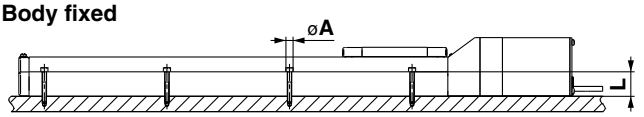
Handling

⚠Caution

8. When mounting the product, use screws with adequate length and tighten them with adequate torque.

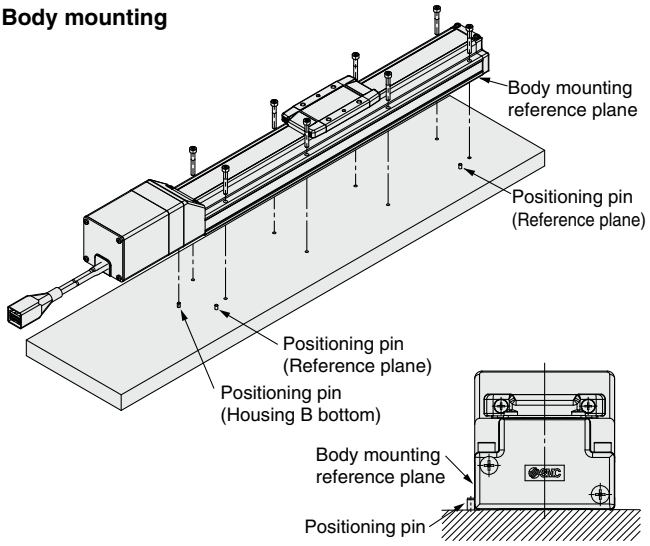
Tightening the screws with a higher torque than recommended may cause a malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

Body fixed



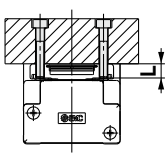
Model	Bolt	ø**A** (mm)	**L** (mm)
LEF□25	M4	4.5	24
LEF□32	M5	5.5	30
LEF□40	M6	6.6	31

Body mounting



The traveling parallelism is the reference plane for the body mounting reference plane.
If the traveling parallelism for a table is required, set the reference plane against parallel pins, etc.

Workpiece fixed



Model	Bolt	Max. tightening torque (N·m)	**L** (Max. screw-in depth) (mm)
LEF□25	M5 x 0.8	3.0	8
LEF□32	M6 x 1	5.2	9
LEF□40	M8 x 1.25	12.5	13

To prevent the workpiece fixing bolts from touching the body, use bolts that are 0.5 mm or shorter than the maximum screw-in depth. If long bolts are used, they can touch the body and cause a malfunction, etc.

9. Do not operate by fixing the table and moving the actuator body.

10. The belt drive actuator cannot be used vertically for applications.

11. Check the specifications for the minimum speed of each actuator.

Otherwise, unexpected malfunctions, such as knocking, may occur.

12. In the case of the belt drive actuator, vibration may occur during operation at speeds within the actuator specifications, this could be caused by the operating conditions. Change the speed setting to a speed that does not cause vibration.

Maintenance

⚠Warning

Maintenance frequency

Perform maintenance according to the table below.

Frequency	Appearance check	Internal check
Inspection before daily operation	○	—
Inspection every 6 months/1000 km/ 5 million cycles*	○	○

* Select whichever comes sooner.

● Items for visual appearance check

1. Loose set screws, Abnormal dirt
2. Check of flaw and cable joint
3. Vibration, Noise

● Items for internal check

1. Lubricant condition on moving parts.
2. Loose or mechanical play in fixed parts or fixing screws.

Model Selection

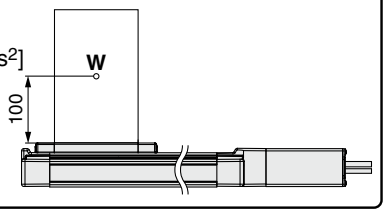
Selection Procedure

Step 1 Check the speed–work load. → **Step 2** Check the cycle time. → **Step 3** Check the allowable moment.

Selection Example

Operating conditions

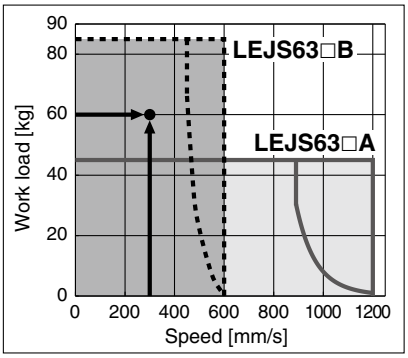
- Work load: 60 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 3000 [mm/s^2]
- Stroke: 300 [mm]
- Mounting orientation: Horizontal
- External force: 10 [N]
- Workpiece mounting condition:



Step 1 Check the speed–work load.

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the <Speed–Work load graph> on page 34.

Selection example) The **LEJS63□B-300** is temporarily selected based on the graph shown on the right side.



<Speed–Work load graph> (LEJS63)

Step 2 Check the cycle time.

Refer to method 1 for a rough estimate, and method 2 for a more precise value.

Method 1: Check the cycle time graph (Page 35)

The graph is based on the maximum speed of each size.

Method 2: Calculation

Cycle time T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1 and T3 can be obtained by the following equation.

$$T1 = V/a1 \text{ [s]} \qquad T3 = V/a2 \text{ [s]}$$

The acceleration and deceleration values have upper limits depending on the workpiece mass and the duty ratio.
Check that they do not exceed the upper limit, by referring to "Work load–Acceleration/Deceleration Graph (Guide)" (Pages 36 and 37).
For the ball screw type, there is an upper limit of the speed depending on the stroke. Check that if it does not exceed the upper limit, by referring to the specifications (Page 42).

- T2 can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4 varies depending on the motor type and load. The value below is recommended.

$$T4 = 0.05 \text{ [s]}$$

∗ The conditions for the settling time vary depending on the AC servo motor or driver to be used.

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 300/3000 = 0.1$ [s],

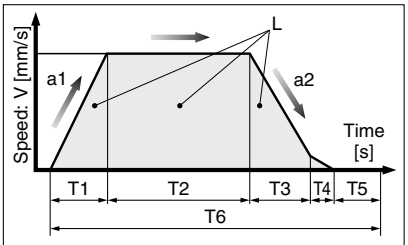
$T3 = V/a2 = 300/3000 = 0.1$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{300 - 0.5 \cdot 300 \cdot (0.1 + 0.1)}{300} = 0.90 \text{ [s]}$$

$T4 = 0.05$[s]

Therefore, the cycle time can be obtained as follows.

$T = T1 + T2 + T3 + T4$
$= 0.1 + 0.90 + 0.1 + 0.05$
$=$ **1.15 [s]**



L : Stroke [mm]
V : Speed [mm/s]
a1: Acceleration [mm/s^2]
a2: Deceleration [mm/s^2]

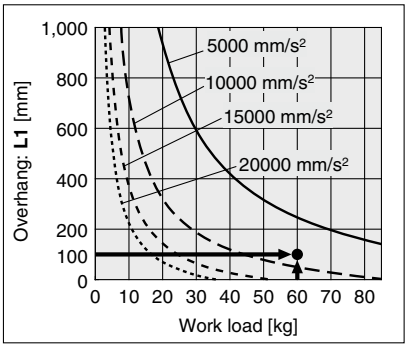
T1: Acceleration time [s]
Time until reaching the set speed
T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
T4: Settling time [s]
Time until in position is completed
T5: Resting time [s]
Time the product is not running
T6: Total time [s]
Total time from T1 to T5

Duty ratio: Ratio of T to T6
T ÷ T6 x 100

Step 3 Check the allowable moment.

Refer to "Dynamic Allowable Moment" graphs (Pages 38 and 39).

Selection example) Select the **LEJS63□B-300** from the graph on the right side.
Confirm that the external force is within the allowable external force (20 [N]).
(The external force is the resistance due to cable duct, flexible trunking or air tubing.)



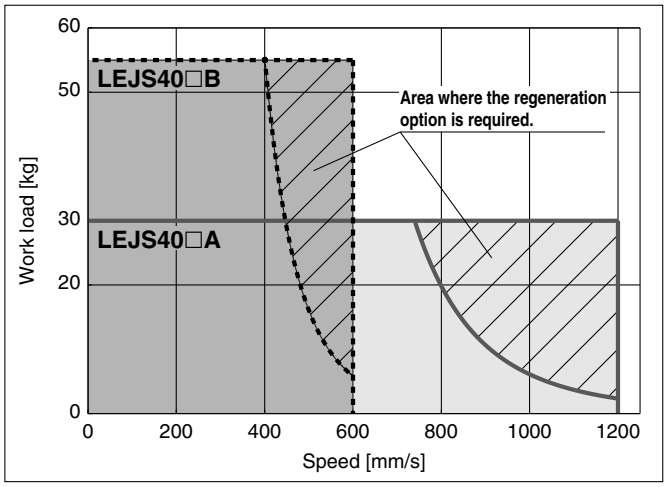
<Dynamic allowable moment> (LEJS63)

Speed–Work Load Graph (Guide)

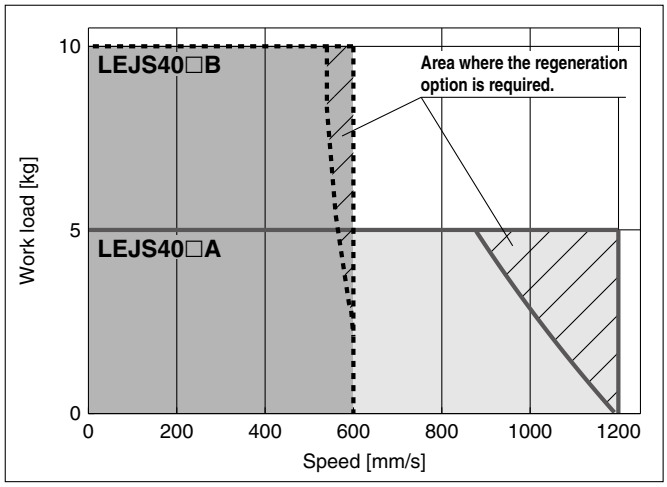
∗ The values shown below are allowable values of the actuator body.
Do not use the actuator so that it exceeds these specification ranges.

LEJS40/Ball Screw Drive

Horizontal

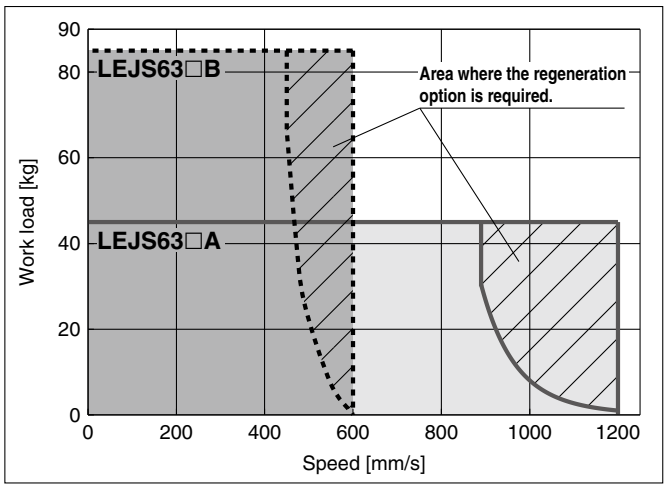


Vertical

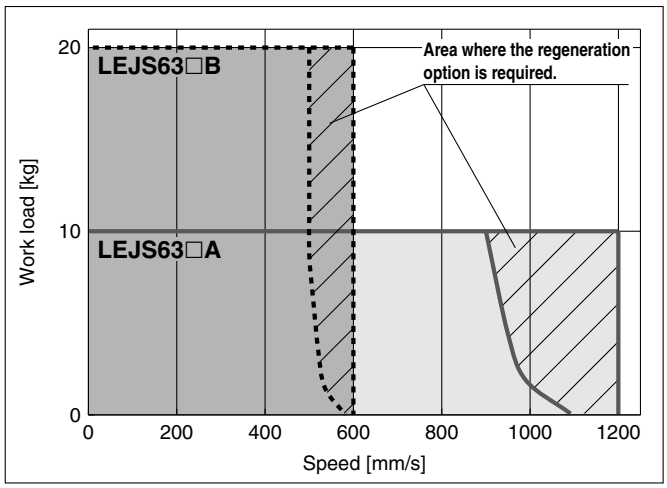


LEJS63/Ball Screw Drive

Horizontal



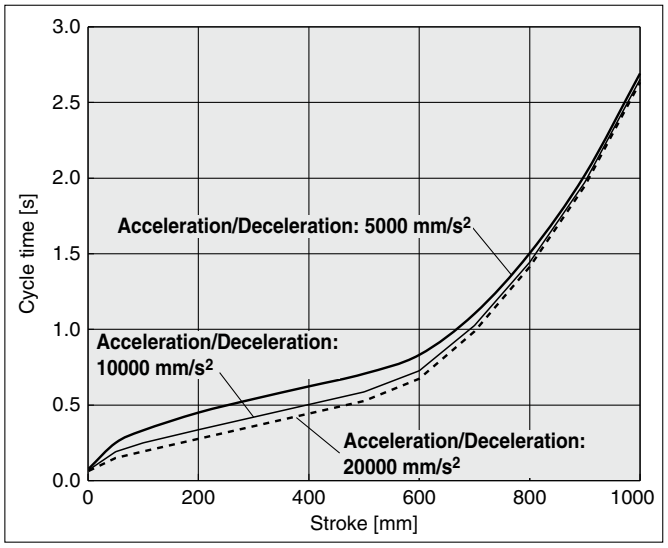
Vertical



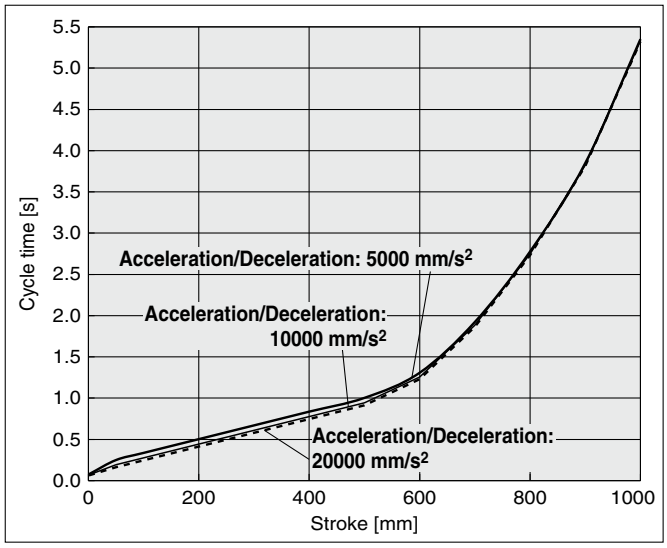
Cycle Time Graph (Guide)

LEJS40/Ball Screw Drive

LEJS40□A

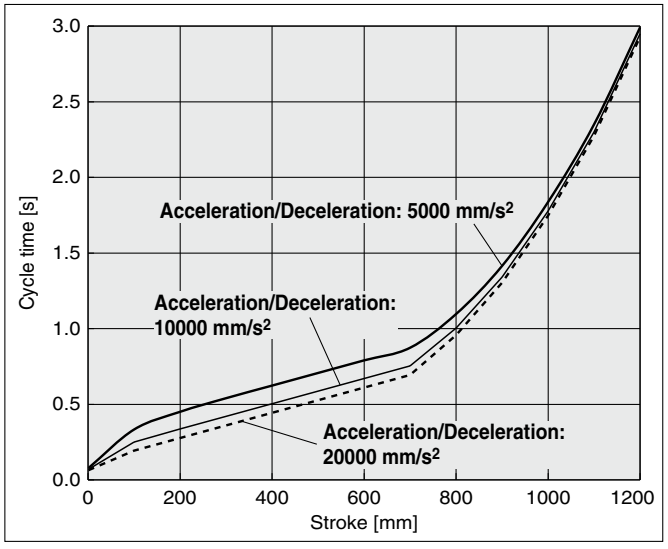


LEJS40□B

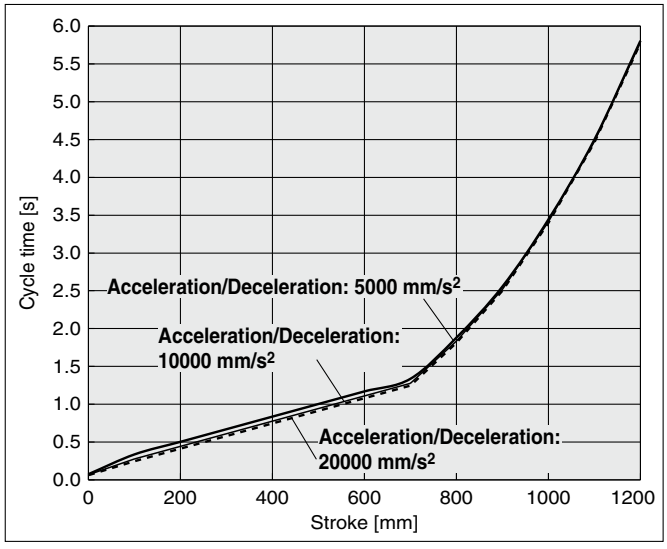


LEJS63/Ball Screw Drive

LEJS63□A



LEJS63□B

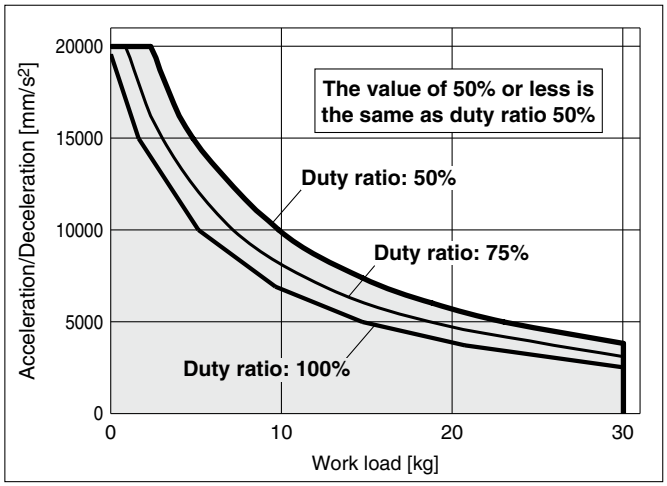


∗ Work load/acceleration/deceleration graph
∗ Maximum speed/acceleration/deceleration values graph for each stroke

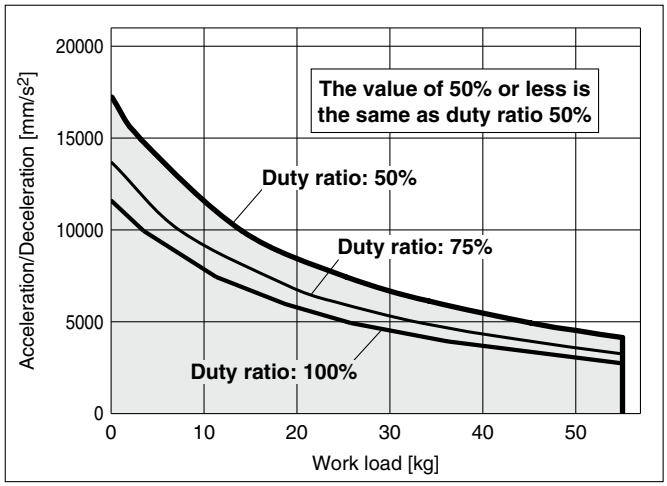
Work Load–Acceleration/Deceleration Graph (Guide)

LEJS40/Ball Screw Drive: Horizontal

LEJS40□A

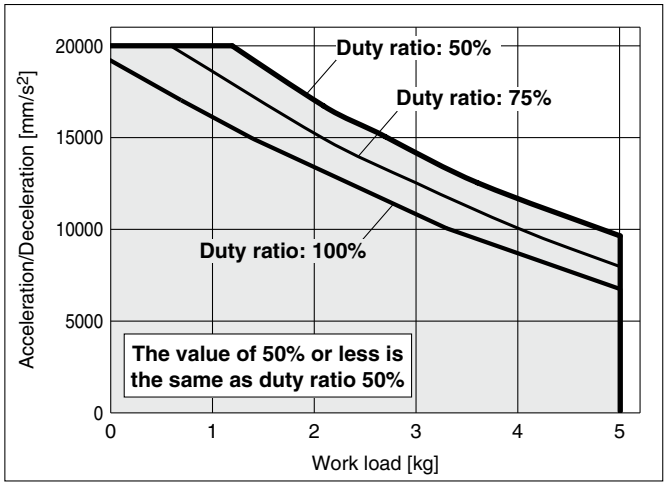


LEJS40□B

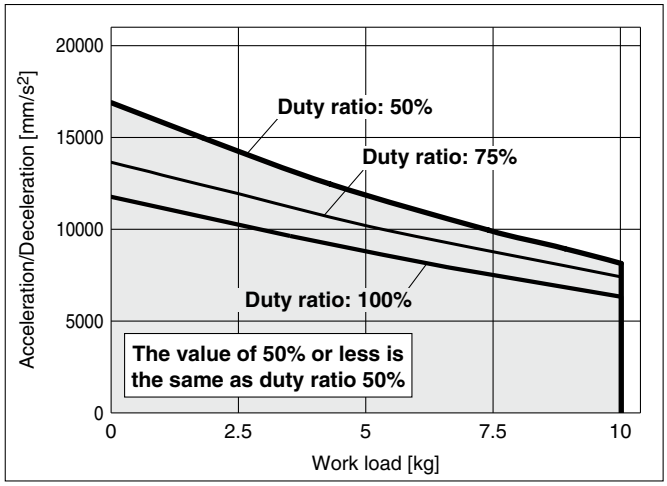


LEJS40/Ball Screw Drive: Vertical

LEJS40□A



LEJS40□B

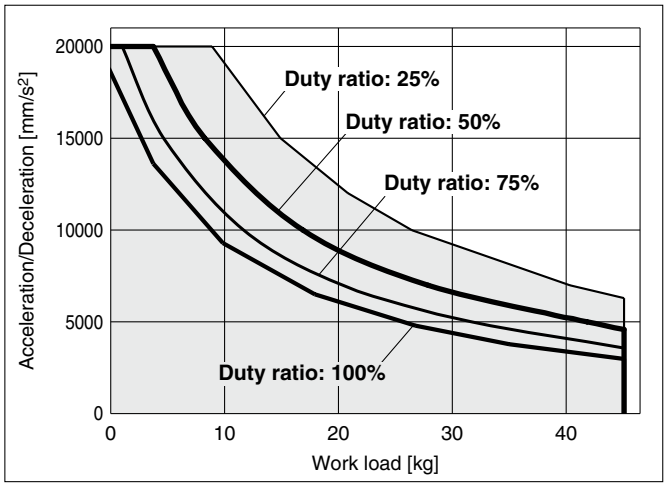


These graphs are reference examples of when an SMC standard AC servo motor is mounted.
Determine the duty ratio after taking into account the load factor of the AC servo motor or driver to be used.
The values show the specifications with a standard SMC motor used. Please use this as a guide.

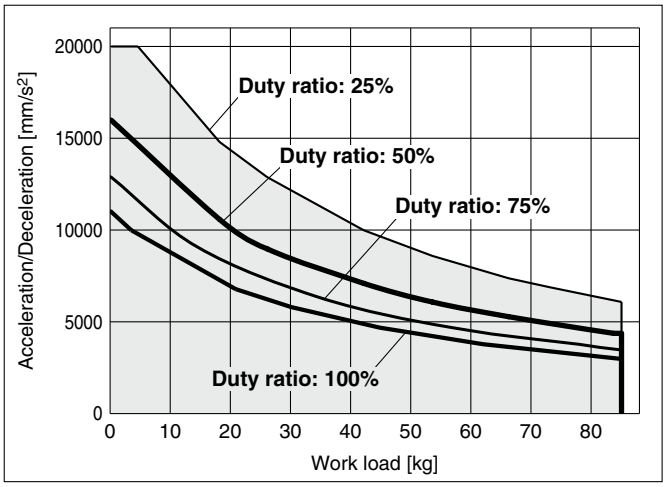
Work Load–Acceleration/Deceleration Graph (Guide)

LEJS63/Ball Screw Drive: Horizontal

LEJS63□A

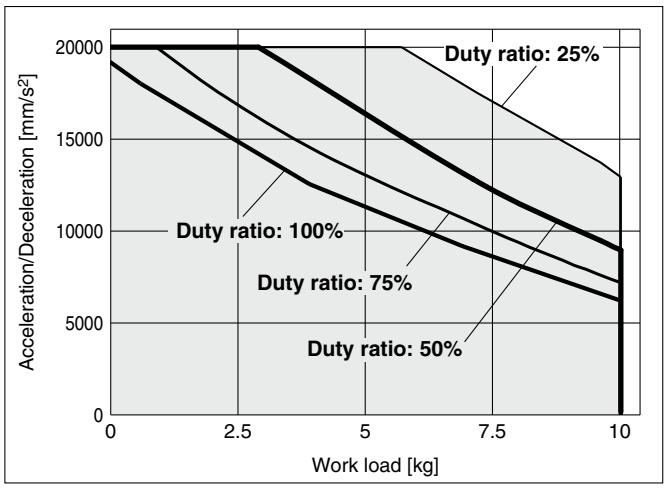


LEJS63□B

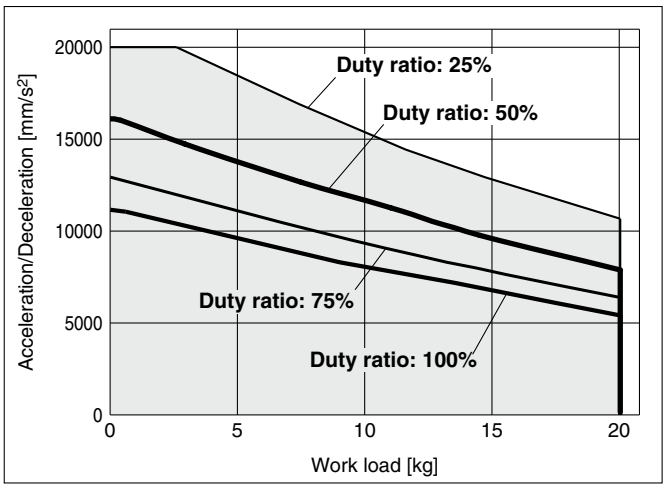


LEJS63/Ball Screw Drive: Vertical

LEJS63□A



LEJS63□B

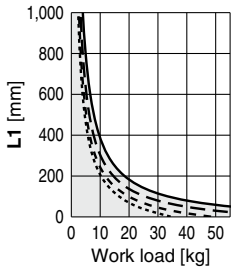
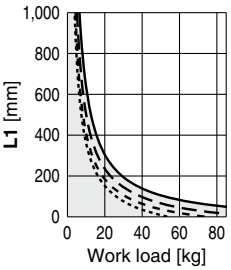
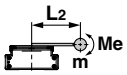
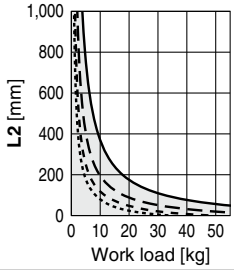
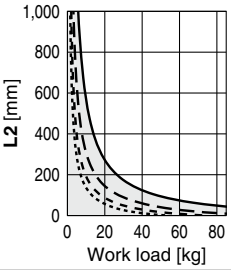
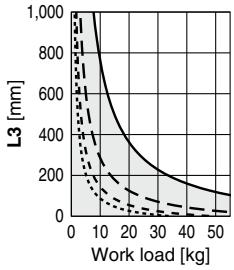
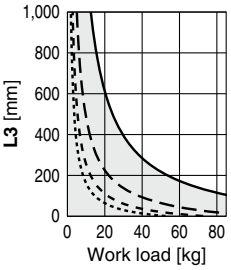
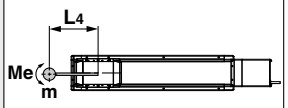
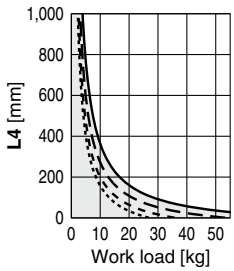
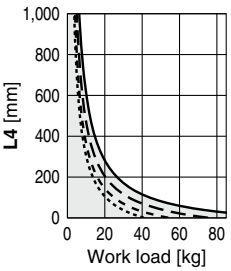
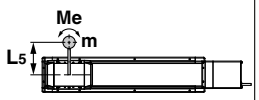
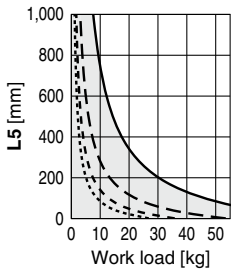
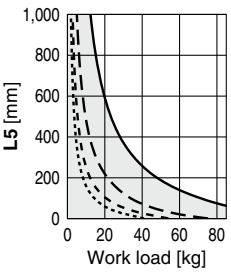
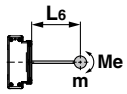
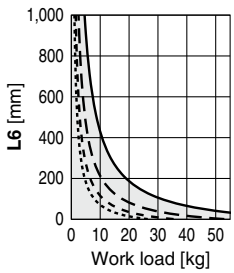
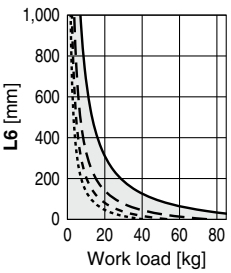


These graphs are reference examples of when an SMC standard AC servo motor is mounted.
Determine the duty ratio after taking into account the load factor of the AC servo motor or driver to be used.
The values show the specifications with a standard SMC motor used. Please use this as a guide.

Dynamic Allowable Moment

∗ This graph shows the amount of allowable overhang when the center of gravity of the workpiece overhangs in one direction. When the center of gravity of the workpiece overhangs in two directions, refer to the Electric Actuator Selection Software for confirmation. http://www.smcworld.com

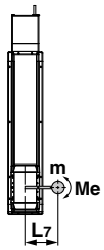
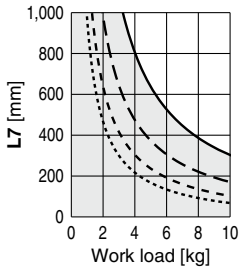
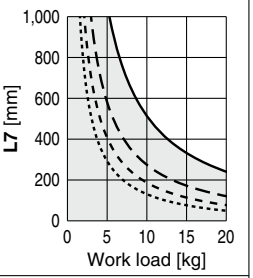
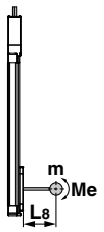
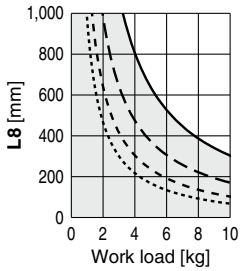
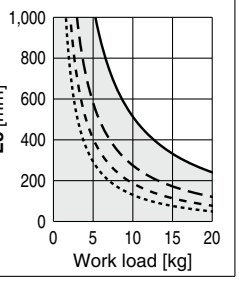
Acceleration/Deceleration —— 5,000 mm/s² – – – 10,000 mm/s² - - - - 15,000 mm/s² ····· 20,000 mm/s²

Orientation	Load overhanging direction **m**: Work load [kg] **Me**: Dynamic allowable moment [N·m] **L**: Overhang to the work load center of gravity [mm]		Model LEJS40	Model LEJS63
Horizontal/Bottom		X		
		Y		
		Z		
Wall		X		
		Y		
		Z		

Dynamic Allowable Moment

∗ This graph shows the amount of allowable overhang when the center of gravity of the workpiece overhangs in one direction. When the center of gravity of the workpiece overhangs in two directions, refer to the Electric Actuator Selection Software for confirmation. http://www.smcworld.com

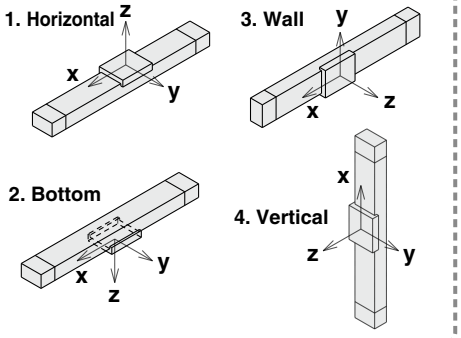
Acceleration/Deceleration —— 5,000 mm/s² – – – 10,000 mm/s² - - - - 15,000 mm/s² ····· 20,000 mm/s²

Orientation	Load overhanging direction **m**: Work load [kg] **Me**: Dynamic allowable moment [N·m] **L**: Overhang to the work load center of gravity [mm]		Model **LEJS40**	Model **LEJS63**
Vertical		Y		
		Z		

Calculation of Guide Load Factor

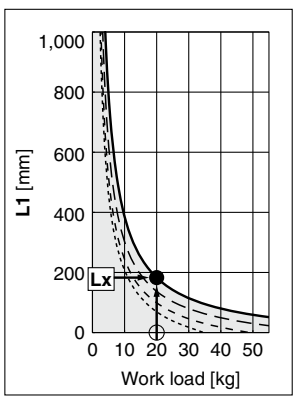
1. Decide operating conditions.
   Model: LEJS
   Size: 40/63
   Mounting orientation: Horizontal/Bottom/Wall/Vertical
   Acceleration [mm/s²]: **a**
   Work load [kg]: **m**
   Work load center position [mm]: **Xc/Yc/Zc**
2. Select the target graph with reference to the model, size and mounting orientation.
3. Based on the acceleration and work load, obtain the overhang [mm]: **Lx/Ly/Lz** from the graph.
4. Calculate the load factor for each direction.
   α**x = Xc/Lx**, α**y = Yc/Ly**, α**z = Zc/Lz**
5. Confirm the total of α**x**, α**y** and α**z** is 1 or less.
   α**x + αy + αz ≤1**
   When 1 is exceeded, please consider a reduction of acceleration and work load, or a change of the work load center position and series.

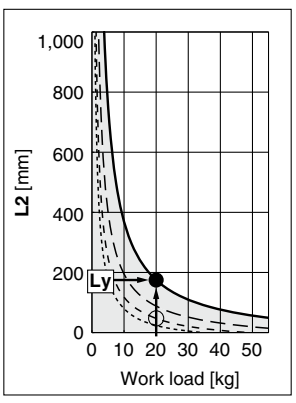
Mounting orientation



Example

1. Operating conditions
   Model: LEJS
   Size: 40
   Mounting orientation: Horizontal
   Acceleration [mm/s²]: 5000
   Work load [kg]: 20
   Work load center position [mm]: **Xc = 0**, **Yc = 50**, **Zc = 200**
2. Select the graph on page 38, top and left side first row.
3. **Lx = 180 mm**, **Ly = 170 mm**, **Lz = 360 mm**
4. The load factor for each direction can be obtained as follows.
   α**x = 0/180 = 0**
   α**y = 50/170 = 0.29**
   α**z = 200/360 = 0.56**
5. α**x + αy + αz = 0.85 ≤1**





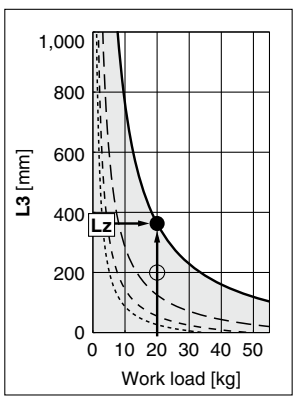
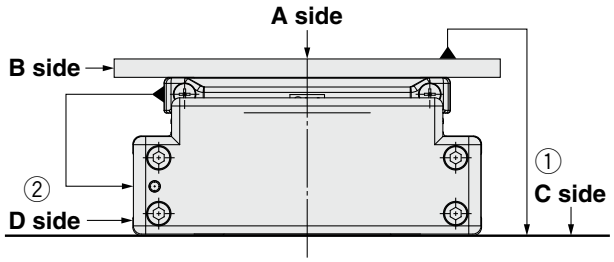


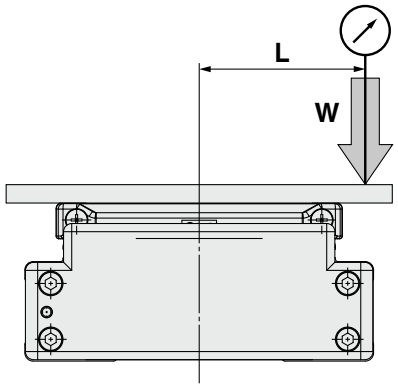
Table Accuracy (Reference Value)

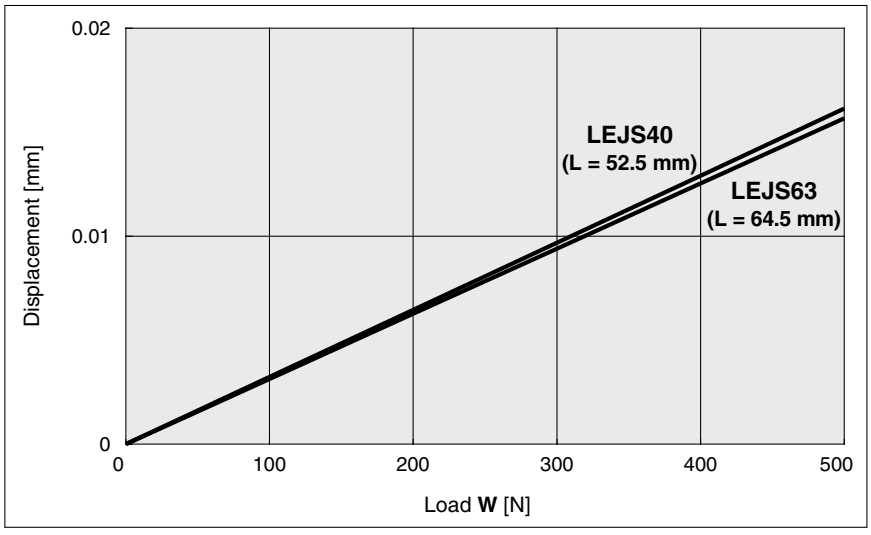


Model	Traveling parallelism [mm] (Every 300 mm)	
	① C side traveling parallelism to A side	② D side traveling parallelism to B side
LEJS40	0.05	0.03
LEJS63	0.05	0.03

Note) Traveling parallelism does not include the mounting surface accuracy.

Table Displacement (Reference Value)





Note) This displacement is measured when a 15 mm aluminum plate is mounted and fixed on the table. (Table clearance is included.)

Electric Actuator/High Rigidity Slider Type
Ball Screw Drive Motorless Type
Series LEJS

RoHS

How to Order

LEJS 40 ❶ ☐ ❷ ☐ ❸ – 500 ❹

❶ Size

40
63

❷ Motor type

NZ	Mounting type Z
NY*	Mounting type Y

* Size 63 only

❸ Lead [mm]

Symbol	LEJS40	LEJS63
A	16	20
B	8	10

❹ Stroke [mm]

200
to
1500

* For details, refer to the table below.

* Applicable stroke table ● Standard/○ Produced upon receipt of order

Model \ Stroke (mm)	200	300	400	500	600	700	800	900	1000	1200	1500
LEJS40	●	●	○	●	●	○	●	○	○	○	—
LEJS63	—	●	○	●	●	○	●	○	●	○	○

* Consult with SMC as all non-standard and non-made-to-order strokes are produced as special orders.

Compatible Motors

Applicable motor model			Size/Motor type			
			40		63	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—
	MELSERVO-J3	HF-KP				
	MELSERVO-J4	HG-KR				
YASKAWA Electric Corporation	Σ-V	SGMJV				
SANYO DENKI CO., LTD.	SANMOTION R	R2				
OMRON Corporation	Sysmac G5	R88M-K			—	●
Panasonic Corporation	MINAS-A4	MSMD	—			
	MINAS-A5	MSMD/MHMD				

For auto switches, refer to Electric Actuators catalog (CAT.E102).

Specifications Note 2) Note 3) Note 4) Note 5) Note 6) Note 7) Note 8)

Model				LEJS40		LEJS63	
Actuator specifications	Stroke [mm] Note 1)			200, 300, (400), 500, 600, (700), 800, (900), (1000), (1200)		300, (400), 500, 600, (700), 800, (900), 1000, (1200), (1500)	
	Work load [kg]		Horizontal	30	55	45	85
			Vertical	5	10	10	20
	Max. speed [mm/s]	Stroke range	Up to 500	1200	600	1200	600
			501 to 600	1050	520		
			601 to 700	780	390		
			701 to 800	600	300	930	460
			801 to 900	480	240	740	370
			901 to 1000	390	190	600	300
			1001 to 1100	320	160	500	250
			1101 to 1200	270	130	420	210
			1201 to 1300	—	—	360	180
			1301 to 1400	—	—	310	150
			1401 to 1500	—	—	270	130
	Max. acceleration/deceleration [mm/s²]			20000			
	Positioning repeatability [mm]			±0.02			
	Ball screw specifications		Thread size [mm]	ø12		ø15	
			Lead [mm]	16	8	20	10
			Shaft length [mm]	Stroke + 118.5		Stroke + 126.5	
	Impact/Vibration resistance [m/s²]			50/20			
	Actuation type			Ball screw			
	Guide type			Linear guide			
	Operating temperature range [°C]			5 to 40			
	Operating humidity range [%RH]			90 or less (No condensation)			
Applicable motor specifications	Motor shape			□40		□60	
	Motor type			AC servo motor (100 V/200 V)			
	Rated output capacity [W]			100		200	
	Rated torque [N·m]			0.32		0.64	
	Rated rotation [rpm]			3000		3000	
Other specifications	Actuation unit weight [kg]			0.86		1.37	
	Other inertia [kg·cm²]			0.031		0.129	
	Friction coefficient			0.05			
	Mechanical efficiency			0.8			

Note 1) Strokes shown in ( ) are produced upon receipt of order.
Note 2) Sensor magnet position is located in the table center.
For detailed dimensions related to auto switches, refer to Electric Actuators catalog (CAT.E102).
Note 3) These specifications are allowable values of the actuator body. Do not use the actuator so that it exceeds these values.
Note 4) When mounting a hub, remove the oil content, dust, or dirt sticking to the shaft and hub inside diameter.
Note 5) This product does not include the motor and motor mounting bolts. (Provided by customer)
For the shaft-end shape of the motor, please prepare the round type.
Note 6) Take loose prevention measures for the motor mounting bolts.
Note 7) Do not allow collisions at either end of the table traveling distance at a speed exceeding “pushing return to origin speed”.
Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 8) Consult with SMC for the manufacture of intermediate strokes.
(LEJS40/Manufacturable stroke range: 200 to 1200 mm, LEJS63/Manufacturable stroke range: 300 to 1500 mm)

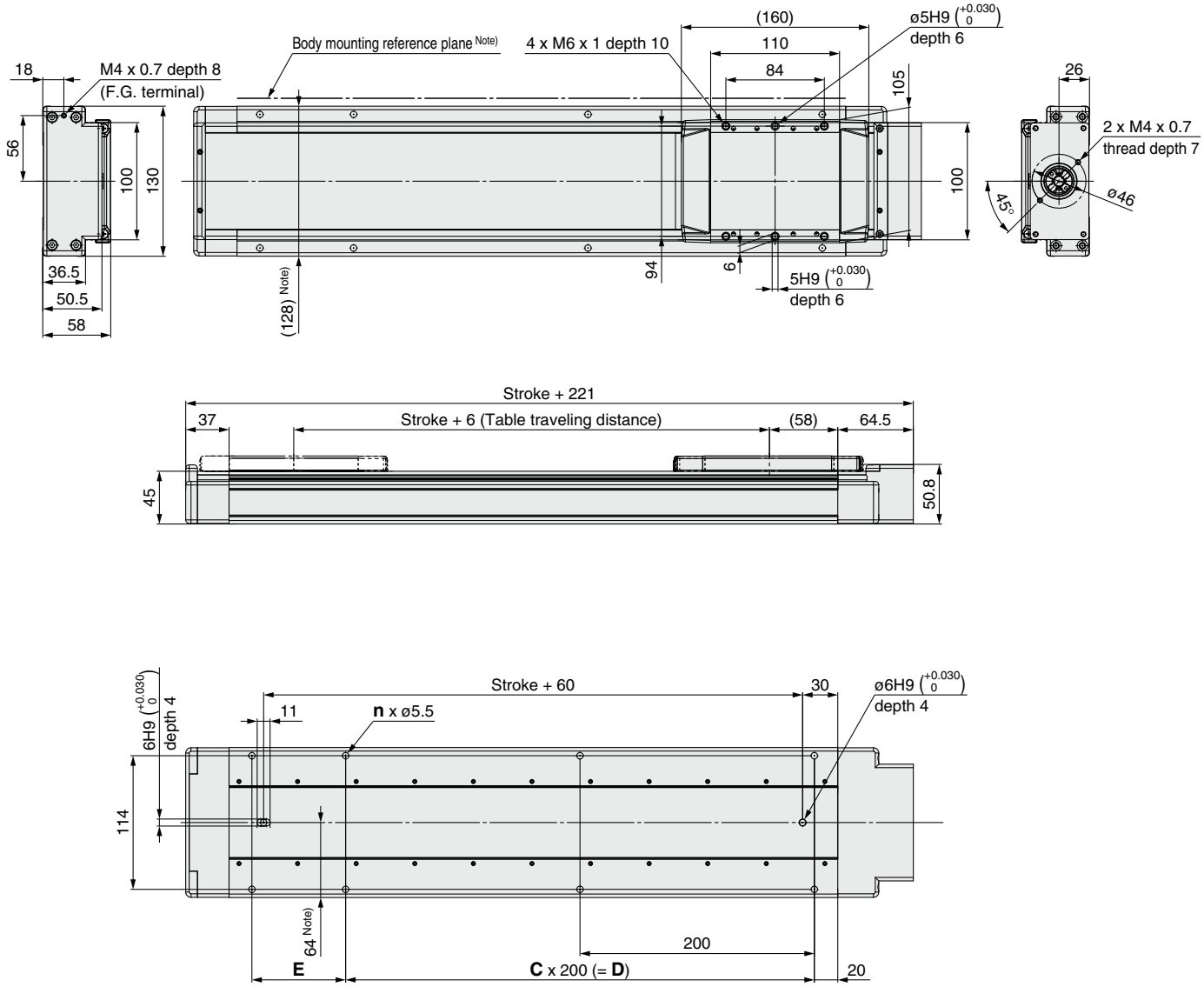
Weight

Series	LEJS40									
Stroke [mm]	200	300	(400)	500	600	(700)	800	(900)	(1000)	(1200)
Product weight [kg]	5.0	5.8	6.5	7.3	8.1	8.8	9.6	10.4	11.1	12.7

Series	LEJS63									
Stroke [mm]	300	(400)	500	600	(700)	800	(900)	1000	(1200)	(1500)
Product weight [kg]	10.4	11.7	12.9	14.2	15.4	16.7	17.9	19.1	21.6	25.4

Dimensions: Ball Screw Drive

LEJS40



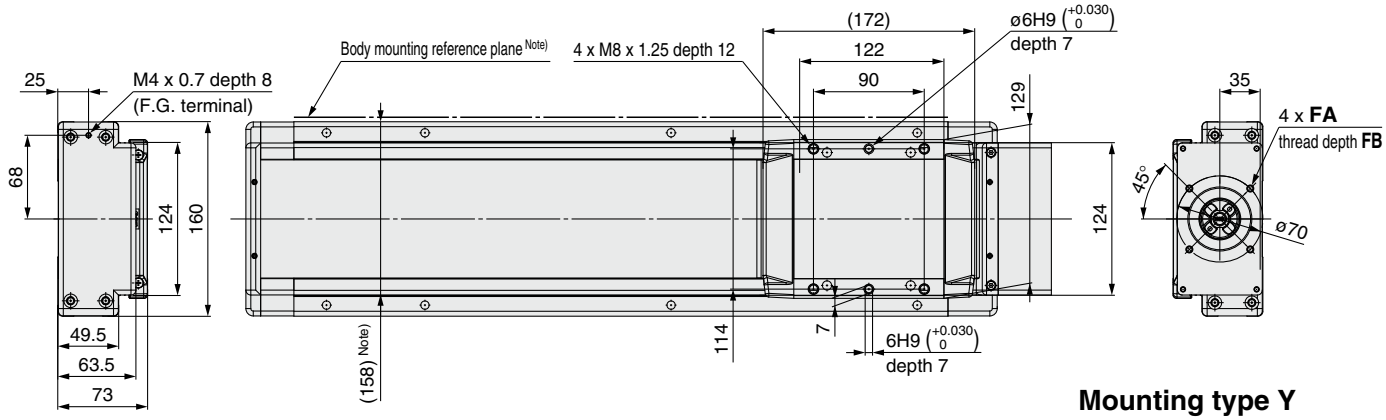
Note) When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of chamfering. (Recommended height 6 mm)

Dimensions [mm]

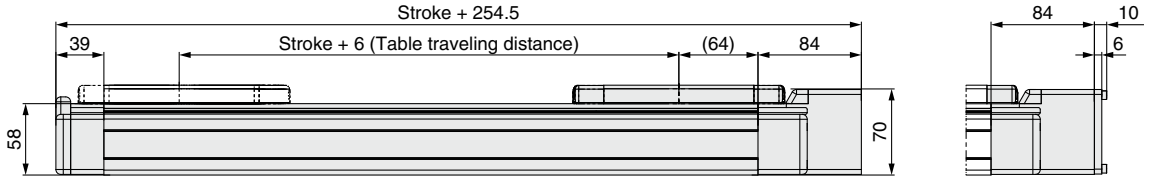
Model	n	C	D	E
LEJS40N□□-200	6	1	200	80
LEJS40N□□-300	6	1	200	180
LEJS40N□□-400	8	2	400	80
LEJS40N□□-500	8	2	400	180
LEJS40N□□-600	10	3	600	80
LEJS40N□□-700	10	3	600	180
LEJS40N□□-800	12	4	800	80
LEJS40N□□-900	12	4	800	180
LEJS40N□□-1000	14	5	1000	80
LEJS40N□□-1200	16	6	1200	80

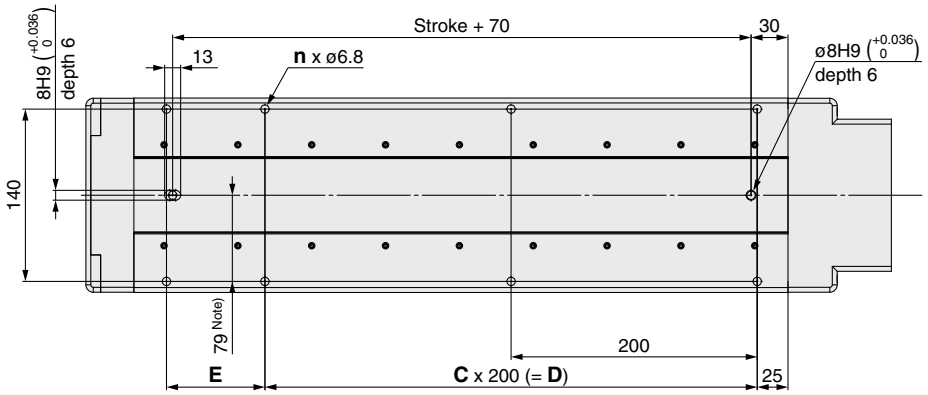
Dimensions: Ball Screw Drive

LEJS63



Mounting type Y
LEJS63NY□-□





Note) When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of chamfering. (Recommended height 6 mm)

Dimensions [mm]

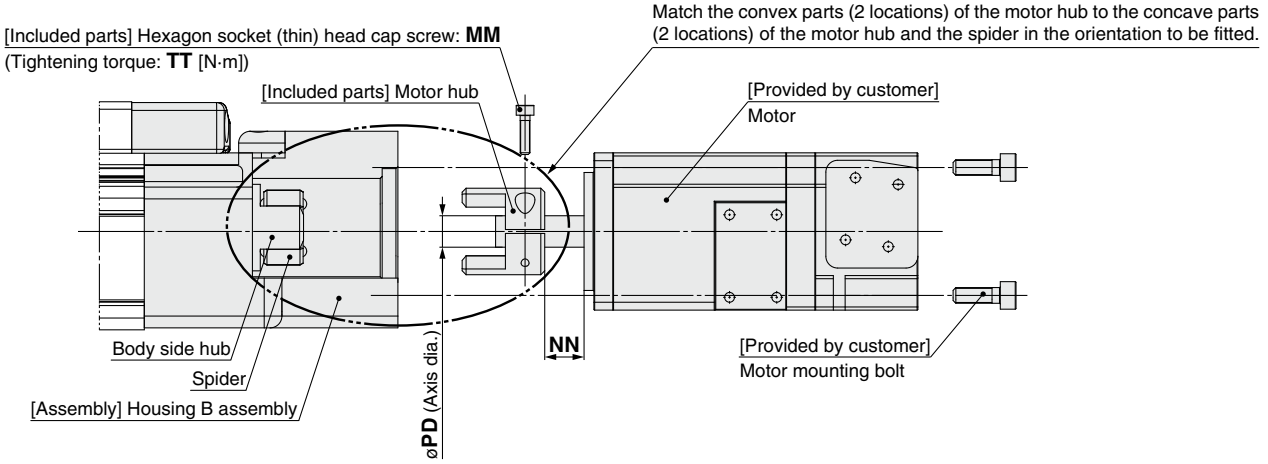
Model	n	C	D	E
LEJS63N□□-300	6	1	200	180
LEJS63N□□-400	8	2	400	80
LEJS63N□□-500	8	2	400	180
LEJS63N□□-600	10	3	600	80
LEJS63N□□-700	10	3	600	180
LEJS63N□□-800	12	4	800	80
LEJS63N□□-900	12	4	800	180
LEJS63N□□-1000	14	5	1000	80
LEJS63N□□-1200	16	6	1200	80
LEJS63N□□-1500	18	7	1400	180

Motor mounting dimensions [mm]

Motor type	FA	FB
NZ/Mounting type Z	M5 x 0.8	7
NY/Mounting type Y	M4 x 0.7	5

Motor Mounting

Mounting procedure
1) Fix the motor (provided by customer) and the motor hub with the MM hexagon socket head cap screw.
2) Check the motor hub position, and then insert it. (Refer to the mounting diagram.)
3) Fix the motor and the housing B assembly with the motor mounting bolts (provided by customer).



Dimensions

[mm]

Size	Motor type	MM	TT	NN	PD
40	NZ/Mounting type Z	M2.5 x 10	0.65	10	8
63	NZ/Mounting type Z	M3 x 12	1.5	15	14
	NY/Mounting type Y	M4 x 12	2.7	15	11

Included Parts List

Size: 40

Description	Qty.
Motor hub	1
Hexagon socket head cap screw (for hub fixing)	1

Size: 63

Description	Qty.
Motor hub	1
Hexagon socket thin head cap screw (for hub fixing)	1

Series LEJS
Motor Mounting Parts

Motor Flange Option

As the motor type "NZ" is selected for the model and this option is mounted, the motor types that can be used are shown below.

How to Order

LEJ – MF 63 D – NY

❶ ❷

❶ Size

63	For LEJ63

❷ Motor mounting position

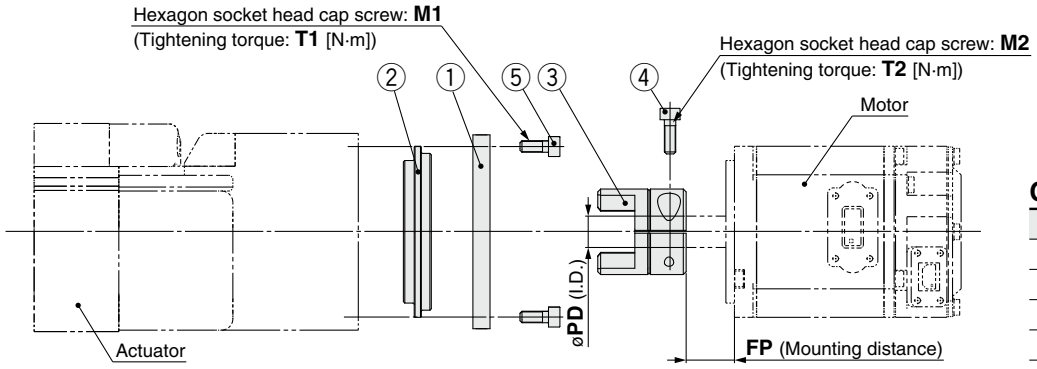
NY	Mounting type Y

∗ Refer to the “Compatible Motors”.

Compatible Motors

Applicable motor model			Size/Motor type
Manufacturer	Series	Type	**63** "NY" Mounting type Y
OMRON Corporation	Sysmac G5	R88M-K	●
Panasonic Corporation	MINAS-A4	MSMD	
	MINAS-A5	MSMD/MHMD	

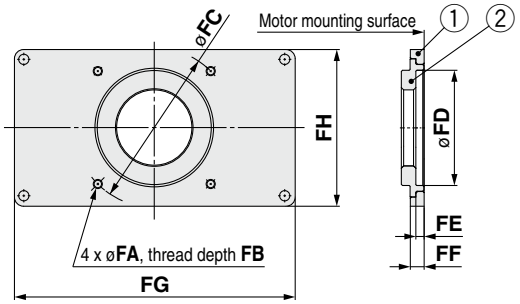
Dimensions: Motor Flange Option



Component Parts

No.	Description	Qty.
1	**Motor plate**	1
2	**Ring**	1
3	**Hub (Motor side)**	1
4	Hexagon socket thin head cap screw	1
5	Hexagon socket head cap screw	4

Motor plate details



Dimensions [mm]

Motor type	FA	FB	FC	FD	FE	FF	FG
NY	M4 x 0.7	5	70	50	3.5	6	123

Motor type	FH	M1	T1	M2	T2	PD	FP
NY	68	M4 x 12	2.7	M4 x 12	2.7	11	15

Series LEJS
Electric Actuator/ Specific Product Precautions 1

Be sure to read before handling. Refer to "Handling Precautions for SMC Products" (M-E03-3) for Safety Instructions and the Operation Manual for Electric Actuator Precautions. Please download it via our website, http://www.smcworld.com

Design

⚠Caution

1. Do not apply a load in excess of the operating limit.

Select a suitable actuator by load and allowable moment. If the product is used outside of the operating limit, the eccentric load applied to the guide will be excessive and have adverse effects such as creating play on the guide, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

The product can be damaged.

The components including the motor are manufactured to precise tolerances. So that even a slight deformation may cause a malfunction or seizure.

Selection

⚠Warning

1. Do not increase the speed in excess of the operating limit.

Select a suitable actuator by the relationship of the allowable work load and speed, and the allowable speed of each stroke. If the product is used outside of the operating limit, it will have adverse effects such as creating noise, degrading accuracy and shortening the life of the product.

2. When the product repeatedly cycles with partial strokes (100 mm or less), lubrication can run out. Operate it at a full stroke at least once a day or every 1000 strokes.

3. When external force is applied to the table, it is necessary to add external force to the work load as the total carried load for the sizing.

When a cable duct or flexible moving tube is attached to the actuator, the sliding resistance of the table increases and may lead to operational failure of the product.

Handling

⚠Caution

1. Do not allow the table to hit the end of stroke.

When the driver parameters, origin or programs are set incorrectly, the table may collide against the stroke end of the actuator during operation. Please check these points before use.

If the table collides against the stroke end of the actuator, the guide, ball screw, belt or internal stopper can be broken. This may lead to abnormal operation.

Handle the actuator with care when it is used in the vertical direction as the workpiece will fall freely from its own weight.

2. The actual speed of this actuator is affected by the work load and stroke.

Check specifications with reference to the model selection section of the catalog.

3. Do not apply a load, impact or resistance in addition to the transferred load during return to origin.

4. Do not dent, scratch or cause other damage to the body and table mounting surfaces.

This may cause unevenness in the mounting surface, play in the guide or an increase in the sliding resistance.

5. Do not apply strong impact or an excessive moment while mounting the product or a workpiece.

If an external force over the allowable moment is applied, it may cause play in the guide or an increase in the sliding resistance.

6. Keep the flatness of mounting surface 0.1 mm or less.

Unevenness of a workpiece or base mounted on the body of the product may cause play in the guide and an increase in the sliding resistance.

In the case of overhang mounting (excluding cantilever), use a support plate or support guide to avoid deflection of the actuator body.

7. When mounting the actuator, use all mounting holes.

If all mounting holes are not used, it influences the specifications, e.g., the amount of displacement of the table increases.

8. Do not hit the table with the workpiece in the positioning operation and positioning range.

9. Do not apply external force to the dust seal band.

Particularly during the transportation.

Series LEJS
Electric Actuator/ Specific Product Precautions 2

Be sure to read before handling. Refer to "Handling Precautions for SMC Products" (M-E03-3) for Safety Instructions and the Operation Manual for Electric Actuator Precautions. Please download it via our website, http://www.smcworld.com

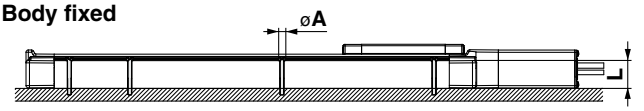
Handling

⚠Caution

10. When mounting the product, use screws with adequate length and tighten them with adequate torque.

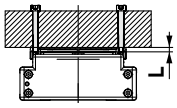
Tightening the screws with a higher torque than recommended may cause a malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

Body fixed



Model	Bolt	øA (mm)	L (mm)
LEJS40	M5	5.5	36.5
LEJS63	M6	6.8	49.5

Workpiece fixed

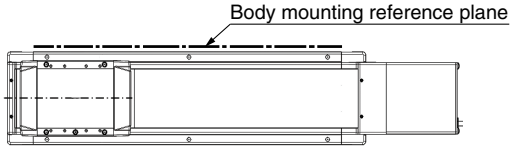


Model	Bolt	Max. tightening torque (N·m)	L (Max. screw-in depth) (mm)
LEJS40	M6 x 1	5.2	10
LEJS63	M8 x 1.25	12.5	12

To prevent the workpiece fixing bolts from touching the body, use bolts that are 0.5 mm or shorter than the maximum screw-in depth. If long bolts are used, they can touch the body and cause a malfunction, etc.

11. Do not operate by fixing the table and moving the actuator body.

12. When mounting the actuator using the body mounting reference plane, use a pin. Set the height of the pin to be 5 mm or more because of chamfering. (Recommended height 6 mm)



Maintenance

⚠Warning

Maintenance frequency

Perform maintenance according to the table below.

Frequency	Appearance check	Internal check
Inspection before daily operation	○	—
Inspection every 6 months/1000 km/5 million cycles*	○	○

* Select whichever comes sooner.

• Items for visual appearance check

1. Loose set screws, Abnormal dirt
2. Check of flaw and cable joint
3. Vibration, Noise

• Items for internal check

1. Lubricant condition on moving parts.
   * For lubrication, use lithium grease No. 2.
2. Loose or mechanical play in fixed parts or fixing screws.

Model Selection

Selection Procedure

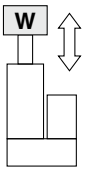
Positioning Control Selection Procedure

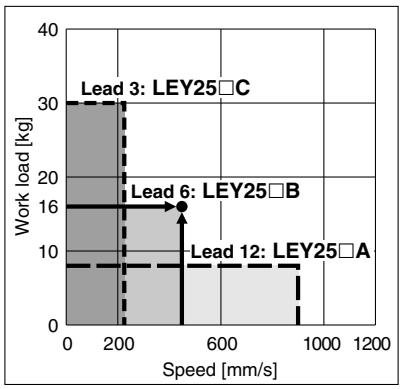
Step 1 Check the work load–speed. (Vertical transfer) → **Step 2** Check the cycle time.

Selection Example

Operating conditions

- Work load: 16 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 5,000 [mm/s^2]
- Stroke: 300 [mm]
- Workpiece mounting condition: Vertical upward / downward transfer





<Speed–Vertical work load graph> (LEY25□)

Step 1 **Check the work load–speed. <Speed–Vertical work load graph>**

Select a model based on the workpiece mass and speed which are within the range of the actuator body specifications with reference to the <Speed–Work load graph> on page 51.

Selection example) The **LEY25□B** is temporarily selected based on the graph shown on the right side.

∗ It is necessary to mount a guide outside the actuator when used for horizontal transfer. When selecting the target model, refer to pages 56 and 57 for the horizontal work load in the specifications, and page 77 for the precautions.

The regeneration option may be necessary. Refer to Electric Actuators catalog (CAT.E102) for "Required Conditions for Regeneration Option".

Step 2 **Check the cycle time.**

Calculate the cycle time using the following calculation method.

- Cycle time T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \ [s]$$

- T1: Acceleration time and T3: Deceleration time can be obtained by the following equation.

$$T1 = V/a1 \ [s] \qquad T3 = V/a2 \ [s]$$

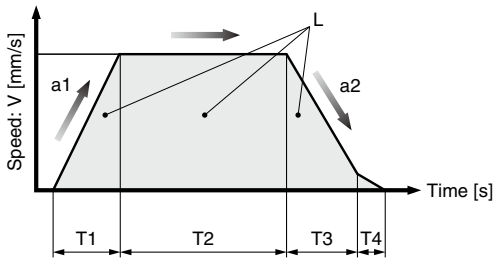
- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \ [s]$$

- T4: Settling time varies depending on the conditions such as motor types, load and in positioning of the step data. Therefore, please calculate the settling time with reference to the following value.

$$T4 = 0.05 \ [s]$$

∗ The conditions for the settling time vary depending on the AC servo motor or driver to be used.



L : Stroke [mm] ····· (Operating condition)
V : Speed [mm/s] ····· (Operating condition)
a1: Acceleration [mm/s^2] ··· (Operating condition)
a2: Deceleration [mm/s^2] ··· (Operating condition)

T1: Acceleration time [s] ··· Time until reaching the set speed
T2: Constant speed time [s] ··· Time while the actuator is operating at a constant speed
T3: Deceleration time [s] ··· Time from the beginning of the constant speed operation to stop
T4: Settling time [s] ··· Time until in position is completed

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 300/5000 = 0.06$ [s], $T3 = V/a2 = 300/5000 = 0.06$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{300 - 0.5 \cdot 300 \cdot (0.06 + 0.06)}{300} = 0.94 \ [s]$$

$T4 = 0.05$ [s]

Therefore, the cycle time can be obtained as follows.
$T = T1 + T2 + T3 + T4 = 0.06 + 0.94 + 0.06 + 0.05 =$ **1.11 [s]**

Based on the above calculation result, the LEY25□B-300 is selected.

Selection Procedure

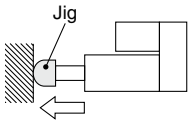
Pushing Control Selection Procedure

Step 1 Check the pushing force. → **Step 2** Check the lateral load on the rod end.

Selection Example

Operating conditions

- Mounting condition: Horizontal (pushing)
- Jig weight: 0.5 [kg]
- Pushing force: 200 [N]
- Speed: 100 [mm/s]
- Stroke: 300 [mm]



Step 1 **Check the pushing force. <Force conversion graph>**

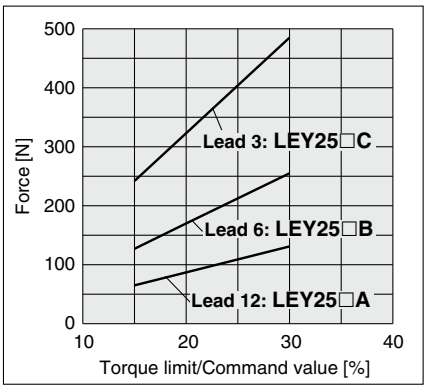
Select the target model based on the torque limit/command value and pushing force with reference to the <Force conversion graph>.

Selection example)

Based on the graph shown on the right side,

- Torque limit/Command value: 24 [%]
- Pushing force: 200 [N]

Therefore, the **LEY25B** is temporarily selected.



<Force conversion graph> (LEY25□)

Step 2 **Check the lateral load on the rod end. <Graph of allowable lateral load on the rod end>**

Confirm the allowable lateral load on the rod end of the actuator: LEY25B, which has been selected temporarily with reference to the <Graph of allowable lateral load on the rod end>.

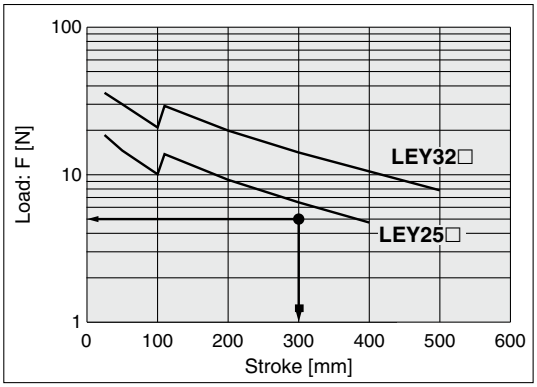
Selection example)

Based on the graph shown on the right side,

- Jig weight: 0.2 [kg] ≈ 2 [N]
- Product stroke: 200 [mm]

Therefore, the lateral load on the rod end is in the allowable range.

Based on the above calculation result, the LEY25B-300 is selected.

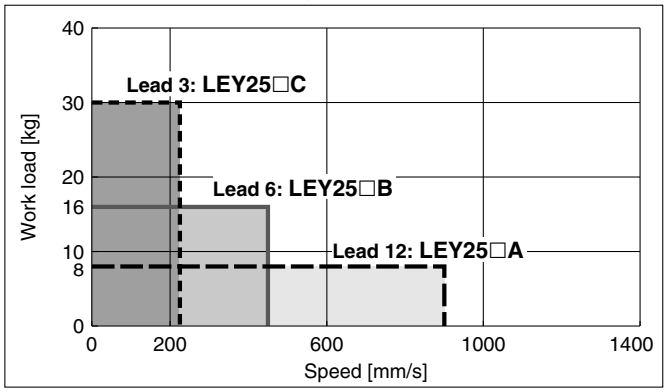


<Graph of allowable lateral load on the rod end>

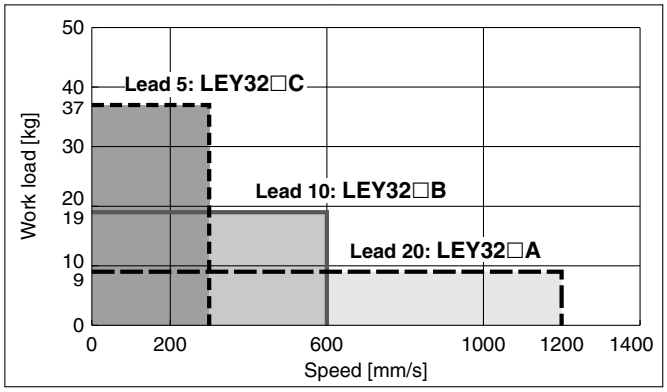
Speed–Vertical Work Load Graph

∗ The values shown below are allowable values of the actuator body.
Do not use the actuator so that it exceeds these specification ranges.

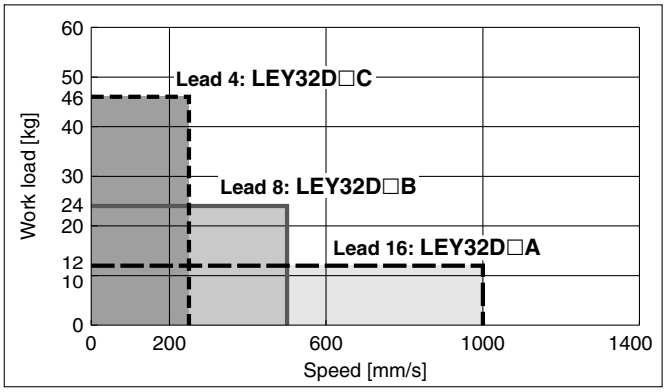
LEY25□ (Motor mounting position: Top/Parallel, In-line)



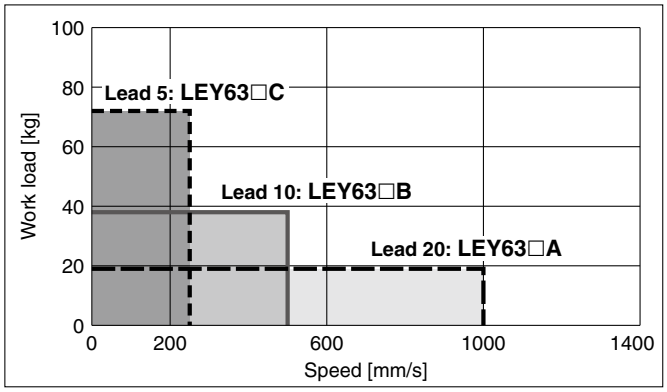
LEY32□ (Motor mounting position: Top/Parallel)



LEY32D (Motor mounting position: In-line)



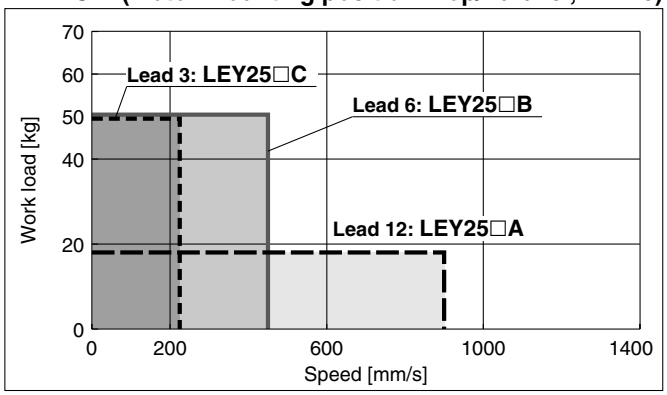
LEY63□



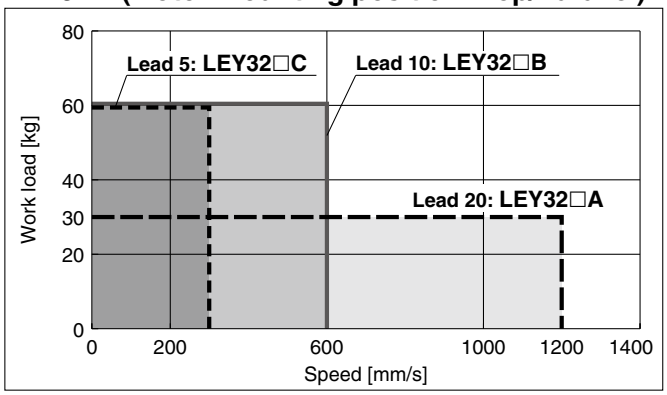
Speed–Horizontal Work Load Graph

∗ The values shown below are allowable values of the actuator body.
Do not use the actuator so that it exceeds these specification ranges.

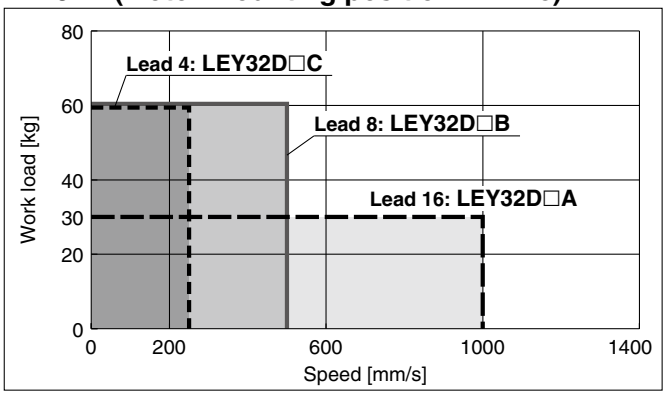
LEY25□ (Motor mounting position: Top/Parallel, In-line)



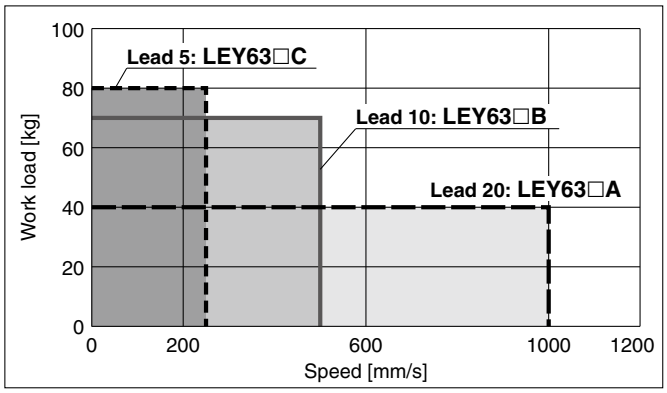
LEY32□ (Motor mounting position: Top/Parallel)



LEY32D (Motor mounting position: In-line)



LEY63□



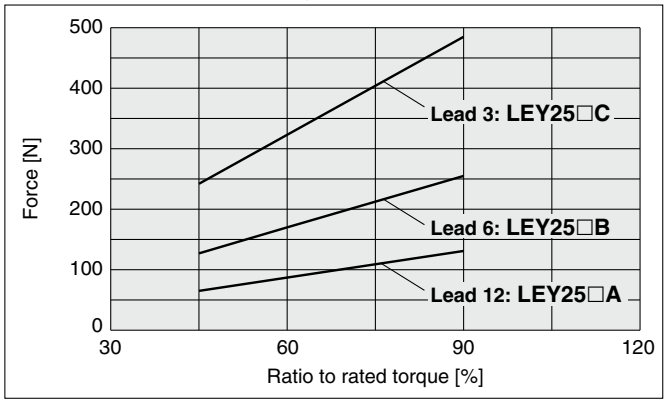
Allowable Stroke Speed

[mm/s]

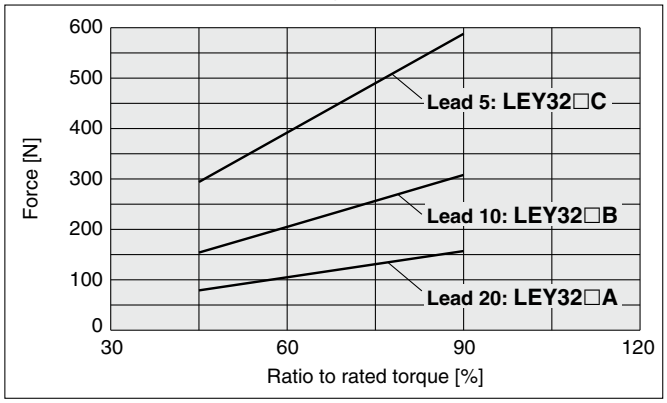
Model	AC servo motor	Lead		Stroke [mm]													
		Symbol	[mm]	30	50	100	150	200	250	300	350	400	450	500	600	700	800
LEY25□ (Motor mounting position: Top/Parallel, In-line)	100 W /□40	**A**	12	900							600		—	—	—	—	—
		B	6	450							300		—	—	—	—	—
		C	3	225							150		—	—	—	—	—
		(Motor rotation speed)		(4500 rpm)							(3000 rpm)		—	—	—	—	—
LEY32□ (Motor mounting position: Top/Parallel	200 W /□60	**A**	20	1200									800		—	—	—
		B	10	600									400		—	—	—
		C	5	300									200		—	—	—
		(Motor rotation speed)		(3600 rpm)									(2400 rpm)		—	—	—
LEY32D (Motor mounting position: In-line	200 W /□60	**A**	16	1000									640		—	—	—
		B	8	500									320		—	—	—
		C	4	250									160		—	—	—
		(Motor rotation speed)		(3750 rpm)									(2400 rpm)		—	—	—
LEY63□	400 W /□60	**A**	20	—		1000	—	1000	—	1000	—	1000	—	1000	800	600	500
		B	10	—		500	—	500	—	500	—	500	—	500	400	300	250
		C	5	—		250	—	250	—	250	—	250	—	250	200	150	125
		(Motor rotation speed)		—		(3000 rpm)	—	(3000 rpm)	—	(3000 rpm)	—	(3000 rpm)	—	(3000 rpm)	(2400 rpm)	(1800 rpm)	(1500 rpm)

Force Conversion Graph (Guide)

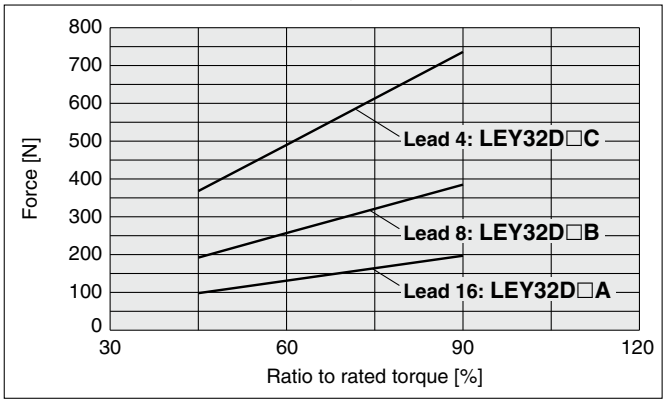
LEY25□ (Motor mounting position: Top/Parallel, In-line)



LEY32□ (Motor mounting position: Top/Parallel)

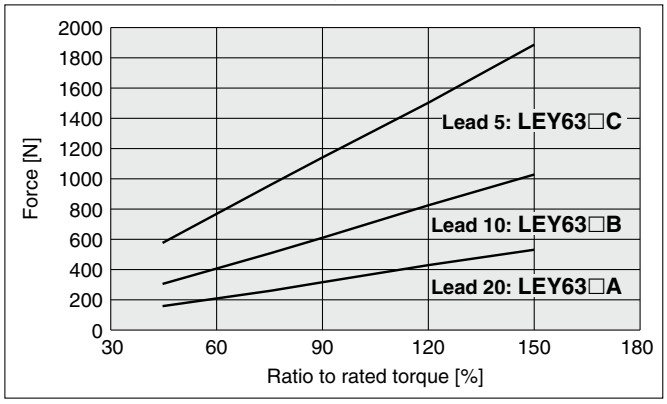


LEY32D□ (Motor mounting position: In-line)



∗ When using the force control or speed control, set the maximum value to be no more than 90% of the rated torque.

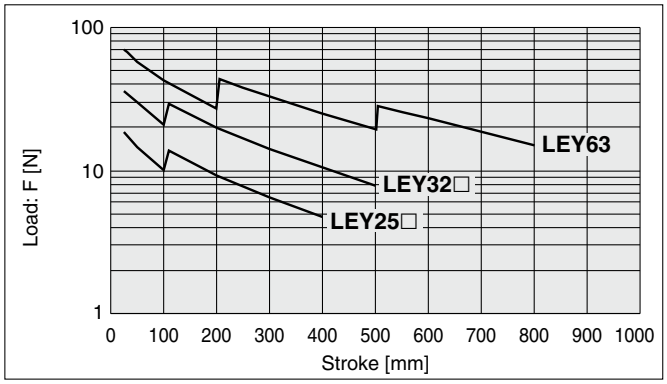
LEY63□ (Motor mounting position: In-line)



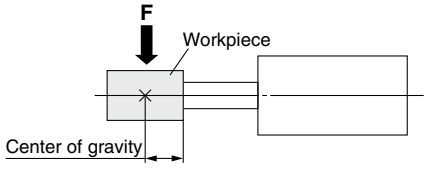
Ratio to rated torque [%]	Duty ratio [%]	Continuous pushing time [minute]
75 or less	100	—
90	100 (60)	— (1.5)
120	50 (30)	1.5 (0.5)
150	30 (20)	0.5 (0.16)

∗1 The values in ( ) are for a closely-mounted driver.
∗2 When using the force control or speed control, set the maximum value to be no more than 150% of the rated torque.

Graph of Allowable Lateral Load on the Rod End (Guide)



[Stroke] = [Product stroke] + [Distance from the rod end to the center of gravity of the workpiece]



Electric Actuator/Rod Type

Motorless Type

Series LEY

LEY25, 32, 63

Size 25, 32, 63

RoHS

How to Order

LEY 25 ❶ ❷ NZ ❸ B ❹ – 500 ❺ ❻ ❼ ❽

❶ Size

25
32
63

❷ Motor mounting position

Nil	Top mounting
R	Right side parallel
L	Left side parallel
D	In-line

∗ Size 63: In-line type only

❸ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y

∗ Refer to the “Compatible Motors”.

∗ When no motor flange is required, use "NN" for the motor type symbol.
Please order “motor flange option” on pages 75 and 76 separately.

❹ Lead [mm]

Symbol	LEY25	LEY32	LEY63
A	12	16 (20)	20
B	6	8 (10)	10
C	3	4 (5)	5

∗ The values shown in ( ) are the lead for top mounting, right/left side parallel types.
(Equivalent lead which includes the pulley ratio [1.25:1])

❺ Stroke [mm]

30	30
to	to
800	800

∗ Refer to the applicable stroke table.

❻ Dust/Drip proof <Only available for LEY63>

Symbol	LEY25/32	LEY63
Nil	Without enclosure	IP5x (Dust proof specification)
P	—	IP65 (Dust/Drip proof specification)/ With vent hole tap

∗ When using the dust/drip proof (IP65), correctly mount the fitting and tubing to the vent hole tap, and then place the end of the tubing in an area not exposed to dust or water.

∗ The fitting and tubing should be provided separately by the customer.
Select [Applicable tubing O.D.: ø4 or more, Connection thread: Rc1/8].

❼ Rod end thread

Nil	Rod end female thread
M	Rod end male thread (1 rod end nut is included.)

❽ Mounting

Symbol	Type	Motor mounting position	
		Top/Parallel	In-line
Nil	Ends tapped (Standard)	●	●
U	Body bottom tapped	●	●
L	Foot	●	—
F	Rod flange	●	●
G	Head flange	●	—
D	Double clevis	●	—

∗ Mounting bracket is shipped together, (but not assembled).

∗ For horizontal cantilever mounting with the ends tapped, rod flange and head flange, use the actuator within the following stroke range.
· LEY25: 200 or less, LEY32: 100 or less, LEY63: 100 or less

∗ For mounting with the double clevis, use the actuator within the following stroke range.
· LEY25: 200 or less, LEY32: 200 or less

∗ Head flange is not available for the LEY32.

∗ Applicable stroke table ● Standard

Model \ Stroke (mm)	30	50	100	150	200	250	300	350	400	450	500	600	700	800
LEY25	●	●	●	●	●	●	●	●	●	—	—	—	—	—
LEY32	●	●	●	●	●	●	●	●	●	●	●	—	—	—
LEY63	—	—	●	—	●	—	●	—	●	—	●	●	●	●

∗ Consult with SMC for the manufacture of intermediate strokes.

Compatible Motors

Applicable motor model			Size/Motor type					
			25		32		63	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—	●	—
	MELSERVO-J3	HF-KP						
	MELSERVO-J4	HG-KR						
YASKAWA Electric Corporation	Σ-V	SGMJV						
SANYO DENKI CO., LTD.	SANMOTION R	R2						
OMRON Corporation	Sysmac G5	R88M-K			—	●	—	●
Panasonic Corporation	MINAS-A4	MSMD	—					
	MINAS-A5	MSMD/MHMD						

Specifications

Model				LEY25N∗□ (Top/Parallel) LEY25DN∗□ (In-line)			LEY32N∗□ (Top/Parallel)			LEY32DN∗□ (In-line)		
Actuator specifications	Stroke [mm] Note 1)			30, 50, 100, 150, 200, 250 300, 350, 400			30, 50, 100, 150, 200, 250 300, 350, 400, 450, 500			30, 50, 100, 150, 200, 250 300, 350, 400, 450, 500		
	Work load [kg]		Horizontal Note 2)	18	50	50	30	60	60	30	60	60
			Vertical	8	16	30	9	19	37	12	24	46
	Pushing force [N] Note 3) (Set value: Rated torque 30 to 90%)			65 to 131	127 to 255	242 to 485	79 to 157	154 to 308	294 to 588	98 to 197	192 to 385	368 to 736
	Max. Note 4) speed [mm/s]	Stroke range	Up to 300	900	450	225	1200	600	300	1000	500	250
			305 to 400	600	300	150						
			405 to 500	—	—	—	800	400	200	640	320	160
	Pushing speed [mm/s] Note 5)			35 or less			30 or less					
	Max. acceleration/deceleration [mm/s²]			5000								
	Positioning repeatability [mm]			±0.02								
	Ball screw specifications	Thread size [mm]		ø10			ø12					
		Lead [mm] (including pulley ratio)		12	6	3	16 (20)	8 (10)	4 (5)	16	8	4
		Shaft length [mm]		Stroke + 93.5			Stroke + 104.5					
	Impact/Vibration resistance [m/s²] Note 6)			50/20								
	Actuation type			Ball screw + Belt (LEY□) Ball screw (LEY□D)			Ball screw + Belt [Pulley ratio 1.25:1]			Ball screw		
	Guide type			Sliding bushing (Piston rod)								
	Operating temperature range [°C]			5 to 40								
	Operating humidity range [%RH]			90 or less (No condensation)								
Applicable motor specifications	Motor shape			□40			□60					
	Motor type			AC servo motor								
	Rated output capacity [W]			100			200					
	Rated torque [N·m]			0.32			0.64					
	Rated rotation [rpm]			3000								
Other specifications Note 7)	Actuation unit weight [kg] (∗ [ST]: Stroke)			0.15 + (0.69 x 10^{-3}) x [ST]: 100 st or less 0.16 + (0.69 x 10^{-3}) x [ST]: Over 100 st			0.24 + (1.40 x 10^{-3}) x [ST]: 100 st or less 0.28 + (1.40 x 10^{-3}) x [ST]: Over 100 st					
	Other inertia [kg·cm²]			0.012 (LEY□) 0.015 (LEY□D)			0.035 (LEY□) 0.061 (LEY□D)					
	Mechanical efficiency			0.8								

Note 1) Consult with SMC for the manufacture of strokes other than shown above.
Note 2) The maximum value of the horizontal work load. An external guide is necessary to support the load. The actual work load changes according to the condition of the external guide. Please confirm using actual device.
Note 3) The force setting range for the pushing operation (Speed control mode, Torque control mode).
The pushing force changes according to the set value. Set it with reference to "Force Conversion Graph" on page 53.
Note 4) The allowable speed changes according to the stroke.
Note 5) The allowable collision speed for the pushing operation.
Note 6) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Note 7) Each value is a guide. Use such value to select a motor capacity.

Weight

Product Weight

Series	LEY25N∗□ (Motor mounting position: Top/Parallel)									LEY32N∗□ (Motor mounting position: Top/Parallel)									
Stroke [mm]	30	50	100	150	200	250	300	350	400	30	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	0.81	0.88	1.05	1.31	1.49	1.66	1.84	2.01	2.19	1.42	1.53	1.82	2.29	2.57	2.85	3.14	3.42	3.70	3.98	4.26

Series	LEY25DN∗□ (Motor mounting position: In-line)									LEY32DN∗□ (Motor mounting position: In-line)									
Stroke [mm]	30	50	100	150	200	250	300	350	400	30	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	0.84	0.91	1.08	1.34	1.52	1.69	1.87	2.04	2.22	1.44	1.55	1.84	2.31	2.59	2.87	3.16	3.44	3.72	4.00	4.28

Additional Weight

[kg]

Size		25	32
Rod end male thread	Male thread	0.03	0.03
	Nut	0.02	0.02
Foot (2 sets including mounting bolt)		0.08	0.14
Rod flange (including mounting bolt)		0.17	0.20
Head flange (including mounting bolt)			
Double clevis (including pin, retaining ring and mounting bolt)		0.16	0.22

Specifications

Model				LEY63DN∗□ (In-line)		
Actuator specifications	Stroke [mm] Note 1)			100, 200, 300, 400, 500, 600, 700, 800		
	Work load [kg]		Horizontal Note 2)	40	70	80
			Vertical	19	38	72
	Pushing force [N] Note 3) (Set value: Rated torque 30 to 150%)			156 to 521	304 to 1012	573 to 1910
	Max. Note 4) speed [mm/s]	Stroke range	Up to 500	1000	500	250
			505 to 600	800	400	200
			605 to 700	600	300	150
			705 to 800	500	250	125
	Pushing speed [mm/s] Note 5)			30 or less		
	Max. acceleration/deceleration [mm/s²]			5000		
	Positioning repeatability [mm]			±0.02		
	Ball screw specifications		Thread size [mm]	ø20		
			Lead [mm]	20	10	5
			Shaft length [mm]	Stroke + 147		
	Impact/Vibration resistance [m/s²] Note 6)			50/20		
	Actuation type			Ball screw		
	Guide type			Sliding bushing (Piston rod)		
	Operating temperature range [°C]			5 to 40		
	Operating humidity range [%RH]			90 or less (No condensation)		
Applicable motor specifications	Motor shape			□60		
	Motor type			AC servo motor		
	Rated output capacity [W]			400		
	Rated torque [N·m]			1.27		
	Rated rotation [rpm]			3000		
Other specifications Note 7)	Actuation unit weight [kg] (∗ [ST]: Stroke)			0.84 + (2.77 x 10⁻³) x [ST]: 200 st or less 0.94 + (2.77 x 10⁻³) x [ST]: Over 200 st, 500 st or less 1.03 + (2.77 x 10⁻³) x [ST]: Over 500 st		
	Other inertia [kg·cm²]			0.056		
	Mechanical efficiency			0.8		

Note 1) Consult with SMC for the manufacture of strokes other than shown above.
Note 2) The maximum value of the horizontal work load. An external guide is necessary to support the load. The actual work load changes according to the condition of the external guide. Please confirm using actual device.
Note 3) The force setting range for the pushing operation (Speed control mode, Torque control mode).
The pushing force changes according to the set value. Set it with reference to "Force Conversion Graph" on page 53.
Note 4) The allowable speed changes according to the stroke.
Note 5) The allowable collision speed for the pushing operation.
Note 6) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Note 7) Each value is a guide. Use such value to select a motor capacity.

Weight

Product Weight

Series	LEY63DN∗□ (Motor mounting position: In-line)							
Stroke [mm]	100	200	300	400	500	600	700	800
Product weight [kg]	4.2	5.3	7.0	8.2	9.3	11.0	12.1	13.3

Additional Weight

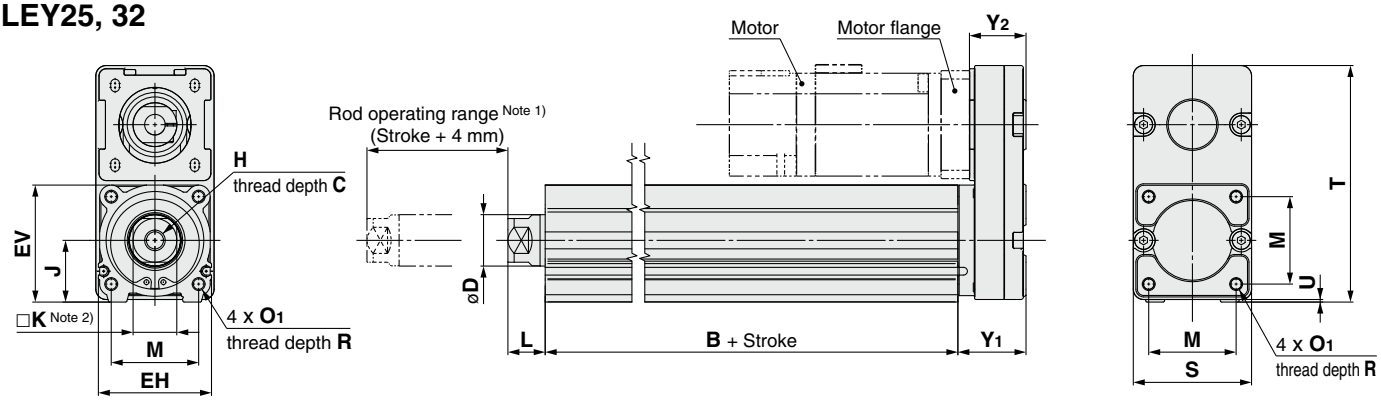
[kg]

Size		63
Rod end male thread	Male thread	0.12
	Nut	0.04
Rod flange (including mounting bolt)		0.51

Refer to "Motor Mounting" on page 73 for details about motor mounting and included parts.

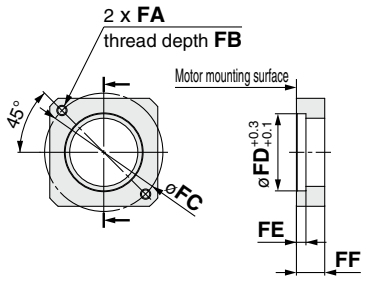
Dimensions: Motor Top/Parallel

LEY25, 32

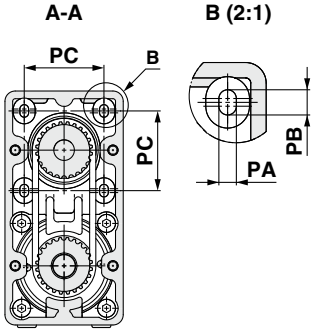


Note 1) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed".
Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 2) The direction of rod end width across flats (□K) differs depending on the products.

Motor flange dimensions



Without motor flange: LEY $^{25}_{32}$□NN



Dimensions

[mm]

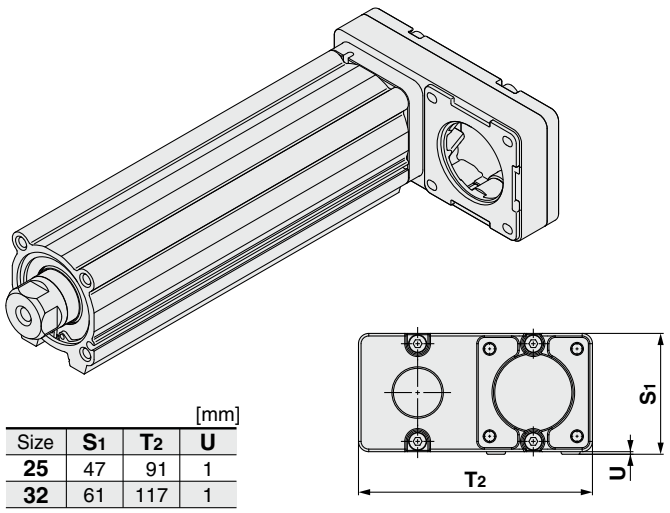
Size	Stroke range (mm)	B	C	D	EH	EV	H	J	K	L	M	O1	R	S	T	U	Y1	Y2
25	15 to 100	89.5	13	20	44	45.5	M8 x 1.25	24	17	12.5	34	M5 x 0.8	8	46	92	1	26.5	22
	105 to 400	114.5																
32	20 to 100	96	13	25	51	56.5	M8 x 1.25	31	22	16.5	40	M6 x 1.0	10	60	118	1	34	27
	105 to 500	126																

∗ The L measurement is when the unit is at the retracted stroke end position.

Size	Motor type	FA	FB	FC	FD	FE	FF
25	**NZ**	M4 x 0.7	7.5	46	30	3.7	11
32	**NZ**	M5 x 0.8	8.5	70	50	3.3	13
	NY	M4 x 0.7	8	70	50	3.3	13

Size	Motor type	PA	PB	PC
25	**NN**	3.4	4.9	31
32	**NN**	4.4	5.9	47.14

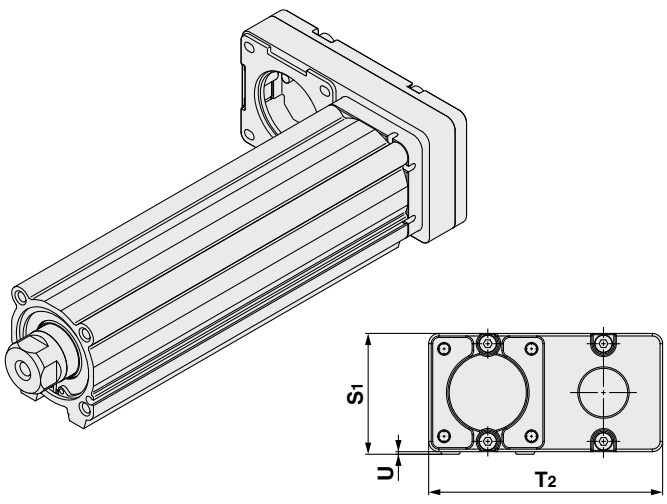
Motor left side parallel type: LEY $^{25}_{32}$L



[mm]

Size	S1	T2	U
25	47	91	1
32	61	117	1

Motor right side parallel type: LEY $^{25}_{32}$R

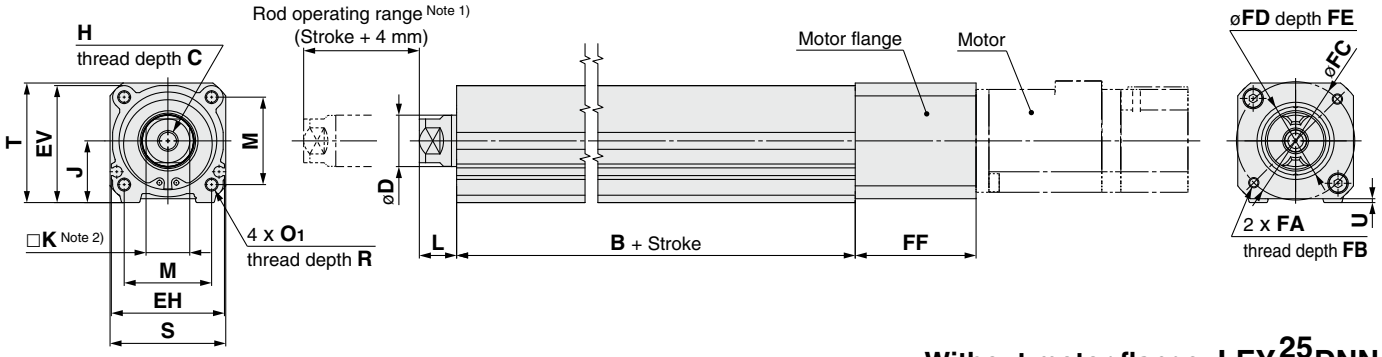


Note) When the motor is mounted on the left or right side in parallel, the groove for auto switch on the side to which the motor is mounted is hidden.

Refer to "Motor Mounting" on page 74 for details about motor mounting and included parts.

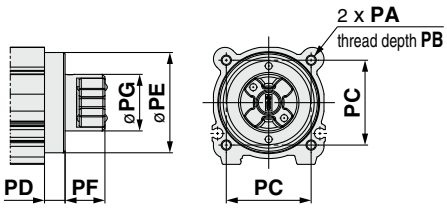
Dimensions: In-line Motor

LEY25, 32



Note 1) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed".
Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 2) The direction of rod end width across flats (□K) differs depending on the products.

Without motor flange: LEY$^{25}_{32}$DNN



Dimensions

[mm]

Size	Stroke range (mm)	B	C	D	EH	EV	H	J	K	L	M	O1	R	S	T	U
25	15 to 100	89.5	13	20	44	45.5	M8 x 1.25	24	17	12.5	34	M5 x 0.8	8	45	46.5	1.5
	105 to 400	114.5														
32	20 to 100	96	13	25	51	56.5	M8 x 1.25	31	22	16.5	40	M6 x 1.0	10	60	61	1
	105 to 500	126														

∗ The L measurement is when the unit is at the retracted stroke end position.

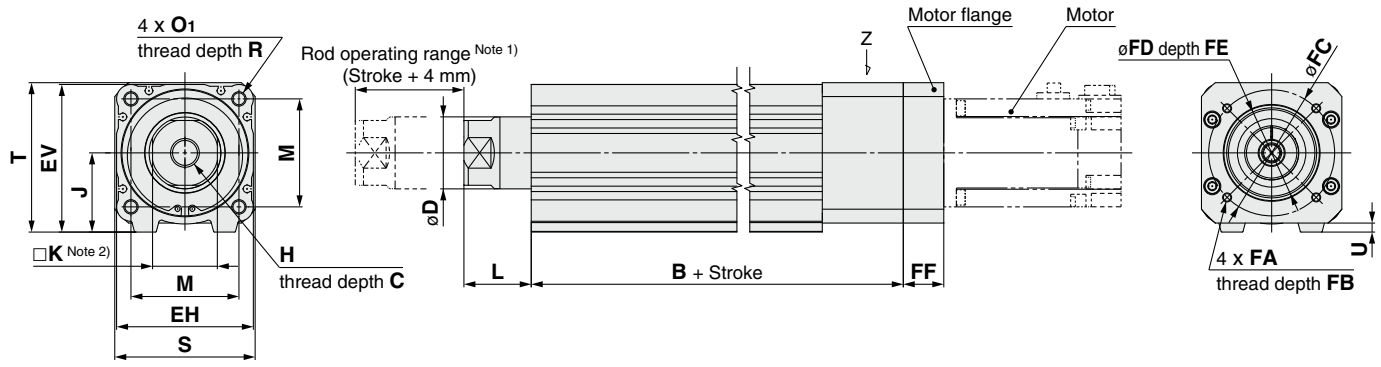
Size	Motor type	FA	FB	FC	FD	FE	FF
25	**NZ**	M4 x 0.7	7.5	46	30	3.7	47
32	**NZ**	M5 x 0.8	8.5	70	50	3.3	60
	NY	M4 x 0.7	8	70	50	3.3	60

Size	Motor type	PA	PB	PC	PD	PE	PF	PG
25	**NN**	M4 x 0.7	6.5	33	8	39	15.5	22
32	**NN**	M6 x 1.0	10	40	10.5	48	18.5	30

Refer to "Motor Mounting" on page 74 for details about motor mounting and included parts.

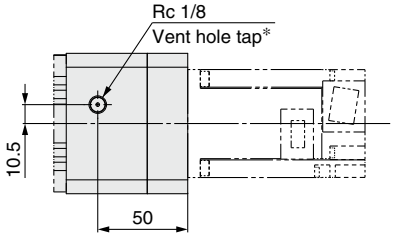
Dimensions: In-line Motor

LEY63



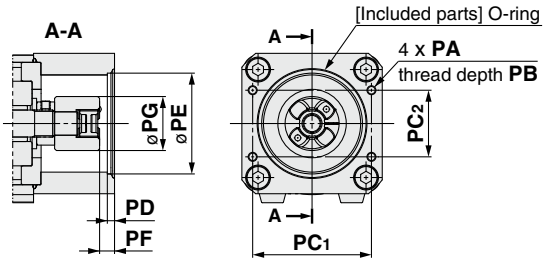
Note 1) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed". Additionally, when running the positioning operation, do not set within 2 mm of both ends.
Note 2) The direction of rod end width across flats (□K) differs depending on the products.

IP65 (Dust/Drip proof specification): LEY63DN□□-□P (View Z)



* When using the dust/drip proof (IP65), correctly mount the fitting and tubing to the vent hole tap, and then place the end of the tubing in an area not exposed to dust or water. The fitting and tubing should be provided separately by the customer.
Select [Applicable tubing O.D.: ø4 or more, Connection thread: Rc1/8].

Without motor flange: LEY63DNN



Dimensions

[mm]

Size	Stroke range (mm)	B	C	D	EH	EV	H	J	K	L	M	O1	R	S	T	U
63	50 to 200	168.2	21	40	76	82	M16 x 2	44	36	33.4	60	M8 x 1.25	16	78	83	5
	205 to 500	203.2														
	505 to 800	238.2														

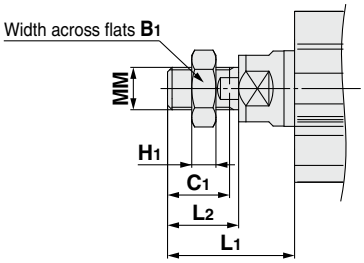
* The L measurement is when the unit is at the retracted stroke end position.

Size	Motor type	FA	FB	FC	FD	FE	FF
63	NZ	M5 x 0.8	10	70	50	3.5	22.5
	NY	M4 x 0.7	8	70	50	3.5	22.5

Size	Motor type	PA	PB	PC1	PC2	PD	PE	PF	PG
63	NN	M5 x 0.8	10	66	37	4	56	8.3	30

Dimensions

End male thread: LEY$^{25}_{32}$$^{A}_{C}$□□B-□□M



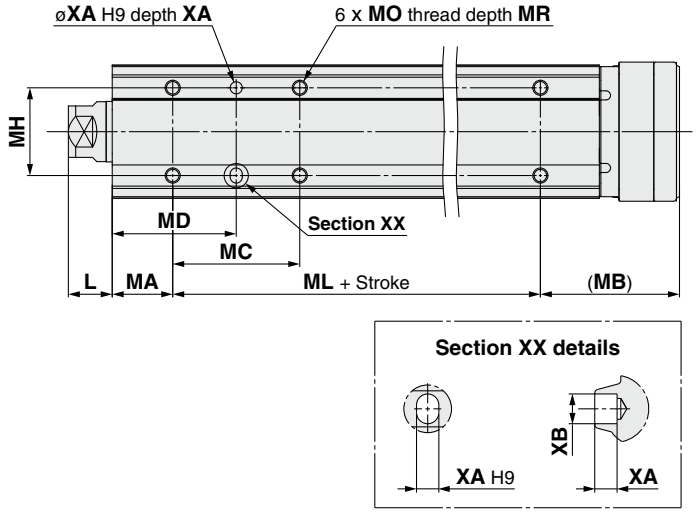
∗ Refer to Electric Actuators catalog (CAT.E102) for details about the rod end nut and mounting bracket.
Note) Refer to the "Mounting" precautions on pages 78 and 79 when mounting end brackets such as knuckle joint or workpieces.

[mm]

Size	B1	C1	H1	L1	L2	MM
25	22	20.5	8	36	23.5	M14 x 1.5
32	22	20.5	8	40	23.5	M14 x 1.5
63	27	26	11	72.4	39	M18 x 1.5

∗ The L1 measurement is when the unit is at the retracted stroke end position.

Body bottom tapped, Motor top/parallel: LEY$^{25}_{32}$$^{A}_{C}$□□B-□□□U

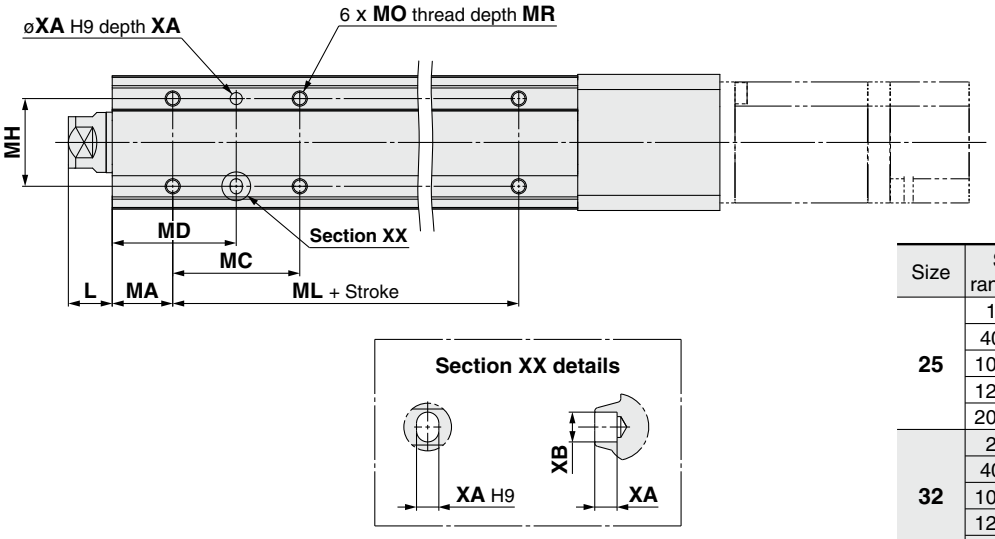


[mm]

Size	Stroke range (mm)	L	MA	MB	MC	MD	MH	ML
25	15 to 39	12.5	20	46	24	32	29	50
	40 to 100				42	41		
	101 to 124							75
	125 to 200				59	49.5		
	201 to 400				76	58		
32	20 to 39	16.5	25	55	22	36	30	50
	40 to 100				36	43		
	101 to 124							80
	125 to 200				53	51.5		
	201 to 500				70	60		
63	50 to 74	33.4	38	—	24	50	44	65
	75 to 124				45	60.5		
	125 to 200				58	67		
	201 to 500				86	81		100
	501 to 800							135

∗ The L measurement is when the unit is at the retracted stroke end position.

Body bottom tapped, In-line motor: LEY$^{25}_{32}$$^{A}_{C}$□□B-□□□U



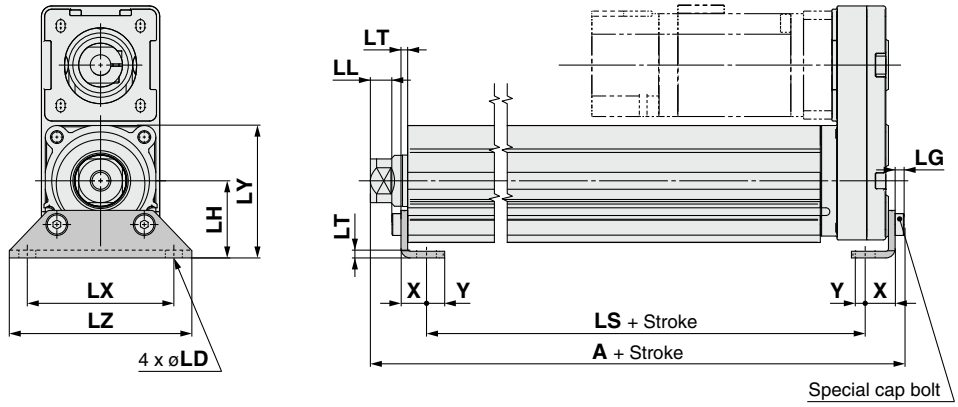
[mm]

Size	Stroke range (mm)	MO	MR	XA	XB
25	15 to 39	M5 x 0.8	6.5	4	5
	40 to 100				
	101 to 124				
	125 to 200				
	201 to 400				
32	20 to 39	M6 x 1.0	8.5	5	6
	40 to 100				
	101 to 124				
	125 to 200				
	201 to 500				
63	50 to 74	M8 x 1.25	10	6	7
	75 to 124				
	125 to 200				
	201 to 500				
	501 to 800				

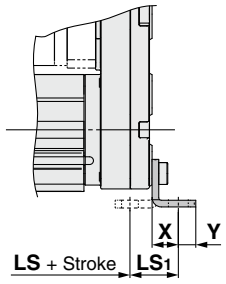
Dimensions

Foot: LEY25/32□□A/B/C-□□□L

Included parts
· Foot
· Body mounting bolt



Outward mounting

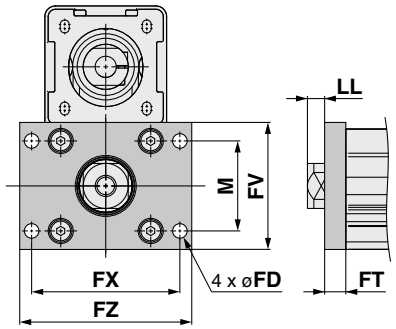


Foot [mm]

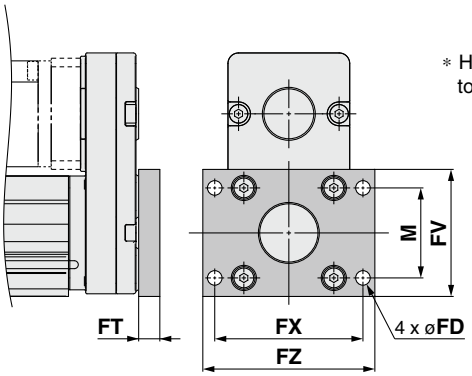
Size	Stroke range (mm)	A	LS	LS1	LL	LD	LG	LH	LT	LX	LY	LZ	X	Y
25	15 to 100	136.6	98.8	19.8	6.4	6.6	3.5	30	2.6	57	51.5	71	11.2	5.8
	101 to 400	161.6	123.8											
32	20 to 100	155.7	114	19.2	9.3	6.6	4	36	3.2	76	61.5	90	11.2	7
	101 to 500	185.7	144											

Material: Carbon steel (Chromate treated)
∗ The A and LL measurements are when the unit is at the retracted stroke end position.
Note) When the motor mounting is the right or left side parallel type, the head side foot should be mounted outwards.

Rod flange: LEY25/32/63□□A/B/C-□□□F



Head flange: LEY25□□A/B/C-□□□G



∗ Head flange is not applicable to the in-line type and LEY32.

Included parts
· Flange
· Body mounting bolt

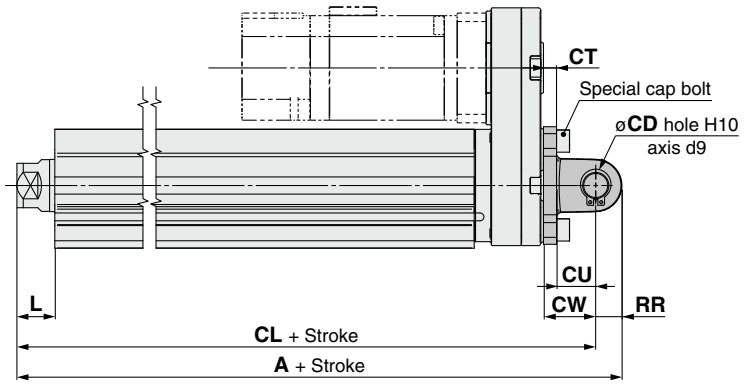
Rod/Head Flange [mm]

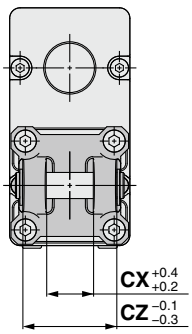
Size	FD	FT	FV	FX	FZ	LL	M
25	5.5	8	48	56	65	4.5	34
32	5.5	8	54	62	72	8.5	40
63	9	9	80	92	108	24.4	60

Material: Carbon steel (Nickel plated)
∗ The LL measurement is when the unit is at the retracted stroke end position.

Dimensions

Double clevis: LEY $\begin{matrix}25\\32\end{matrix}$ **□□** $\begin{matrix}A\\B\\C\end{matrix}$ **-□□□D**





Included parts
- Double clevis
- Body mounting bolt
- Clevis pin
- Retaining ring

∗ Refer to Electric Actuators catalog (CAT.E102) for details about the rod end nut and mounting bracket.

Double Clevis

[mm]

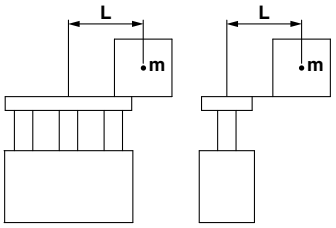
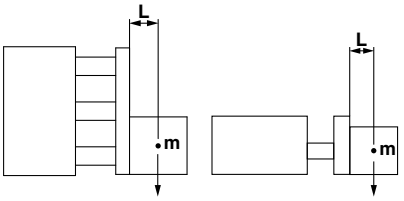
Size	Stroke range (mm)	A	CL	CD	CT	CU	CW	CX	CZ	L	RR
25	15 to 100	158.5	148.5	10	5	14	20	18	36	12.5	10
	101 to 200	183.5	173.5								
32	20 to 100	178.5	168.5	10	6	14	22	18	36	16.5	10
	101 to 200	208.5	198.5								

Material: Cast iron (Coating)
∗ The A, CL and L measurements are when the unit is at the retracted stroke end position.

Series LEYG
Model Selection

Moment Load Graph

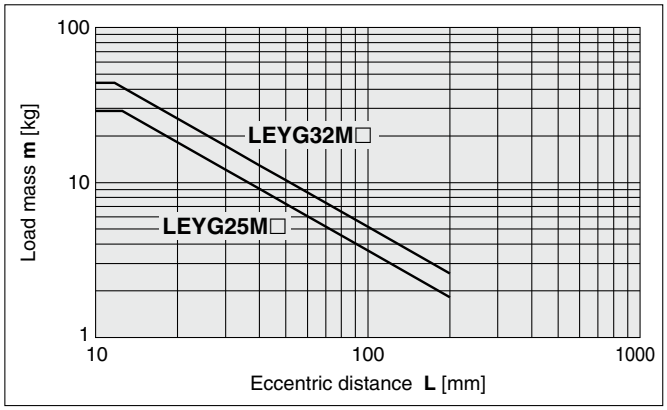
Selection conditions

	Vertical	Horizontal	
Mounting orientation			
Max. speed [mm/s]	"Speed–Vertical Work Load Graph"	200 or less	Over 200
Graph (Sliding bearing type)	①, ②	⑤, ⑥*	⑦, ⑧
Graph (Ball bushing bearing type)	③, ④	⑨, ⑩	⑪, ⑫

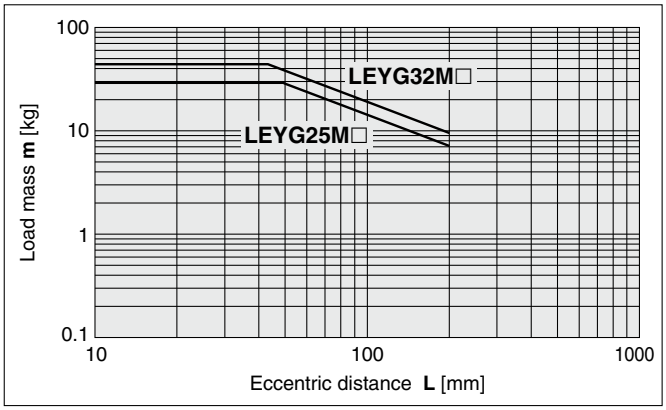
∗ For the sliding bearing type, the speed is restricted with a horizontal/moment load.

Vertical Mounting, Sliding Bearing

① 70 stroke or less



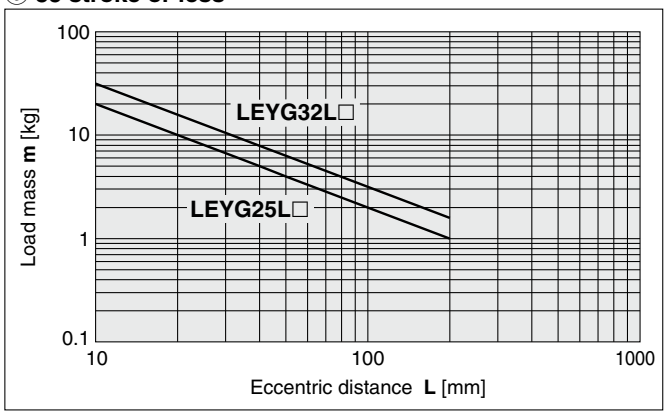
② Over 75 stroke



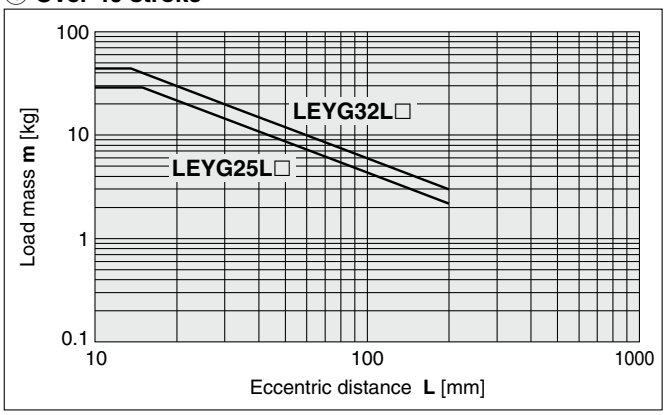
∗ The limit of vertical load mass varies depending on "lead" and "speed".
Check "Speed–Vertical Work Load Graph" on page 67.

Vertical Mounting, Ball Bushing Bearing

③ 35 stroke or less



④ Over 40 stroke

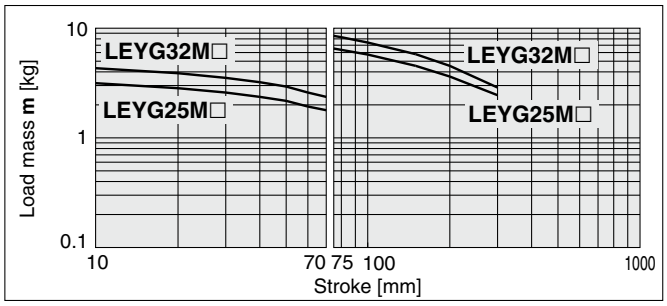


∗ The limit of vertical load mass varies depending on "lead" and "speed".
Check "Speed–Vertical Work Load Graph" on page 67.

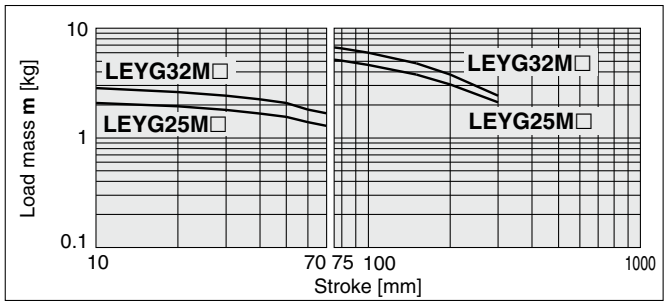
Moment Load Graph

Horizontal Mounting, Sliding Bearing

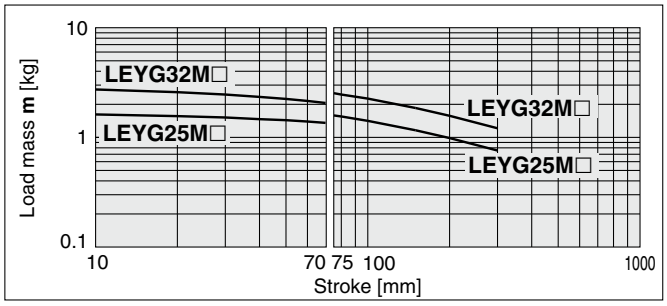
⑤ **L = 50 mm Max. speed = 200 mm/s or less**



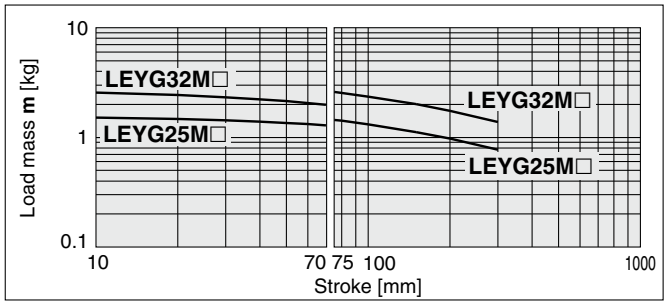
⑥ **L = 100 mm Max. speed = 200 mm/s or less**



⑦ **L = 50 mm Max. speed = Over 200 mm/s**

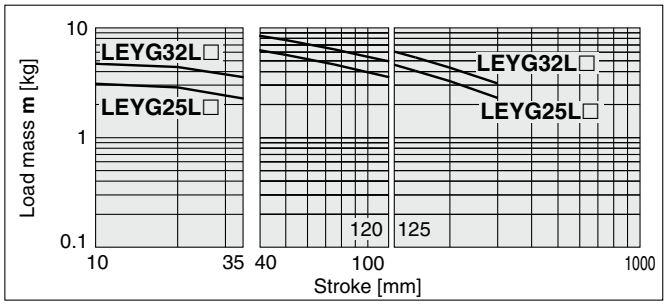


⑧ **L = 100 mm Max. speed = Over 200 mm/s**

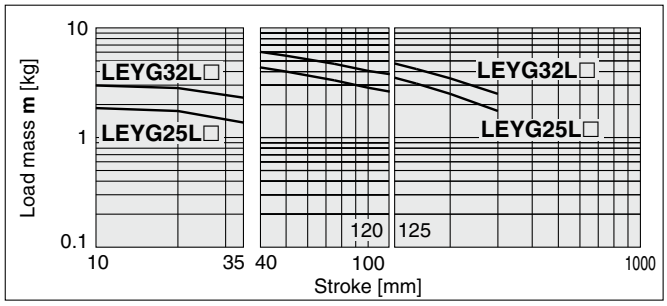


Horizontal Mounting, Ball Bushing Bearing

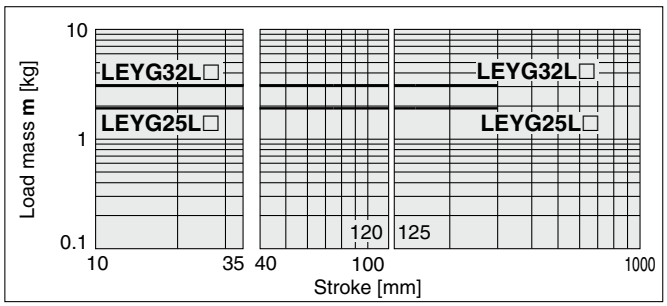
⑨ **L = 50 mm Max. speed = 200 mm/s or less**



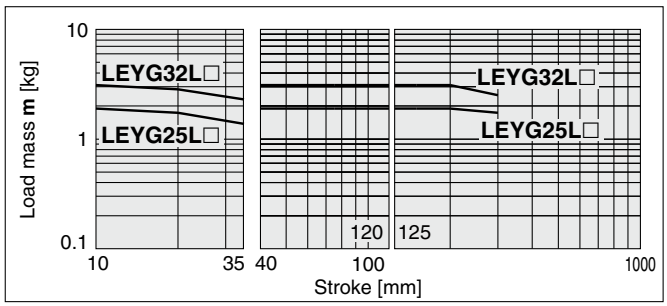
⑩ **L = 100 mm Max. speed = 200 mm/s or less**



⑪ **L = 50 mm Max. speed = Over 200 mm/s**

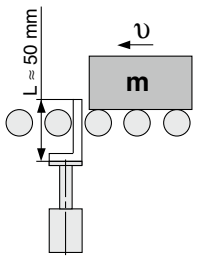


⑫ **L = 100 mm Max. speed = Over 200 mm/s**



Operating Range when Used as Stopper

LEYG□M (Sliding bearing)



⚠Caution

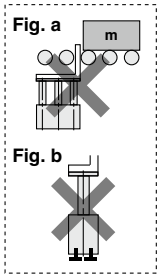
Handling Precautions

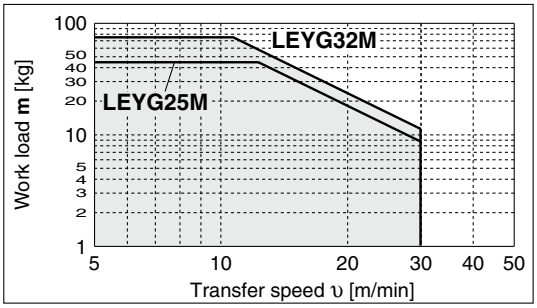
Note 1) When used as a stopper, select a model with 30 stroke or less.

Note 2) LEYG□L (ball bushing bearing) cannot be used as a stopper.

Note 3) Workpiece collision in series with guide rod cannot be permitted (**Fig. a**).

Note 4) The body should not be mounted on the end. It must be mounted on the top or bottom (**Fig. b**).

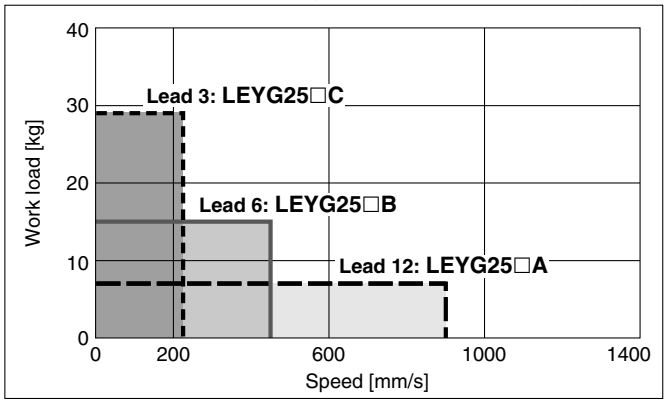




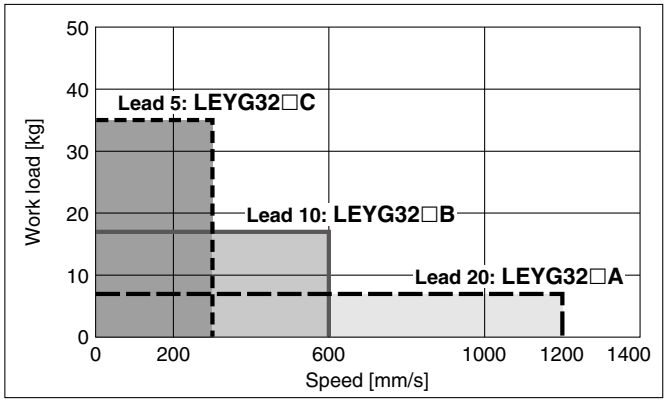
Speed–Vertical Work Load Graph

∗ The values shown below are allowable values of the actuator body.
Do not use the actuator so that it exceeds these specification ranges.

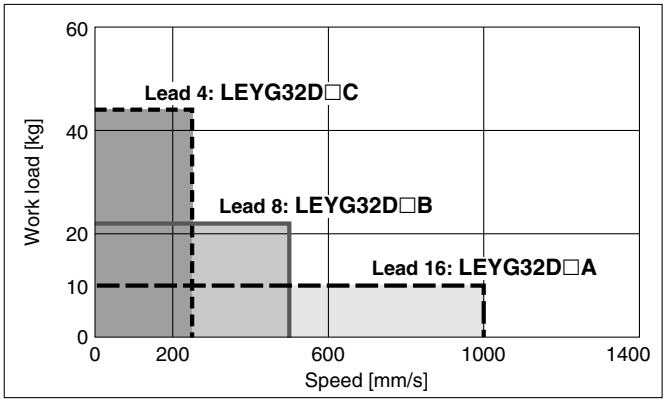
LEYG25□ (Motor mounting position: Top mounting/In-line)



LEYG32□ (Motor mounting position: Top mounting)

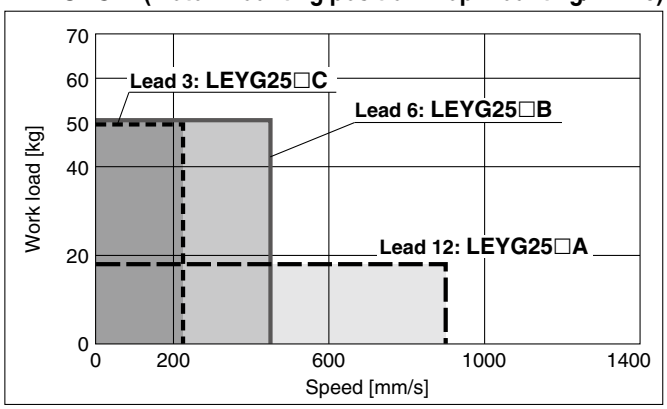


LEYG32D (Motor mounting position: In-line)

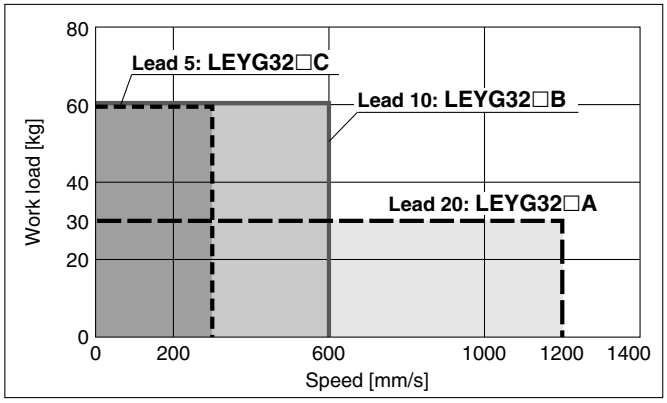


Speed–Horizontal Work Load Graph

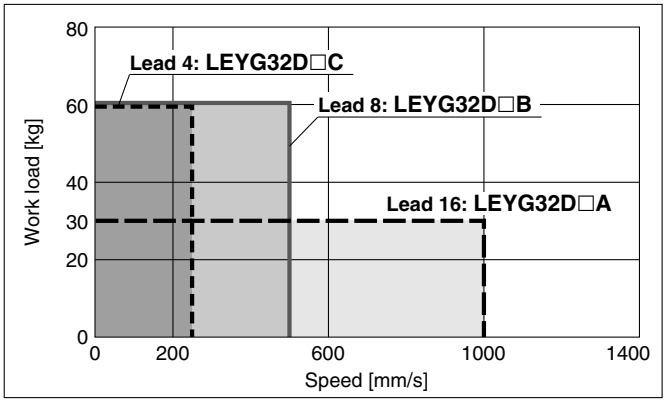
LEYG25□ (Motor mounting position: Top mounting/In-line)



LEYG32□ (Motor mounting position: Top mounting)

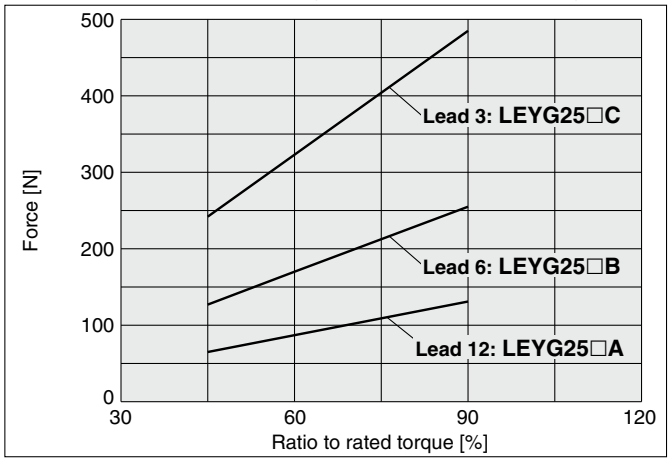


LEYG32D (Motor mounting position: In-line)

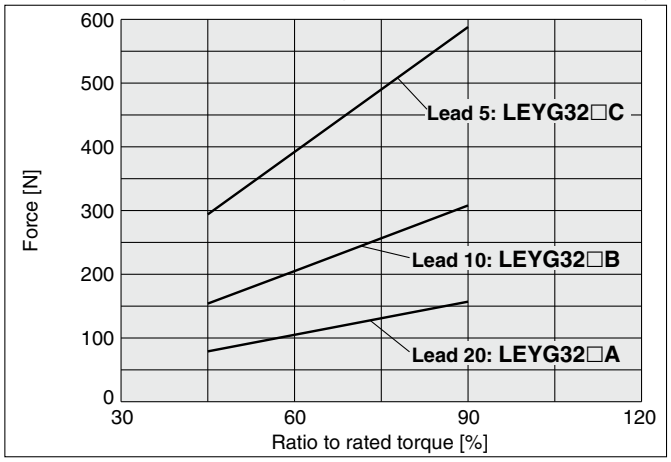


Force Conversion Graph

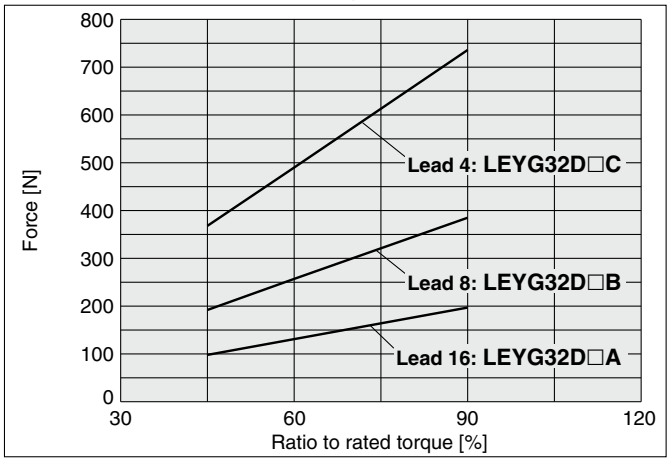
LEYG25□ (Motor mounting position: Top mounting/In-line)



LEYG32□ (Motor mounting position: Top mounting)



LEYG32D (Motor mounting position: In-line)



∗ When using the force control or speed control, set the maximum value to be no more than 90% of the rated torque.

Electric Actuator/Guide Rod Type

Motorless Type

Series LEYG

LEYG25, 32

RoHS

How to Order

LEYG 25 M □ NZ B – 200 □

❶ ❷ ❸ ❹ ❺ ❻ ❼

❶ Size

25
32

❷ Bearing type

M	Sliding bearing
L	Ball bushing bearing

❸ Motor mounting position

Nil	Top mounting
D	In-line

❹ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y

∗ Refer to the “Compatible Motors”.
∗ When no motor flange is required, use "NN" for the motor type symbol.
Please order “motor flange option” on pages 75 and 76 separately.

❺ Lead [mm]

Symbol	LEYG25	LEYG32
A	12	16 (20)
B	6	8 (10)
C	3	4 (5)

❻ Stroke [mm]

30	30
to	to
300	300

∗ Refer to the applicable stroke table.

❼ Guide option

Nil	Without option
F	With grease retaining function

∗ Only available for sliding bearing.

∗ Applicable stroke table ●Standard

Model \ Stroke (mm)	30	50	100	150	200	250	300
LEYG25	●	●	●	●	●	●	●
LEYG32	●	●	●	●	●	●	●

∗ Consult with SMC for the manufacture of intermediate strokes.

Compatible Motors

Applicable motor model			Size/Motor type			
			25		32	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—
	MELSERVO-J3	HF-KP				
	MELSERVO-J4	HG-KR				
YASKAWA Electric Corporation	Σ-V	SGMJV				
SANYO DENKI CO., LTD.	SANMOTION R	R2				
OMRON Corporation	Sysmac G5	R88M-K			—	●
Panasonic Corporation	MINAS-A4	MSMD	—			
	MINAS-A5	MSMD/MHMD				

Specifications

Model			LEYG25□N∗□ (Top mounting) LEYG25□DN∗□ (In-line)			LEYG32□N∗□ (Top mounting)			LEYG32□DN∗□ (In-line)		
Actuator specifications	Stroke [mm] Note 1)		30, 50, 100, 150 200, 250, 300			30, 50, 100, 150 200, 250, 300			30, 50, 100, 150 200, 250, 300		
	Work load [kg]	Horizontal Note 2)	18	50	50	30	60	60	30	60	60
		Vertical	7	15	29	7	17	35	10	22	44
	Pushing force [N] Note 3) (Set value: Rated torque 30 to 90%)		65 to 131	127 to 255	242 to 485	79 to 157	154 to 308	294 to 588	98 to 197	192 to 385	368 to 736
	Max. speed [mm/s]		900	450	225	1200	600	300	1000	500	250
	Pushing speed [mm/s] Note 4)		35 or less			30 or less					
	Max. acceleration/deceleration [mm/s²]		5000								
	Positioning repeatability [mm]		±0.02								
	Ball screw specifications	Thread size [mm]	ø10			ø12					
		Lead [mm] (including pulley ratio)	12	6	3	16 (20)	8 (10)	4 (5)	16	8	4
		Shaft length [mm]	Stroke + 93.5			Stroke + 104.5					
	Impact/Vibration resistance [m/s²] Note 5)		50/20								
	Actuation type		Ball screw + Belt (LEY□) Ball screw (LEY□D)			Ball screw + Belt [Pulley ratio 1.25:1]			Ball screw		
	Guide type		Sliding bearing (LEYG□M), Ball bushing bearing (LEYG□L)								
	Operating temperature range [°C]		5 to 40								
	Operating humidity range [%RH]		90 or less (No condensation)								
Applicable motor specifications	Motor shape		□40			□60					
	Motor type		AC servo motor								
	Rated output capacity [W]		100			200					
	Rated torque [N·m]		0.32			0.64					
	Rated rotation [rpm]		3000								
Other specifications Note 6)	Actuation unit weight [kg] (∗ [ST]: Stroke)	LEYG□M Sliding bearing	0.29 + (2.20 x 10⁻³) x [ST]: 185 st or less 0.34 + (1.92 x 10⁻³) x [ST]: Over 185 st			0.48 + (2.91 x 10⁻³) x [ST]: 180 st or less 0.55 + (2.62 x 10⁻³) x [ST]: Over 180 st					
		LEYG□L Ball bushing bearing	0.33 + (1.69 x 10⁻³) x [ST]: 110 st or less 0.36 + (1.80 x 10⁻³) x [ST]: Over 110 st			0.50 + (2.40 x 10⁻³) x [ST]: 110 st or less 0.55 + (2.51 x 10⁻³) x [ST]: Over 110 st					
	Other inertia [kg·cm²]		0.012 (LEY□) 0.015 (LEY□D)			0.035 (LEY□) 0.061 (LEY□D)					
	Mechanical efficiency		0.8								

Note 1) Consult with SMC for the manufacture of strokes other than shown above.
Note 2) The maximum value of the horizontal work load. An external guide is necessary to support the load. The actual work load changes according to the condition of the external guide. Please confirm using actual device.
Note 3) The force setting range for the pushing operation (Speed control mode, Torque control mode).
The pushing force changes according to the set value. Set it with reference to "Force Conversion Graph" on page 68.
Note 4) The allowable collision speed for the pushing operation.
Note 5) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Note 6) Each value is a guide. Use such value to select a motor capacity.

Weight

Product Weight

[kg]

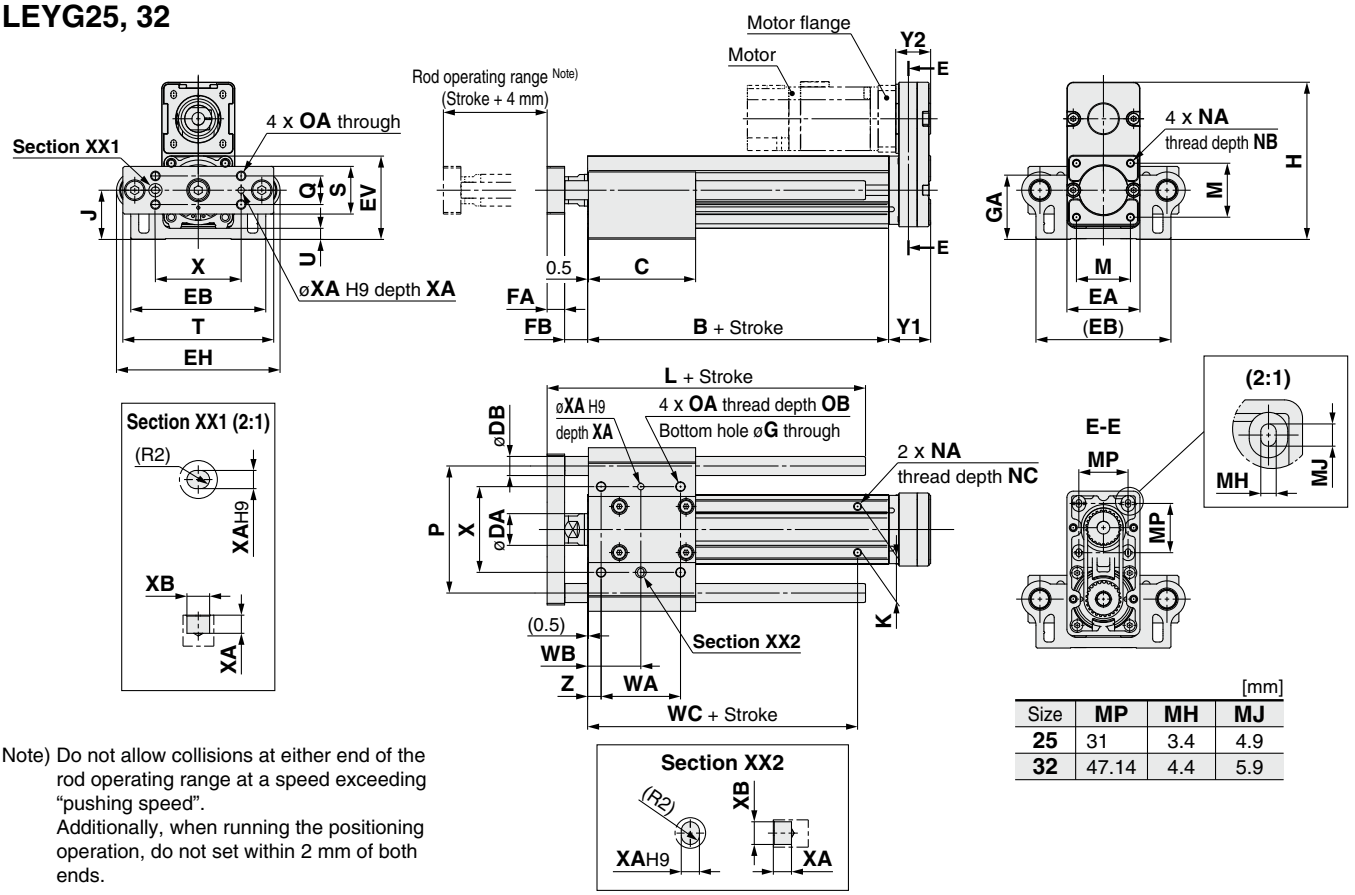
Series	LEYG25□N∗□ (Motor mounting position: Top mounting)							LEYG32□N∗□ (Motor mounting position: Top mounting)						
Stroke [mm]	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Sliding bearing LEYG□M	1.30	1.49	1.81	2.23	2.57	2.91	3.17	2.24	2.50	3.05	3.80	4.35	4.83	5.28
Ball bushing bearing LEYG□L	1.31	1.52	1.76	2.19	2.45	2.77	3.01	2.24	2.51	2.90	3.64	4.06	4.56	4.96

Series	LEYG25□DN∗□ (Motor mounting position: In-line)							LEYG32□DN∗□ (Motor mounting position: In-line)						
Stroke [mm]	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Sliding bearing LEYG□M	1.33	1.52	1.84	2.26	2.60	2.94	3.20	2.26	2.52	3.07	3.82	4.37	4.85	5.30
Ball bushing bearing LEYG□L	1.34	1.55	1.79	2.22	2.48	2.80	3.04	2.26	2.53	2.92	3.66	4.08	4.58	4.98

Refer to "Motor Mounting" on page 73 for details about motor mounting and included parts.

Dimensions: Motor Top Mounting

LEYG25, 32



[mm]

Size	MP	MH	MJ
25	31	3.4	4.9
32	47.14	4.4	5.9

Note) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed".
Additionally, when running the positioning operation, do not set within 2 mm of both ends.

LEYG□L (Ball bushing bearing) [mm]

Size	Stroke range (mm)	L	DB
25	Up to 114	91	10
	115 to 190	115	
	191 to 300	133	
32	Up to 114	97.5	13
	115 to 190	116.5	
	191 to 300	34	

LEYG□M (Sliding bearing) [mm]

Size	Stroke range (mm)	L	DB
25	Up to 59	67.5	12
	60 to 185	100.5	
	186 to 300	138	
32	Up to 59	74	16
	60 to 185	107	
	186 to 300	144	

LEYG□M, LEYG□L Common [mm]

Size	Stroke range (mm)	B	C	DA	EA	EB	EH	EV	FA	FB	G	GA	H	J	K	M	NA	NB
25	Up to 39	89.5	50	20	46	85	103	52.5	11	12.5	5.4	41	99	30.8	29	34	M5 x 0.8	8
	40 to 100		67.5															
	101 to 124	114.5																
	125 to 200		84.5															
	201 to 300		102															
32	Up to 39	96	55	25	60	101	123	64	12	16.5	5.4	50.5	126	38.3	30	40	M6 x 1.0	10
	40 to 100		68															
	101 to 124	126																
	125 to 200		85															
	201 to 300		102															

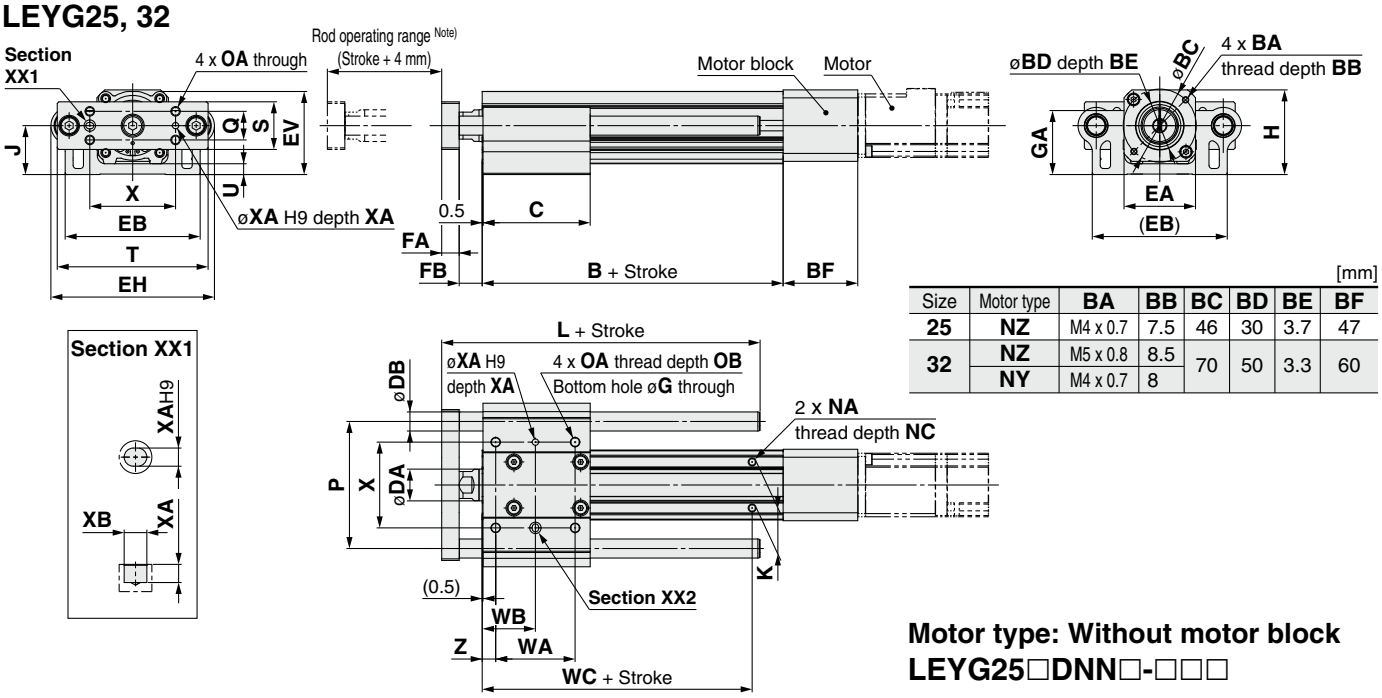
Size	Stroke range (mm)	NC	OA	OB	P	Q	S	T	U	WA	WB	WC	X	XA	XB	Y1	Y2	Z
25	Up to 39	6.5	M6 x 1.0	12	80	18	30	95	6.8	35	26	70	54	4	5	26.5	22	8.5
	40 to 100									50	33.5							
	101 to 124											95						
	125 to 200									70	43.5							
	201 to 300									85	51							
32	Up to 39	8.5	M6 x 1.0	12	95	28	40	117	7.3	40	28.5	75	64	5	6	34	27	8.5
	40 to 100									50	33.5							
	101 to 124											105						
	125 to 200									70	43.5							
	201 to 300									85	51							

∗ The FB measurement is when the unit is at the retracted stroke end position.

Refer to "Motor Mounting" on page 74 for details about motor mounting and included parts.

Dimensions: In-line Motor

LEYG25, 32

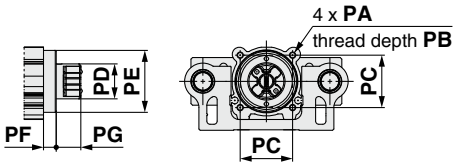


[mm]

Size	Motor type	BA	BB	BC	BD	BE	BF
25	NZ	M4 x 0.7	7.5	46	30	3.7	47
32	NZ	M5 x 0.8	8.5	70	50	3.3	60
	NY	M4 x 0.7	8				

Note) Do not allow collisions at either end of the rod operating range at a speed exceeding "pushing speed".
Additionally, when running the positioning operation, do not set within 2 mm of both ends.

Motor type: Without motor block
LEYG25□DNN□-□□□



[mm]

Size	PA	PB	PC	PD	PE	PF	PG
25	M4 x 0.7	6.5	33	22	39	8	15.5
32	M6 x 1.0	10	40	30	48	10.5	18.5

LEYG□L (Ball bushing bearing) [mm]

Size	Stroke range (mm)	L	DB
25	Up to 114	91	10
	115 to 190	115	
	191 to 300	133	
32	Up to 114	97.5	13
	115 to 190	116.5	
	191 to 300	34	

LEYG□M (Sliding bearing) [mm]

Size	Stroke range (mm)	L	DB
25	Up to 59	67.5	12
	60 to 185	100.5	
	186 to 300	138	
32	Up to 59	74	16
	60 to 185	107	
	186 to 300	144	

LEYG□M, LEYG□L Common [mm]

Size	Stroke range (mm)	B	C	DA	EA	EB	EH	EV	FA	FB	G	GA	H	J	K	NA
25	Up to 39	89.5	50	20	45	85	103	52.5	11	12.5	5.4	40.5	53.5	31	29	M5 x 0.8
	40 to 100		67.5													
	101 to 124	114.5														
	125 to 200		84.5													
	201 to 300		102													
32	Up to 39	96	55	25	60	101	123	64	12	16.5	5.4	50.5	68.5	38.5	30	M6 x 1.0
	40 to 100		68													
	101 to 124	126														
	125 to 200		85													
	201 to 300		102													

Size	Stroke range (mm)	NC	OA	OB	P	Q	S	T	U	WA	WB	WC	X	XA	XB	Z
25	Up to 39	6.5	M6 x 1.0	12	80	18	30	95	7	35	26	70	54	4	5	8.5
	40 to 100									50	33.5					
	101 to 124											95				
	125 to 200									70	43.5					
	201 to 300									85	51					
32	Up to 39	8.5	M6 x 1.0	12	95	28	40	117	7.5	40	28.5	75	64	5	6	8.5
	40 to 100									50	33.5					
	101 to 124											105				
	125 to 200									70	43.5					
	201 to 300									85	51					

∗ The FB measurement is when the unit is at the retracted stroke end position.

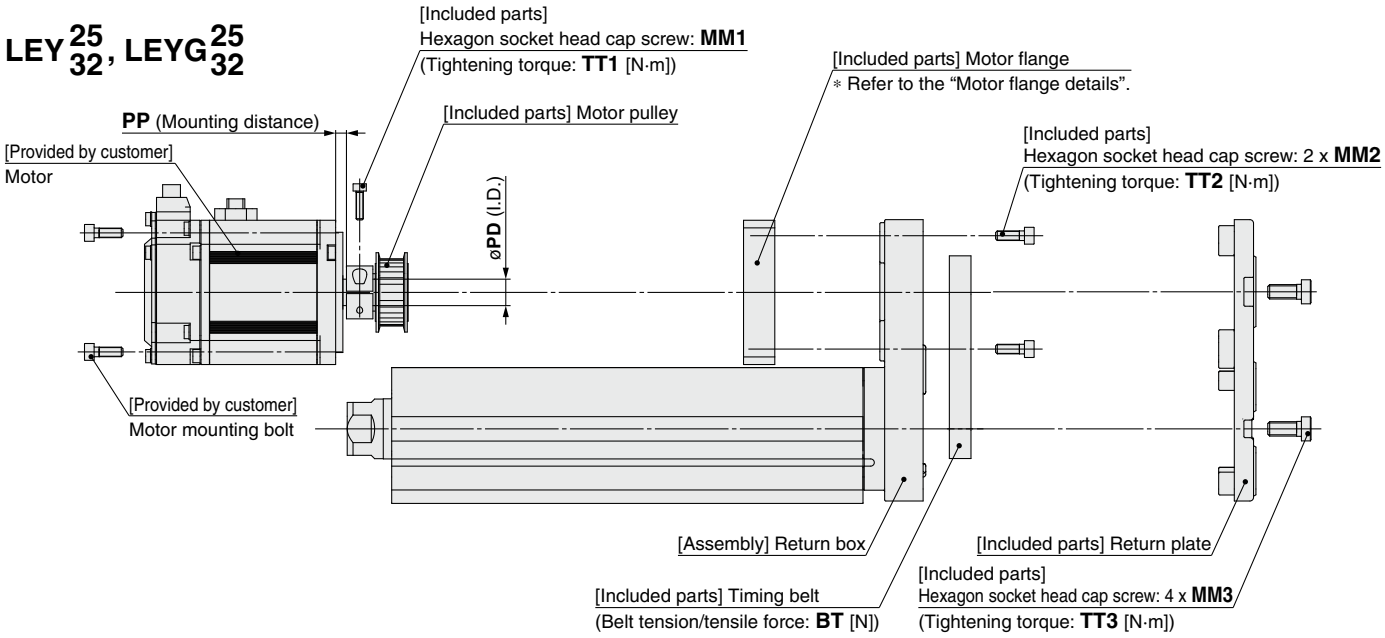
Motor Mounting: Top Mounting

- The motor and motor mounting bolts should be provided by the customer.
- When selecting the motor type NN, no motor flange and motor pulley include with the product. The body side pulley and timing belt are specially designed, so order the motor flange option on pages 75 and 76 separately.

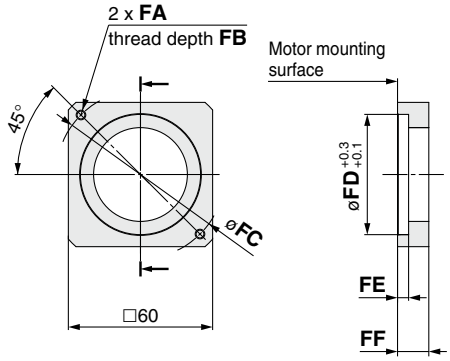
Mounting procedure

1) Fix the motor (provided by customer) and the motor pulley with the MM1 hexagon socket head cap screw.
2) Fix the motor and the motor flange with the motor mounting bolts (provided by customer).
3) Put the timing belt on the motor pulley and body side pulley, and then fix it temporarily with the MM2 hexagon socket head cap screws. (Refer to the mounting diagram.)
4) Apply the belt tension and tighten the timing belt with the MM2 hexagon socket head cap screws. (The reference level is the elimination of the belt deflection.)
5) Fix the return plate with the MM3 hexagon socket head cap screws.

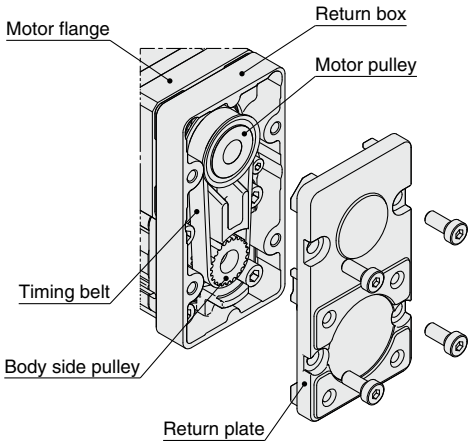
LEY$^{25}_{32}$, LEYG$^{25}_{32}$



Motor flange details



Mounting diagram



Dimensions

[mm]

Size	Motor type	MM1	TT1	MM2	TT2
25	NZ	M2.5 x 10	1.0	M3 x 8	0.63
32	NZ	M3 x 12	1.5	M4 x 12	1.5
	NY	M4 x 12	2.5		

Size	Motor type	MM3	TT3	PD	PP	BT
25	NZ	M4 x 10	1.5	8	7.5	19
32	NZ	M6 x 14	5.2	14	4.5	30
	NY			11		

Size	Motor type	FA	FB	FC	FD	FE	FF
25	NZ	M4 x 0.7	7.5	46	30	3.7	11
32	NZ	M5 x 0.8	8.5	70	50	3.3	13
	NY	M4 x 0.7	8	70	50	3.3	13

Included Parts List

Size: 25

Description	Qty. Motor type NZ	Qty. Motor type NN
Motor flange	1	—
Motor pulley	1	—
Return plate	1	1
Timing belt	1	1
Hexagon socket head cap screw (for return plate mounting)	4	4
Hexagon socket head cap screw (for motor flange mounting)	2	—
Hexagon socket head cap screw (for pulley fixing)	1	—

Size: 32

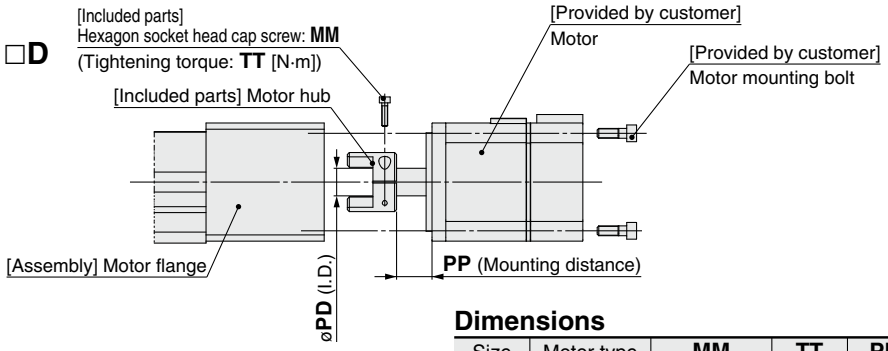
Description	Qty. Motor type NZ/NY	Qty. Motor type NN
Motor flange	1	—
Motor pulley	1	—
Return plate	1	1
Timing belt	1	1
Hexagon socket head cap screw (for return plate mounting)	4	4
Hexagon socket head cap screw (for motor flange mounting)	2	—
Hexagon socket head cap screw (for pulley fixing)	1	—

- The motor and motor mounting bolts should be provided by the customer.
- When selecting the motor type NN, no motor flange and hub include with the product. The body side hub and spider are specially designed, so order the motor flange option on pages 75 and 76 separately.

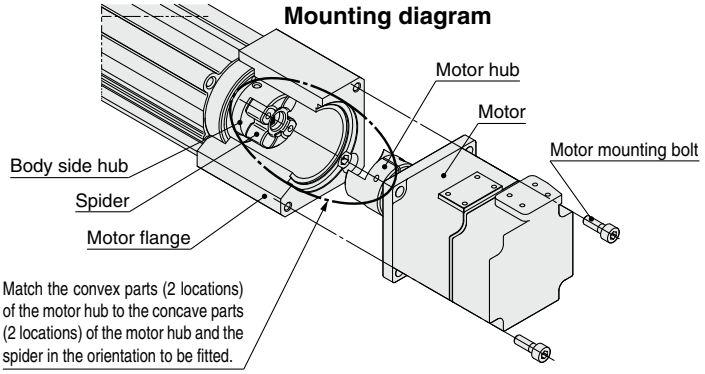
Motor Mounting: In-line

Mounting procedure
1) Fix the motor (provided by customer) and the motor hub with the MM hexagon socket head cap screw.
2) Check the orientation of the motor hub position and insert it. (Refer to the mounting diagram.)
3) Fix the motor and the motor flange with the motor mounting bolts (provided by customer).

LEY$^{25}_{32}$D, LEYG$^{25}_{32}$□D



Mounting diagram



Dimensions [mm]

Size	Motor type	MM	TT	PD	PP
25	NZ	M2.5 x 10	1.0	8	12.5
32	NZ	M3 x 12	1.5	14	18
	NY	M4 x 12	2.5	11	

Included Parts List

Size: 25

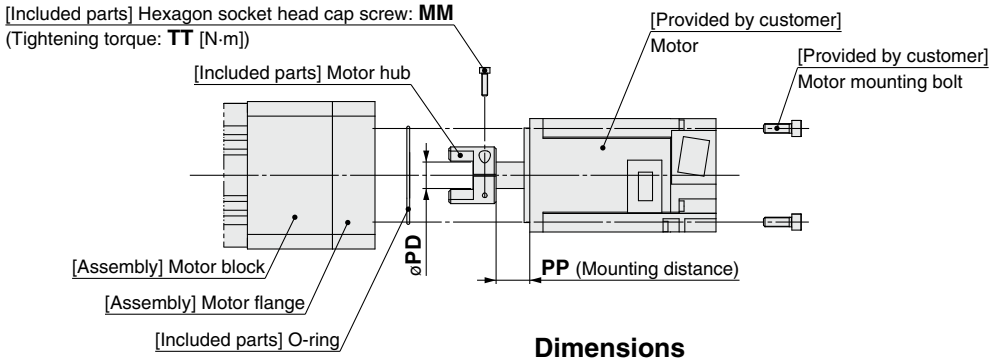
Description	Qty. Motor type NZ	NN
Motor hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Size: 32

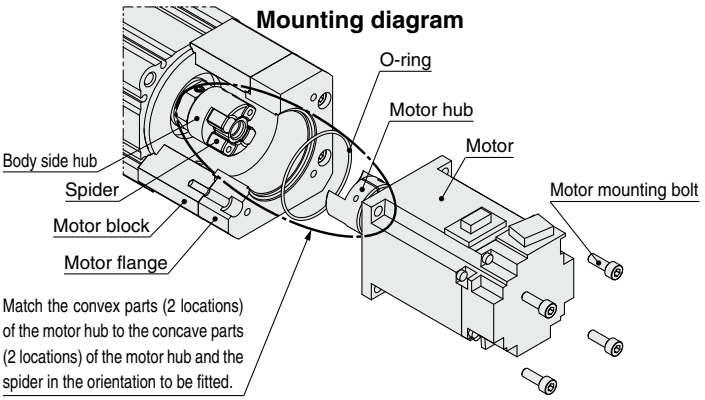
Description	Qty. Motor type NZ/NY	NN
Motor hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—

Mounting procedure
1) Fix the motor (provided by customer) and the motor hub with the MM hexagon socket head cap screw.
2) Put the O-ring on the mating part of the motor, and check the orientation of the motor hub position and insert it. (Refer to the mounting diagram.)
3) Fix the motor and the motor flange with the motor mounting bolts (provided by customer).

LEY63D



Mounting diagram



Dimensions [mm]

Size	Motor type	MM	TT	PD	PP
63	NZ	M3 x 12	1.5	14	17.8
	NY	M3 x 12	1.5	14	

Included Parts List

Size: 63

Description	Qty. Motor type NZ/NY	NN
Motor hub	1	—
Hexagon socket head cap screw (for hub fixing)	1	—
O-ring (O.D. ø52/Wire dia. ø1.5)	1	—

Series LEY
Motor Mounting Parts

Motor Flange Option

When the motor type "NN" is selected for the model, no motor flange for motor mounting includes with the product.
Select an applicable motor flange option according to the part number shown below, and then order it.

How to Order

LEY−MF 25 □ − NZ

❶ ❷ ❸

❶ Size

25	For LEY25/LEYG25
32	For LEY32/LEYG32
63	For LEY63

❷ Motor mounting position

P	Top mounting
D	In-line

∗ Size 63: In-line type only

❸ Motor type

Symbol	Type
NZ	Mounting type Z
NY	Mounting type Y

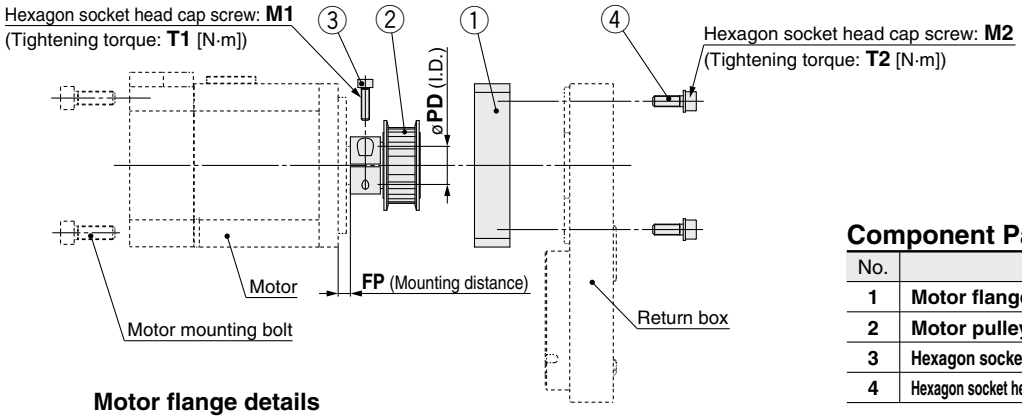
∗ Refer to the “Compatible Motors”.

Compatible Motors

Applicable motor model			Size/Motor type					
			25		**32**		**63**	
Manufacturer	Series	Type	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y	"NZ" Mounting type Z	"NY" Mounting type Y
Mitsubishi Electric Corporation	MELSERVO-JN	HF-KN	●	—	●	—	●	—
	MELSERVO-J3	HF-KP						
	MELSERVO-J4	HG-KR						
YASKAWA Electric Corporation	Σ-V	SGMJV						
SANYO DENKI CO., LTD.	SANMOTION R	R2						
OMRON Corporation	Sysmac G5	R88M-K			—	●	—	●
Panasonic Corporation	MINAS-A4	MSMD	—					
	MINAS-A5	MSMD/MHMD						

Dimensions: Motor Flange Option

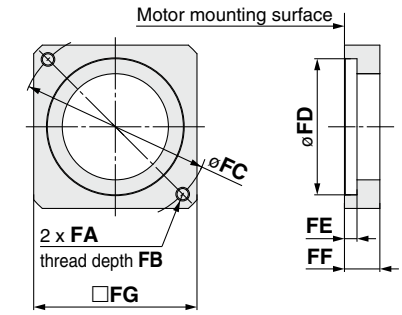
Motor mounting position: Top mounting



Component Parts

No.	Description	Qty.
1	**Motor flange**	1
2	**Motor pulley**	1
3	**Hexagon socket head cap screw (for pulley fixing)**	1
4	**Hexagon socket head cap screw (for motor flange mounting)**	2

Motor flange details



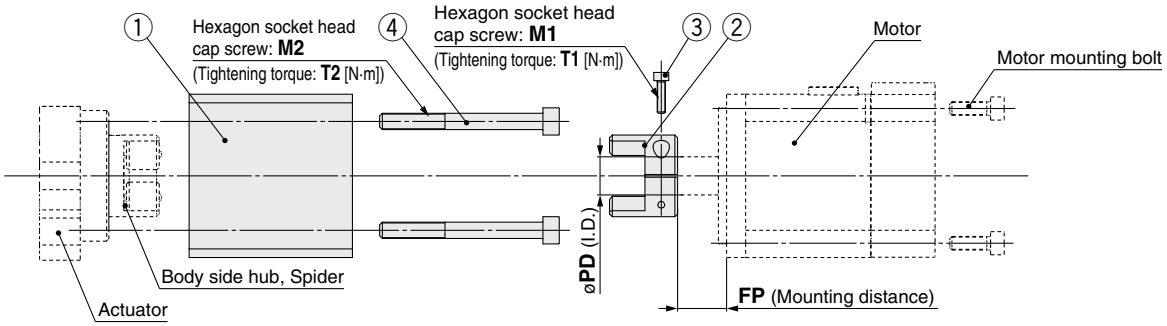
Dimensions

[mm]

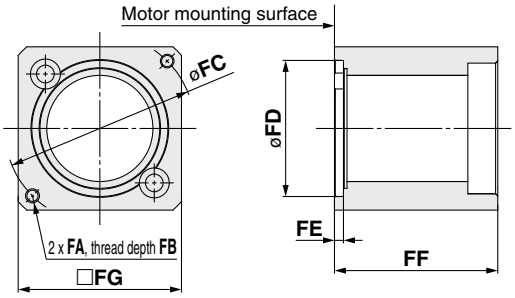
Size	Motor type	FA	FB	FC	FD	FE	FF	FG	M1	T1	M2	T2	PD	FP
25	**NZ**	M4 x 0.7	7.5	46	30	3.7	11	42	M2.5 x 10	1.0	M3 x 8	0.63	8	7.5
32	**NZ**	M5 x 0.8	8.5	70	50	3.3	13	60	M3 x 12	1.5	M4 x 12	1.5	14	4.5
	NY	M4 x 0.7	8						M4 x 12	2.5			11	

Dimensions: Motor Flange Option

Motor mounting position: In-line [Size 25, 32]



Motor flange details



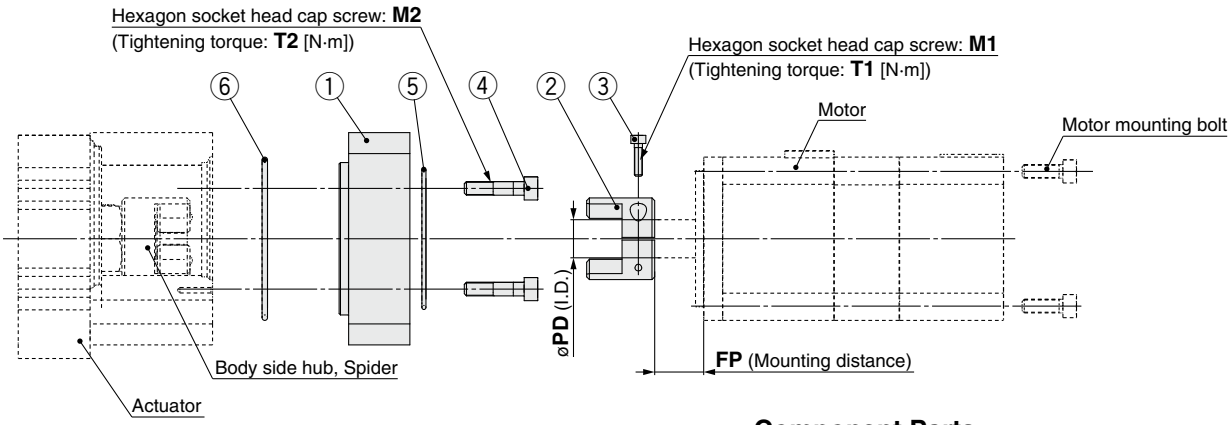
Component Parts

No.	Description	Qty.
1	**Motor flange**	1
2	**Motor hub**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor block mounting)**	2

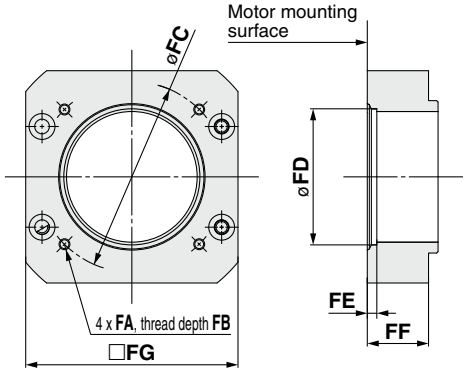
Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	M1	T1	M2	T2	PD	FP
25	**NZ**	M4 x 0.7	7.5	46	30	3.7	47	45	M2.5 x 10	1.0	M4 x 45	1.5	8	12.5
32	**NZ**	M5 x 0.8	8.5	70	50	3.3	60	60	M3 x 12	1.5	M6 x 60	5.2	14	18
	NY	M4 x 0.7	8						M4 x 12	2.5			11	

Motor mounting position: In-line [Size 63]



Motor flange details



Component Parts

No.	Description	Qty.
1	**Motor flange**	1
2	**Motor hub**	1
3	**Hexagon socket head cap screw (for hub fixing)**	1
4	**Hexagon socket head cap screw (for motor adapter mounting)**	4
5	**O-ring (O.D. ø52/Wire dia. ø1.5)**	1
6	**O-ring (O.D. ø60/Wire dia. ø2.0)**	1

Dimensions [mm]

Size	Motor type	FA	FB	FC	FD	FE	FF	FG	M1	T1	M2	T2	PD	FP
63	**NZ**	M5 x 0.8	10	70	50	3.5	22.5	78	M3 x 12	1.5	M5 x 22	3.0	14	18
	NY	M4 x 0.7	8											

Series LEY/LEYG
Electric Actuators/ Specific Product Precautions 1

Be sure to read before handling. Refer to "Handling Precautions for SMC Products" (M-E03-3) for Safety Instructions and the Operation Manual for Electric Actuator Precautions. Please download it via our website, http://www.smcworld.com

Design/Selection

⚠Warning

1. Do not apply a load in excess of the operating limit.

Select a suitable actuator by load and allowable lateral load on the rod end. If the product is used outside of the operating limit, the eccentric load applied to the piston rod will be excessive and have adverse effects such as creating play on the sliding parts of the piston rod, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.

This can cause failure.

3. Do not use as a stopper.

Handling

⚠Caution

1. When using the pushing operation, be sure to set to force/speed control, and use within the specified pushing speed range for each series.

Do not allow the piston rod to hit the workpiece and end of the stroke in the position control. The lead screw, bearing and internal stopper may be damaged and lead to malfunction.

2. When using the pushing operation, set the maximum value to be no more than 90% of the rated torque (no more than 150% for the LEY63).

It may lead to damage and malfunction.

3. The maximum speed of this actuator is affected by the product stroke.

Check the model selection section of the catalog.

4. Do not apply a load, impact or resistance in addition to the transferred load during return to origin.

Additional force will cause the displacement of the origin position.

5. Do not scratch or dent the sliding parts of the piston rod, by striking or attaching objects.

The piston rod and guide rod are manufactured to precise tolerances, even a slight deformation may cause malfunction.

6. When an external guide is used, connect it in such a way that no impact or load is applied to it.

Use a freely moving connector (such as a floating joint).

7. Do not operate by fixing the piston rod and moving the actuator body.

Excessive load will be applied to the piston rod, leading to damage to the actuator and reduced the life of the product.

Handling

⚠Caution

8. When an actuator is operated with one end fixed and the other free (ends tapped (standard), flange type), a bending moment may act on the actuator due to vibration generated at the stroke end, which can damage the actuator. In such a case, install a mounting bracket to suppress the vibration of the actuator body or reduce the speed so that the actuator does not vibrate.

Also, use a mounting bracket when moving the actuator body or when a long stroke actuator is mounted horizontally and fixed at one end.

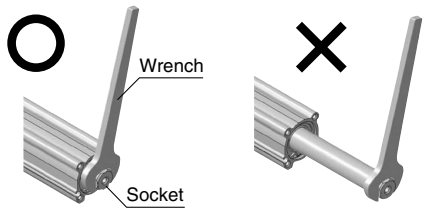
9. Avoid using the electric actuator in such a way that rotational torque would be applied to the piston rod.

This may cause deformation of the non-rotating guide, abnormal responses of the auto switch, play in the internal guide or an increase in the sliding resistance.

Refer to the table below for the approximate values of the allowable range of rotational torque.

Allowable rotational torque [N·m] or less	LEY25□	LEY32	LEY63
	1.1	1.4	3.8

When screwing in a bracket or nut to the end of the piston rod, hold the flats of the rod end with a wrench (the piston rod should be fully retracted). Do not apply tightening torque to the non-rotating mechanism.



10. When using auto switch with the guide rod type LEYG series, the following limits will be in effect.
Please select the product while paying attention to this.

- Insert the auto switch from the front side with rod (plate) sticking out.
- For the parts hidden behind the guide attachment (Rod stick out side), the auto switch cannot be fixed.
- Consult with SMC when using auto switch on the rod stick out side.

Enclosure

IP – □□

First characteristic numeral ● ● **Second characteristic numeral**

● **First Characteristics: Degrees of protection against solid foreign objects**

0	Non-protected
1	Protected against solid foreign objects of 50 mmø and greater
2	Protected against solid foreign objects of 12 mmø and greater
3	Protected against solid foreign objects of 2.5 mmø and greater
4	Protected against solid foreign objects of 1.0 mmø and greater
5	Dust-protected
6	Dust-tight

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Enclosure

● **Second Characteristics: Degrees of protection against water**

0	Non-protected	—
1	Protected against vertically falling water drops	Dripproof type 1
2	Protected against vertically falling water drops when enclosure tilted up to 15°	Dripproof type 2
3	Protected against rainfall when enclosure tilted up to 60°	Rainproof type
4	Protected against splashing water	Splashproof type
5	Protected against water jets	Water-jet-proof type
6	Protected against powerful water jets	Powerful water-jet-proof type
7	Protected against the effects of temporary immersion in water	Immersible type
8	Protected against the effects of continuous immersion in water	Submersible type

Example) In the case of stipulated as IP65, we can know the degrees of protection is dust-tight and water-jet-proof on the grounds that the first characteristic numeral is "6" and the second characteristic numeral is "5" respectively, that gives it will not be adversely affected by direct water jets from any direction. (∗ The water jets which are "5" of the second characteristic numeral based on JIS C 0920 (2003) indicates a flow of water for 3 minutes at 12.5 L per minute.)

Mounting

⚠Caution

1. When mounting workpieces or jigs to the piston rod end, hold the flats of the piston rod end with a wrench so that the piston rod does not rotate. The bolt should be tightened within the specified torque range.

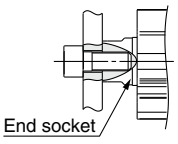
This may cause abnormal responses of the auto switch, play in the internal guide or an increase in the sliding resistance.

2. When mounting the product and/or a workpiece, tighten the mounting screws within the specified torque range.

Tightening the screws with a higher torque than recommended may cause a malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

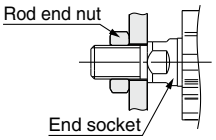
<Series LEY>

Workpiece fixed/Rod end female thread

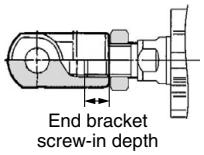


Model	Bolt	Max. tightening torque (N·m)	Max. screw-in depth (mm)	End socket width across flats (mm)
LEY25	M8 x 1.25	12.5	13	17
LEY32	M8 x 1.25	12.5	13	22
LEY63	M16 x 2	106	21	36

Workpiece fixed/Rod end male thread (When "Rod end male thread" is selected.)



Model	Thread size	Max. tightening torque (N·m)	Effective thread length (mm)	End socket width across flats (mm)
LEY25	M14 x 1.5	65.0	20.5	17
LEY32	M14 x 1.5	65.0	20.5	22
LEY63	M18 x 1.5	97.0	26	36



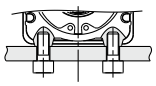
Model	Rod end nut		End bracket screw-in depth (mm)
	Width across flats (mm)	Length (mm)	
LEY25	22	8	8 or more
LEY32	22	8	8 or more
LEY63	27	11	11 or more

∗ Rod end nut is an accessory.

Mounting

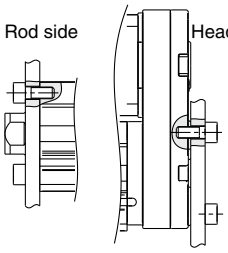
⚠Caution

Body fixed/Body bottom tapped style (When "Body bottom tapped" is selected.)



Model	Bolt	Max. tightening torque (N·m)	Max. screw-in depth (mm)
LEY25	M5 x 0.8	3.0	6.5
LEY32	M6 x 1.0	5.2	8.8
LEY63	M8 x 1.25	12.5	10

Body fixed/Rod side/Head side tapped style

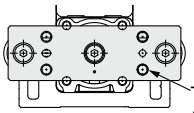


Model	Bolt	Max. tightening torque (N·m)	Max. screw-in depth (mm)
LEY25	M5 x 0.8	3.0	8
LEY32	M6 x 1.0	5.2	10
LEY63	M8 x 1.25	12.5	14

∗ Except the LEY□D.

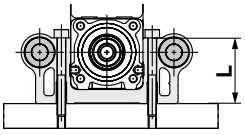
<Series LEYG>

Workpiece fixed/Plate tapped style



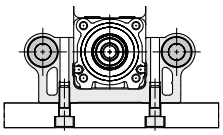
Model	Bolt	Max. tightening torque (N·m)	Max. screw-in depth (mm)
LEYG25$^{M}_{L}$	M6 x 1.0	5.2	11
LEYG32$^{M}_{L}$	M6 x 1.0	5.2	12

Body fixed/Top mounting



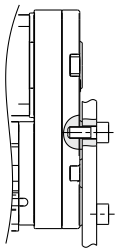
Model	Bolt	Max. tightening torque (N·m)	Length: L (mm)
LEYG25$^{M}_{L}$	M5 x 0.8	3.0	40.5
LEYG32$^{M}_{L}$	M5 x 0.8	3.0	50.5

Body fixed/Bottom mounting



Model	Bolt	Max. tightening torque (N·m)	Max. screw-in depth (mm)
LEYG25$^{M}_{L}$	M6 x 1.0	5.2	12
LEYG32$^{M}_{L}$	M6 x 1.0	5.2	12

Body fixed/Head side tapped style



Model	Bolt	Max. tightening torque (N·m)	Max. screw-in depth (mm)
LEYG25$^{M}_{L}$	M5 x 0.8	3.0	8
LEYG32$^{M}_{L}$	M6 x 1.0	5.2	10

Series LEY/LEYG
Electric Actuators/ Specific Product Precautions 3

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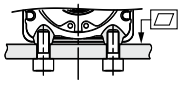
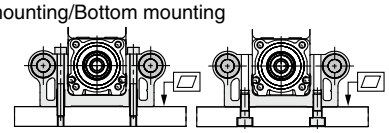
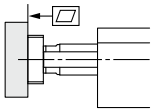
Mounting

⚠Caution

3. Keep the flatness of the mounting surface within the following ranges when mounting the actuator body and workpiece.

Unevenness of a workpiece or base mounted on the body of the product may cause an increase in the sliding resistance.

Model	Mounting position	Flatness
LEY□	Body/Body bottom 	0.1 mm or less
LEYG□	Top mounting/Bottom mounting 	0.05 mm or less
	Workpiece/Plate mounting 	0.05 mm or less

Maintenance

⚠Warning

1. Ensure that the power supply is stopped and the workpiece is removed before starting maintenance work or replacement of the product.

- **Maintenance frequency**

Perform maintenance according to the table below.

Frequency	Appearance check	Belt check
Inspection before daily operation	○	—
Inspection every 6 months/ 250 km/5 million cycles*	○	○

* Select whichever comes sooner.

- **Items for visual appearance check**

1. Loose set screws, Abnormal dirt
2. Check of flaw and cable joint
3. Vibration, Noise

- **Items for belt check**

Stop operation immediately and replace the belt when belt appear to be below. Further, ensure your operating environment and conditions satisfy the requirements specified for the product.

a. Tooth shape canvas is worn out.
Canvas fiber becomes fuzzy. Rubber is removed and the fiber becomes whitish. Lines of fibers become unclear.

b. Peeling off or wearing of the side of the belt
Belt corner becomes round and frayed thread sticks out.

c. Belt partially cut
Belt is partially cut. Foreign matter caught in teeth other than cut part causes flaw.

d. Vertical line of belt teeth
Flaw which is made when the belt runs on the flange.

e. Rubber back of the belt is softened and sticky.

f. Crack on the back of the belt

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